

WASHINGTON UNIVERSITY
THE HENRY EDWIN SEVER INSTITUTE OF TECHNOLOGY
DEPARTMENT OF CHEMICAL ENGINEERING

STEADY STATE AND DYNAMIC REACTOR MODELS FOR COUPLING
EXOTHERMIC AND ENDOTHERMIC REACTIONS

by

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Prepared under the direction of Prof. P.A. Ramachandran and Prof. M.P. Duduković

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ABSTRACT

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Several endothermic reaction systems, such as synthesis gas generation from hydrocarbons, can benefit from coupling with a suitable exothermic reaction. The coupling of exothermic and endothermic reactions can be achieved in the following configurations: (i) Recuperative coupling (counter-current reactor, co-current reactor), (ii) Regenerative coupling (reverse-flow reactor) and (iii) Direct coupling (directly coupled adiabatic reactor). However, the comparative performance studies of various modes of coupling are not available in the literature. Hence, the overall objectives of this research are to develop steady state and dynamic reactor models to study and compare the different modes of coupling (counter-current, co-current, and adiabatic reactors), and to investigate such coupling in the catalytic partial oxidation of methane to synthesis gas.

The steady state and transient pseudo-homogeneous plug flow models have been used to analyze and compare the different modes of coupling. Model predictions are used to assess the effects of design and operational parameters on conversion of endothermic reaction and on the hot spot. Measures to reduce the hotspots by inert packing and by shifting the operating regime are investigated. These model predictions are used as the guidelines for the selection of a suitable mode of coupling for the desired

application. The performance of different reactors is also compared based on the exergy losses in each system.

A new robust numerical tool, that combines the boundary element method (BEM) and the arc-length continuation technique, is developed to investigate the coupling of exothermic and endothermic reactions within the catalyst particle. This algorithm has been used to identify and analyze the multiple steady states exhibited by the catalyst particles.

As a case study, the catalytic partial oxidation of methane to syngas in a short contact time packed bed reactor has been investigated using steady state and transient heterogeneous plug flow and axial dispersion models. Some of the hotly debated issues, such as the effects of gas hourly space velocity and the presence of steam in the feed on the conversion of methane and the observed temperature peak, are addressed. The evidences to support the occurrence of wrong-way behavior in the short contact time reactor are presented.

dedicated to

My Father

Shri. R. Chidambareswara Bhattar

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Nomenclature

A_c	Cross sectional area of the reactor
a_p	Specific surface area of the catalyst particle
C	Concentration of the reactant
C_o	Inlet / reference concentration of the reactant
C_{pg}	Specific heat capacity of the gas mixture
C_{ps}, C_{peat}	Specific heat capacity of the solid packing
Da	Damkohler Number
$D_{axi,m}$	Effective mass dispersion coefficient
$D_{i,m}$	Effective diffusivity of species i in a mixture
d_p	Diameter of catalyst particle
d_t	Reactor / tube diameter
E	Activation Energy
h	Heat transfer coefficient
k	Rate constant of the reaction
K_{mix}	Thermal conductivity of the mixture
K_{wall}	Thermal conductivity of the wall
k_g	Mass transfer coefficient
L	Reactor length
ℓ	Characteristic length $(= d_p \frac{\epsilon_b}{1 - \epsilon_b})$
M_T	Total mass flux of reactants
$M_{wt,i}$	Molecular weight of species i
n_{ifo}	Flux of species i in the gas solid film
$nrxg$	Number of gas phase reactions
$nrxs$	Number of solid phase reactions
Nu	Nusselt number

p	Partial pressure of species in gas phase
P	Total pressure of the system
Pe_M	Mass Peclet number based on the particle diameter
Pe_{mg}	Mass Peclet number
Pe_{Mr}	Radial mass Peclet number
Pe_T	Thermal Peclet number based on the particle diameter (gas phase)
Pe_{Tc}	Solid phase thermal Peclet Number
Pe_{Tg}	Gas phase thermal Peclet Number
Pe_{Tr}	Radial thermal Peclet number (gas phase)
r	Radial position within the reactor
r_j	Rate of reactions (Chapter 7)
R_g	Universal gas constant
R_i	Net rate of production of species i
R_1	Radius of tubes
R_2	Radius of shell or the half-length of the distance between two tubes (surface)
R_T	$R_1 + R_2 + t_{wall}$
Re	Reynolds number (based on particle)
S_p	Surface area of the catalyst particle
Sc	Schmidt Number
Sh	Sherwood Number
t	Time
t_{wall}	Thickness of the tube wall
T	Gas phase temperature
T_{ref}	Reference temperature
U	Overall wall heat transfer coefficient
u_g	Velocity of the gas flow (at any point in the reactor)
V	Volume of the reactor
x	Dimensionless concentration

y	Mass fraction of the species
z	Axial position along the reactor
<i>Greek letters</i>	
α	Activity of the catalyst bed at exothermic side
β	Dimensionless heat of reaction
γ	Dimensionless activation energy
$-\Delta H$	Heat of the reaction
ϵ_b	Void fraction
η	Activity of the catalyst bed at endothermic side
θ	Dimensionless temperature
λ	Thermal conductivity (gas /solid)
μ	Dynamic viscosity of gas mixture
ξ	Dimensionless axial position
ϑ	Characteristic velocity ($= \frac{M_T}{\rho_{mix} \epsilon_b}$)
ρ	Density
τ	Dimensionless time
Φ_{Mrj}^2	$= Pe_{Mr}^j Da^j \frac{R_T}{L}$
Φ_{Trj}^2	$= Pe_{Tr}^j Da^j \frac{R_T}{L}$
Ψ	Ratio of rate of endothermic reaction to the rate of exothermic reaction at the reference temperature
Ω	$= \frac{\rho_g^c C_{pg}^c u_g^c}{\rho_g^h C_{pg}^h u_g^h}$
<i>Subscripts / Superscripts</i>	
b	Bed
c	Endothermic reaction
cat	Catalyst
e	effective

f	Gas-solid film
g	Gas phase
h	Exothermic reaction
hom	homogeneous
i	Species index
in	Inlet
j	= c, h / reaction index (Chapter 7)
mix, m	Mixture
p	Catalyst Particle
ref	Reference
s	Solid phase
T	Total
0	Inlet / Initial
*	Dimensionless quantity

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To sum up what I have done over these years, I would say, as it goes in Tamil –

“ *Katradu kai mannalavu ; Kallathadu ulagalavu* ”

(What we have learnt is equivalent to a fistful of sand and to explore further, the sky is the limit)

R.C. Ramaswamy

CREL, Washington University in St. Louis

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Chapter 1

Introduction

1.1 Scope

Coupling energy intensive endothermic reaction systems with suitable exothermic reactions improves the thermal efficiency of the processes and reduces the size of the reactors. The aim of this dissertation is to investigate and provide comprehensive information on different modes of coupling exothermic and endothermic reactions, especially the recuperative and direct mode of coupling, using suitable mathematical models. It is to be noted that the efficient coupling of exothermic and endothermic reactions increases the profitability of the reactor operation. In Chapter 1 the background and the motivation for this research are briefly described. The objectives of this thesis are listed in Section 1.3. An outline of the thesis is presented in the final section of this chapter.

1.1 Motivation for Research

Multifunctional reactors integrate, in one vessel, one or more transport processes and a reaction system (Agar, 1999; Zafir and Gavriilidis, 2003) and are increasingly used in industries as process intensification tools. These multifunctional reactors make the process more efficient and compact and result in large savings of operational and capital costs (Dautzenberg and Mukherjee, 2001; Freide et al., 2003). A multifunctional reactor can be used, for example, for coupling exothermic and endothermic reactions. In it, an exothermic (combustion) reaction is used as the energy (heat) source to drive the endothermic reaction(s). The auto-thermal reformer is an example of a multifunctional reactor which is used to produce syngas from natural gas.

The coupling of exothermic and endothermic reactions can be achieved in the following reactor configurations: (i) Direct coupling (directly coupled adiabatic reactor); (ii) Regenerative coupling (reverse-flow reactor); (iii) Recuperative coupling (counter-current heat exchanger reactor and co-current heat exchanger reactor). Figure 1-1 shows the schematic of the flow pattern in these reactors.

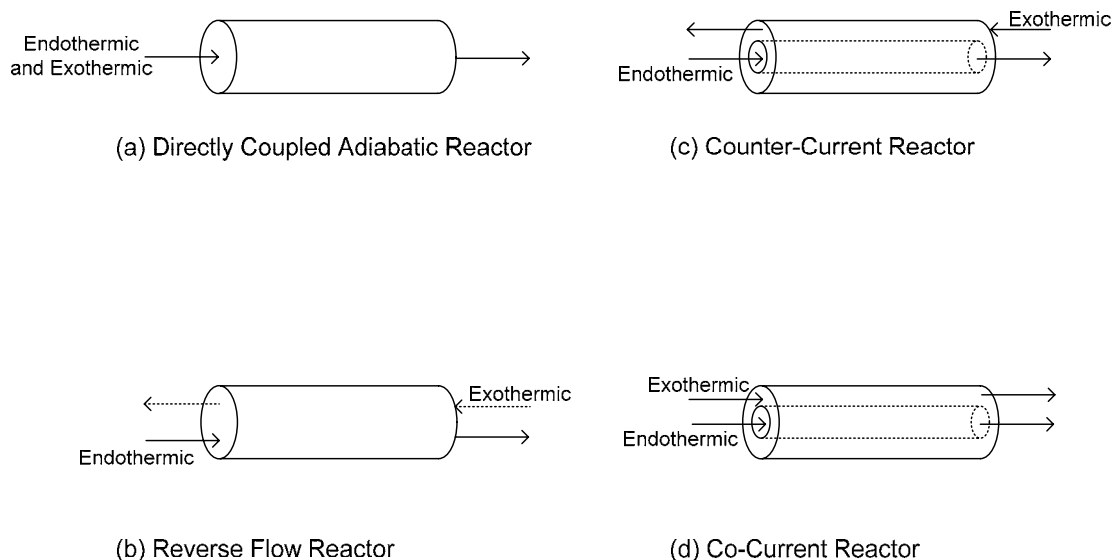


Figure 1-1: Schematic of Various Reactor Configurations for Coupling Exothermic and Endothermic Reactions

In directly coupled adiabatic reactors (Figure 1-1a), both reactions take place simultaneously in the same bed. In reverse flow reactors (Figure 1-1b), the exothermic and endothermic reactions occur periodically in the same reactor space but separated in time. In the recuperative reactors (with counter-current and co-current flow, Figures 1-1c and 1-1d), the endothermic reactions are carried out on the one (tube) side and the exothermic reactions on the other (shell) side of the heat exchanger reactors.

Most of the available literature on reactors for coupling exothermic and endothermic reactions has focused either on wall coated reactors (Venkataraman et al., 2003; Zanfir and Gavriilidis, 2003) or on monolith reactors (Hickman and Schmidt, 1992, 1993;

Bharadwaj and Schmidt, 1994, 1995; Kolios et al., 2001, 2002). In this work, we investigate the packed bed reactors, which are simple to construct, easy to operate, and can handle the amount of gas produced on an industrial scale. The steady state and transient performance of different packed bed reactor schemes, like the previously mentioned counter-current, co-current and directly coupled adiabatic reactors, are compared using the pseudo-homogeneous model to identify the best reactor for our applications.

As we couple highly exothermic reactions with endothermic reactions, there is a possibility that the exothermic reactions will reach complete conversion very near the reactor inlet, resulting in a high temperature peak. These hot spots can deactivate the catalyst and hence decrease the performance of the reactor. Our research addresses this issue and introduces suitable measures to reduce the hot spot by optimizing the design and operating variables, such as varying the flow rate of the streams, activity profiling of the catalysts, using inert packing etc. A parametric study of the effects of wall heat transfer coefficients, Damkohler number of the exothermic reaction, and other operating variables, on the conversion of the endothermic reaction and on the temperature peak of the exothermic reaction is also studied. The guidelines for the selection of suitable modes of coupling exothermic and endothermic reactions, for a given process of interest, are not available in the literature. Hence, this work presents a preliminary strategy for the reactor selection.

The search for efficient new reactor concepts for coupling exothermic and endothermic reactions has been intensified in the last decade in an attempt to produce syngas, commercially, in a cost-effective manner. Syngas (a mixture of carbon mono-oxide and hydrogen) is a primary feedstock for the production of pollutant free synthetic automotive fuel, various chemicals like methanol and its derivatives, and for the production of hydrogen gas for fuel cell applications. These applications are gaining importance in reducing the dependence on non-renewable crude oil (De Groot and Froment, 1996; Pena et al., 1996). Syngas is produced from natural gas (mostly

methane) or any other hydrocarbon fuels (e.g. naphtha etc.) and from coal, by partial oxidation reactions or by energy intensive steam reforming reactions.

Syngas production by the catalytic partial oxidation route proceeds through the coupled exothermic combustion reaction and the endothermic reforming reactions. In partial oxidation reactors, the exothermic and endothermic reactions are carried out in the same bed. Hence, a proper strategy for coupling these reactions should be studied to tailor the product quality and control the reactors. In reformers, the coupling of steam reforming reactions with suitable exothermic reactions could supply the necessary energy demand for reforming while minimizing the energy losses. Thus, detailed knowledge on the coupling of exothermic and endothermic reactions is important to maximize both the conversion of the desired reaction and the yield of the desired product. Hence, our goal is to develop reactor models suitable for improved understanding of these coupling phenomena and to design a reactor for the production of syngas from methane.

In the available literature, most of the work on syngas generation by partial oxidation route has focused on the fuel cell applications, which are normally carried out at atmospheric conditions (de Smet et al., 2001). On the other hand, the production of syngas at higher operating pressure conditions is attractive to gas-to-liquids, intermediates (methanol synthesis) and specialty chemicals industries due to the ease of integration with downstream processes and due to larger volumetric reactor productivity. However, only a limited amount of experimental work is available at higher reactor operating pressures in the open literature (Poirier et al., 1992; Gomez et al., 1995; Basini et al., 2001). In this work, we propose to investigate the operation of these reactors for syngas generation at higher operating pressures.

Several ongoing research studies suggest that with the advent of high activity catalysts, the desired conversion of methane and desired selectivity to CO/ H₂ can be obtained in short contact time (SCT) reactors (Hohn and Schmidt, 2001). In short contact time reactors, the desired yield of syngas is attained in a very short length of the order of 1-5 cm., with the temperature peak around 1400 K. In such reactors, the interaction of the

exothermic and the endothermic reaction time scales with other transport and flow time scales results in non-intuitive and interesting steady state and dynamic behavior which has not been fully described in the literature. In general, not much information is available on the dynamic behavior of coupling exothermic and endothermic reactions, in particular in short contact time reactors. Yet, understanding such behavior is very important from the start-up, shut-down and a control point of view. For that reason we investigate the steady state and transient behavior of catalytic partial oxidation of methane in short contact time packed bed reactors using the transient heterogeneous plug flow and axial dispersion models. Additionally, the coupling of exothermic and endothermic reactions at the catalyst particle scale is investigated for the first time.

The performance of different modes of coupling is compared based on the conversion of the desired reaction and the magnitude of the temperature peak (hot spot), if any, observed in the reactor. Another mode of comparison of the reactor performance is based on the exergy loss. The concept of exergy, a measure of available energy of any mechanical or material stream, incorporates the energy balance (first law of thermodynamics) and the entropy balance (second of law of thermodynamics) and hence it accounts for any process irreversibility occurring in the system. The procedure to calculate exergy losses in the recuperative and directly coupled adiabatic reactors is presented and is used to compare various modes of coupling. Similarly, suitable algorithms are developed and implemented to calculate the exergy losses in an industrial reactor and, as a case study, the exergy losses in the catalytic partial oxidation of methane to syngas in a packed bed reactor is presented.

1.2 Research Objectives

The overall objective of this research is to develop steady state and transient mathematical models for studying and comparing different modes of coupling solid catalyzed exothermic and endothermic chemical reactions in a packed bed reactor, as indicated in Section 1.2. The itemized scope of work includes:

1. Develop a one dimensional transient and steady state models (a pseudo-homogeneous model is presented) for co-current, counter-current, and directly coupled adiabatic reactors.
2. Develop a two dimensional model to study the radial effects in a recuperative reactor. (This model is necessary because the temperature profile in the radial direction is important in determining the heat flux transferred between the shell and tube side of the reactor.)
3. Develop a particle level governing model to study the coupling mechanism at the catalyst pellet scale.
4. Develop an effective numerical solution procedure to solve the reactor level one dimensional and two dimensional transient models, which includes:
 - i) Use the Method Of Lines (MOL) to solve transient partial differential equations
 - ii) Implement the Total Variation Diminishing (TVD) (Harten, 1984) scheme to avoid Gibbs Phenomenon / spurious oscillations in the solution.
5. Develop a technique to identify and analyze the multiple steady states at particle level using BEM and continuation techniques.
6. Simulate the catalytic partial oxidation of methane to syngas in a short contact time packed bed reactors.
7. Finally, perform a thermal efficiency analysis based on the exergy losses to compare the performance of different reactors.

1.3 Organization of the Thesis

This thesis has been structured as follows. Chapter 2 provides a brief literature survey on the work carried out on (i) the coupling of exothermic and endothermic reactions, and (ii) the production of syngas from methane. This includes both experimental and theoretical work. Chapter 3 presents a detailed steady state and transient analyses of recuperative reactors using 1-D model. Chapter 4 discusses the coupling of exothermic and endothermic reactions in heat exchanger reactors using the 2-D model. The direct coupling of exothermic and endothermic reactions at the reactor level, in DCAR, is

investigated in Chapter 5, and at the particle level in Chapter 6. The steady state and dynamic analysis of partial oxidation of methane to syngas in short contact time packed bed reactors are discussed in Chapter 7. The exergy analysis and the comparison of performance of different modes of coupling are presented in Chapter 8. Conclusions and the recommendations for further work are outlined in Chapter 9. The references are listed at the end.

Chapter 2

Background

2.1 Scope

This chapter presents a brief background of the work reported in the literature on the coupling of exothermic and endothermic reactions in different reactor schemes and on the catalytic partial oxidation of methane to syngas. Several reactor configurations have been tested and evaluated in the literature to couple these two classes of reactions but a comprehensive understanding of the performance of various modes of coupling and the guidelines for selection of the best reactor choice are still not complete. Also as stated in Chapter 1, we noted that not much information is available in the literature on the dynamics of coupling exothermic and endothermic reactions. Similarly, a detailed steady state and transient analyses of interaction of exothermic and endothermic reactions in a short contact time reactors, which is very important for the processes like catalytic partial oxidation of methane to syngas, is not recorded in the literature. Thus, the scope of this chapter is to document the state of the art information on coupling of exothermic and endothermic reactions.

2.2 Coupling of Exothermic and Endothermic Reactions

The energy coupling between exothermic and endothermic reactions can be broadly classified into Recuperative, Direct and Regenerative (Kolios et al., 2000). In recuperative coupling, exothermic and endothermic reactions are spatially segregated (Zanfir and Gavriilidis, 2003) in the reactor with heat transfer occurring through the wall. On the other hand, in the direct and regenerative mode of coupling the same catalytic bed is used to conduct both the exothermic and endothermic reactions. Further,

in the direct coupling, both the reactions occur simultaneously in the bed where, as in the regenerative mode of coupling, the reactions are segregated in time (also known as periodic coupling).

2.2.1 Reactors for Recuperative Coupling

In recuperative reactors, heat is transferred between the exothermic and the endothermic reactions through the wall that separates the reactor space in which they occur. In 2002, BP installed a compact syngas reformer of 3 million scfd of natural gas processing capacity using the counter-current technology at their Nikiski Test Facility in Nikiski, Alaska. Here, the endothermic steam reforming of natural gas is coupled to the combustion of hydrogen. These compact reformers offer major cost and size advantages (Ruhl et al., 2000; Freide et al., 2003).

Reactors for recuperative coupling can be operated in either counter-current or co-current modes. In these heat exchanger type reactors, air (or oxygen) mixed with fuel gas is employed for the combustion reaction, and the reactants for the endothermic reactions are fed either counter-currently or co-currently through the adjacent passages of the reactor (Frauhammer et al., 1999; Kolios et al., 2001, 2002). These passages can be channels in a monolith or catalyst packed (or catalyst coated) tubes and annular spaces in the shell and tube reactor. This type of coupling of exothermic and endothermic reactions allows the operation to be carried out in a steady-state fashion (Frauhammer et al., 1999).

Monoliths can handle large volume of gases with relatively low pressure drop but require special distributors to feed the reactants for exothermic and endothermic reactions in the alternate channels (Frauhammer et al., 1999). In packed bed reactors, both the exothermic and endothermic reactions have their respective catalyst beds. The reactions occur at the catalyst surface with or without the homogenous reactions. The packed bed reactors are simple to construct and operate and are well suited for industry. In catalytic wall reactors, the wall separating the exothermic and endothermic reactions

is coated with the respective catalysts on the two sides. This arrangement minimizes the heat-transfer resistance in thermal boundary layers and reduces the needed residence times (Venkataraman et al., 2002; Venkataraman et al., 2003). Some of the experimental and modeling work carried out using the recuperative reactors is discussed in the following sections.

Experimental Work: Hunter and McGuire (1980) were among the first to suggest the coupling of an exothermic and endothermic reaction in a recuperative fashion. Koga and Watanabe (1991) described a plate type reformer that coupled catalytic combustion and reforming, which took place in alternate channels. Here, the catalysts filled the gaps between the plates and were not deposited on the walls, which resulted in a higher heat-transfer resistance. Igarshi et al. (1992) described a wall reactor that used a heating medium to supply heat to endothermic reactions which occur on walls in alternate channels. Here the combustion side offered high heat transfer resistance. The “dual flow chemical reactor” of Kaminsky et al., (1997) employed oxidative coupling of methane on catalytically coated surfaces to provide heat for thermal hydrocarbon cracking. In this process, useful compounds are obtained from both sides of the reactor. Ioannides and Verykios (1997, 1998) later introduced a new reactor concept, where the reactor is an open ended non-porous ceramic tube whose surfaces are coated with catalytic layers. In this scheme, the methane and oxygen feeds enter the tube and part of it combusts on its inner catalytic surface. Subsequently, the reaction mixture comes in contact with the outside wall where the endothermic reforming reactions occur.

Frauhammer et al., (1999) described a reactor that coupled catalytic combustion and methane steam reforming in alternate channels with catalysts coated on both sides of the walls. They studied the process both experimentally and theoretically, mainly in a counter-current fashion using a ceramic honey-comb monolith with specially designed distribution channels for combustion and process gases. In the counter-current scheme, the cold feeds are heated up by the respective hot effluents on the both sides of the reactor. The temperature profiles for both the reactions exhibited a peak around the same axial position in the reactor. These peaks usually occurred near the reactor inlet

for the exothermic reaction but, depending on the kinetics, this high temperature region may be shifted to the middle of the reactor. Kolios et al. (2001, 2002) showed that the hot spots could be avoided by using a suitable co-current arrangement or by distributing the fuel feed along the reactor.

Venkataraman et al., (2002) experimentally and theoretically explored ethane dehydrogenation coupled with methane catalytic combustion in a concentric tube configuration operating at about 1000 °C in both co-current and counter-current fashions. They showed that the counter-current mode of operation results in a hot spot with a higher conversion of ethane and a lower selectivity to ethylene compared to the co-current reactor mode. The system showed comparable performance to a conventional cracker, but at a much shorter contact time. They also showed that by employing multiple passes on the combustion side, the heat losses can be reduced and both the conversion and selectivity can be increased. In addition, they extended the above study to a parallel plate catalytic reactor (Venkataraman et al., 2003). From this study, they found that the two pass parallel plate systems give better conversion and selectivity than the one pass parallel plate system and the respective two pass tubular system. Finally, they introduced the extended two pass system, wherein the plates on the endothermic side are larger than the plates on the combustion side. In the extended reactor configuration, water-gas shift reaction is promoted and more hydrogen is produced. In these reactors, the mass-transfer rates to the catalyst walls play a key role in conversion and selectivity.

Ismagilov et al., (2001) developed and tested a heat exchanging tubular reactor where methane combustion and steam reforming catalysts were incorporated within metal foams attached to the external and internal surfaces of the metal tube. The addition of hydrogen to the combustion chamber increases the conversion of methane in the steam reforming section while maintaining a more uniform reactor temperature profile in the range of 850 to 900 °C.

Robbins et al., (2003) studied the CH₄ reforming and H₂/CH₄ combustion reactions in a wall coated co-current flow reactor, experimentally and theoretically, and showed the importance of the ratio of the reforming fuel flow rate to the combustion fuel flow rate on the desired conversion and temperature peak. Table 2-1 summarizes some of the key reaction systems studied in the recuperative reactors. The operating conditions used and the dimensions of the reactors used are also listed in the same table.

Table 2-1: Reaction Systems Studied, in the Literature using Recuperative Reactors

No.	Reaction Systems	Reactor Dimensions	Type of Study (Experiments / Model)	Reference
1	CH ₄ steam reforming (water gas shift reaction and reverse methanation) on Ni-Mg-Al ₂ O ₃ coupled with CH ₄ oxidation (homogeneous and catalytic)	L = 50 cm	1-D steady-state dispersion model	Frauhammer et al., 1999
2	CH ₄ reforming coupled with CH ₄ oxidation	L = 25 cm	Experiments T _{in} = 653 K (reformer) T _{in} = 803 K (combustor)	Polman et al., 1999
3	C ₂ H ₆ dehydrogenation on Pd coupled with CH ₄ combustion on Pd	L = 1 m W = 2 mm T = 2 mm H = 1 m	2D Steady-state dispersion model T _{in} = 923 K	Zanfir & Gavrillidis, 2001
4	CH ₄ reforming coupled with CH ₄ combustion (Ni/Ni-Cr foam on Al ₂ O ₃ as catalyst for both reactions)	L = 15 cm D = 18 mm T = 2 mm	Experiments (tubular reactor) T _{in} = 373-573 K	Ismagilov et al., 2001
5	CH ₄ steam reforming (WGS and reverse methanation) on Ni-MgO-Al ₂ O ₃ coupled with CH ₄ oxidation on Pt-Al ₂ O ₃	L = 40 cm (bench scale) L = 12 m (industrial)	Experiments and 1-D steady-state model T _{in} = 650 – 800 K	Avci et al., 2001
6	CH ₄ steam reforming coupled with CH ₄ oxidation (homogeneous and catalytic)	L = 1 m	1-D steady-state model	Kolios et al., 2002
7	C ₂ H ₆ dehydrogenation (homogeneous) coupled with CH ₄ combustion on Pt-Al ₂ O ₃	L = 30 cm D = 4 mm	Experiments (tubular reactor) And 1-D PFR model	Venkataraman et al., 2002
8	CH ₄ steam reforming (WGS and reverse methanation) on Ni-Mg-Al ₂ O ₃ coupled with CH ₄ oxidation on Pt	L = 30 cm W = 1-4 mm T = 0.5 mm	2-D steady-state model T _{in} = 793 K	Zanfir & Gavrillidis, 2003
9	CH ₄ steam reforming on Rh (with Pt-ceria extended reactor for WGS) coupled with CH ₄ oxidation on Pt	L = 8 cm W = 4 mm T = 0.1 mm H = 5 cm	Experiments and CFD simulations T _{in} = 573 K (reformer) T _{in} = 298 K (combustor)	Venkataraman et al., 2003

10	CH ₄ steam reforming on Rh/Al ₂ O ₃ coupled with CH ₄ or H ₂ combustion on Pd/Al ₂ O ₃ (Wall coated co-current reactor)	L = 10 cm W = 3 mm H = 2 cm	Experiments and 1-D transient model T _{in} = 673 – 873 K	Robbins et al., 2003
11	CH ₃ OH steam reforming on Cu/ZnO coupled with CH ₃ OH combustion on cobalt oxide	L = 3 cm W = 0.32 mm T = 0.2 mm	experiments	Reuse et al., 2004
12	CH ₄ steam reforming (WGS and reverse methanation) on Ni-Mg-Al ₂ O ₃ coupled with CH ₄ oxidation on Pt	L = 30 cm W = 2 mm T = 0.5 mm	2-D steady-state model T _{in} = 793 K	Zanfir & Gavrilidis, 2004
13	C ₄ H ₁₀ combustion on Pt-Al ₂ O ₃ coupled with NH ₃ cracking on Ir-Al ₂ O ₃	L = 3 mm W = 200 μm H = 500 μm T = 2 μm	Experiments in a suspended tube reactor and heat transfer modeling	Arana et al., 2003
14	CH ₄ (hexane and isooctane) steam reforming on a Ni-GIAP-3 catalyst coupled with H ₂ oxidation on Pt-Al ₂ O ₃	L = 20 cm T = 1 mm W = 1.5 cm H = 7 cm	Experiments and 2-D mathematical modeling T _{in} = 293 K (combustor) T _{in} = 473 K (reformer)	Kirillov et al., 2001
15	Ammonia decomposition on catalytic wall (Ru) with Propane combustion (homogeneous) in counter current micro-channel reactor	L = 1 cm W _{comb} = 600 μm W _{ref} = 300 μm T = 300 μm H = 5-10 mm	2-D CFD simulation T _{in} = 300 K (combustor) T _{in} = 300 K (reformer)	Deshmukh & Vlachos, 2005
16	Methanol decomposition (Ni/Al) coupled with methane combustion (Pt/Al ₂ O ₃) (co-current and counter current wall type reactor and packed bed)	L = 20 cm W = 40 mm H = 10 mm T = 2 mm	2-D model T _{in} = 350 C (combustor) T _{in} = 350 C (reformer)	Fukuhara & Igarashi, 2005

L is the length, W is the width of the reactor channel, D is the diameter of the inner tube in a tubular reactor, T is the wall thickness and H is the height.

Modeling Work: Modeling studies were carried out to understand steady state behavior exhibited by the reactors mentioned above.

Eigenberger's group (Frauhammer et al., 1999; Kolios et al., 2001, 2002) used a one dimensional modeling approach to study mainly the axial temperature profiles in counter-current systems. Frauhammer et al.(1999) studied the influence of fuel gas flow rates, the varying axial distribution of the catalyst and of the homogeneous reactions on the internal heat exchange of the reactor. The maximum temperature on the exothermic side is the main concern in these types of reactors and an optimal overlapping of both reaction zones minimizes the temperature peak (Kolios et al., 2001, 2002).

Zanfiri and Gavriilidis (2001) studied the coupling of the dehydrogenation and combustion reactions in a co-current catalytic plate reactor. Their (Zanfiri and Gavriilidis, 2001) primary results show the importance of the catalyst loading to avoid hot spots, and the effect of wall conductivity on the axial and radial temperature gradients. They also studied methane steam reforming and methane catalytic combustion systems using a two dimensional model (Zanfiri and Gavriilidis, 2003) and showed that the channel height and the thickness of the catalyst layer play a very important role in the temperature profile and in the exit conversion. From this study it is clear that the Fourier Number, defined as the ratio of the local space time and the transverse diffusion time, should be greater than unity so that the reactant molecules can have enough time to reach the catalyst wall.

Fukuhara and Igarashi (2005) recently compared the performance of coupling exothermic and endothermic reactions recuperatively in the wall coated reactors and in packed bed reactors using 2-D models. They showed that the temperature difference between the exothermic and endothermic side is larger in the packed bed reactors compared to the wall coated reactors (due to effective wall heat transfer in catalyst coated wall reactors). The magnitude of the hotspot in packed bed reactors is larger in the counter-current reactors compared to the co-current flow mode. A detailed explanation for the larger temperature difference in the packed bed reactors is not provided.

Recently, due to the need for the production of hydrogen for fuel cell applications, there is a renewed interest in coupling of exothermic and endothermic reactions and the compact reformers. The flexibility of using independent choice of fuel, catalysts and the reaction conditions for the combustor and the reformer with the smaller size of the micro-devices (which facilitates heat transfer and can also be used as onboard reformer) renders recuperative coupling attractive for the micro-devices. Deshmukh and Vlachos (2005) studied the homogenous propane combustion coupled to catalytic ammonia decomposition, experimentally and using CFD models, in a micro-channel reactor in counter current flow mode. They have showed that the flow rate of the endothermic

streams (ammonia in this case, which should be larger than the flow rate of the combustion fuel) plays a huge role in self-sustaining this process and in controlling the temperature peak.

It is to be noted from the above studies that the understanding of these coupled systems is not complete and, in particular for the packed bed reactors, the effects of design and operating parameters on the steady state behavior are not systematically documented in the literature. Similarly, transient behavior exhibited by these reactors, such as the start-up and shut down features, which are important from a control point of view, is also not investigated at length.

2.2.2 Reactors for Direct Coupling

In the direct mode of coupling, both exothermic and endothermic reactions are carried out in the same catalytic bed. For example, the catalytic partial oxidation of methane to syngas can be carried out in a single bed in the above fashion. This is an active area of research and to date there is no plant operating commercially to produce syngas by the catalytic partial oxidation route.

Directly coupled adiabatic reactor (DCAR) has also been applied industrially in secondary methane steam reforming within the ammonia synthesis (Ridler and Twigg, 1989) and hydrogen cyanide processes (Agar, 1999), where hydrogen combustion is employed to produce in situ heat for the endothermic synthesis reactions. Other examples of its use are in-situ hydrogen combustion in oxidative dehydrogenations (Grasselli et al. 1999 a,b; Henning and Schmidt, 2002), coupling of propane combustion and endothermic thermal cracking of propane to propylene and ethylene (Chaudhary et al., 2000), coupling of methane steam reforming with catalytic oxidation of methane in partial oxidation reactors (De Groote and Froment, 1996; Ma and Trimm, 1996; Avci et al. 2001). The major concern in directly coupled adiabatic reactor is that the catalyst bed should favor both exothermic and endothermic reaction and is not deactivated by the former.

Directly coupled adiabatic reactor can be further classified into Simultaneous DCAR (SIMDCAR) and Sequential DCAR (SEQDCAR). In SIMDCAR, the bed is made of a catalyst that favors both the exothermic and endothermic reaction or it is made of uniformly mixed exothermic and endothermic catalysts (Biesheuvel and Kramer, 2003). The SEQDCAR has an alternating exothermic and endothermic catalyst bed. An example of sequential DCAR is the new auto-thermal reformer (ATR) being developed by The Institute of Applied Energy, Tokyo for steam reforming of natural gas into hydrogen and carbon monoxide (Ondrey, 2003). This new ATR consists of a reactor packed with alternating layers of oxidation and reforming catalysts. The new endeavor of ABB Lummus (SMART) in developing the reactor for producing styrene by dehydrogenation of ethyl benzene and combustion of hydrogen is an example of SEQDCAR. More information on some of the earlier experimental and modeling activities, available in the literature, carried out in the directly coupled adiabatic reactors, in particular for the catalytic partial oxidation of methane to syngas process, will be presented in Section 2.3.

2.2.3 Reactors for Regenerative Coupling

Reverse flow reactor is a chronologically segregated reactor and is an example for regenerative mode of coupling exothermic and endothermic reactions. Reverse flow reactors are well suited for weakly exothermic reactions such as the catalytic purification of exhaust streams contaminated by volatile organic compounds (Kulkarni, 1996).

In this reactor, both the exothermic and endothermic reactions occur in the same catalyst bed but are separated in time. Here, the exothermic fuel combustion takes place in the first half of the cycle. Then, in the next half cycle, the flow is reversed and the endothermic reaction takes place using the energy stored in the bed during the previous exothermic half cycle (de Groote et al., 1996; Kulkarni and Dudukovic, 1996, 1998; Kolios et al., 2000; Gosiewski, 2001; van Sint Annaland and Nijssen, 2002). Hence, the reverse flow reactors are operated in a periodic and dynamic mode. Various

investigators have studied reverse flow reactors and have concluded that one of the key issues is the development of hot spots that can damage the catalyst and the reactor walls. The dynamics of this scheme are complex and good operation requires proper switching time between the exothermic and endothermic reactions (Kulkarni and Dudukovic, 1998; Frauhammer et al., 1999). Research on the integration of air separation membrane unit in a reverse flow reactor is also underway (Smit et al., 2003), which is important for catalytic partial oxidation of methane to syngas. Smit et al. (2005) have recently demonstrated that the catalytic partial oxidation process can be carried out in both the half cycles in reverse flow packed bed reactor and with the distribution of oxygen through the membranes (for controlling the temperature excursions). More details on this mode of coupling can be found in the dissertation of Kulkarni (1996) and in the references cited above.

2.3 The Production of Syngas from Methane

Production of syngas (a mixture of CO and H₂) and/or hydrogen has been gaining importance in recent years because of the increased demand in (i) petroleum refining processes such as hydro de-sulphurisation, and hydrocracking (Prins et al., 1989), (ii) petrochemical applications, such as synthesis of methanol and its derivatives (Hindermann et al., 1993), methanol-to-gasoline conversion (Chang, 1988), ammonia synthesis (Nielsen, 1981) and Fischer-Tropsch synthesis, and (iii) fuel cell applications (Kolios et al., 2005). Industrially, syngas (or hydrogen) is produced by steam reforming of fuels such as methane, naphtha, heavy oil, and coal. The production of synfuels and chemicals from natural gas and coal through the syngas route could reduce the consumption of crude oil. The research on the conversion of methane to synthesis gas has recently gained momentum due to the availability of pollutant free natural gas and the ability of this process to produce syngas with the desired ratio of CO/H₂ (~0.5) required for downstream processes (such as methanol synthesis etc.). In large-scale conversions of natural gas into liquid fuels, 60-70% of the cost of the overall process is associated with syngas production (Aasberg-Petersen, 2001). Hence, a reduction in

syngas generation costs would have a large impact on the overall economics of these industrial processes.

2.3.1 Available Technologies to Produce Syngas

Syngas can be produced by one of the following methods based on its end use (de Groote and Froment, 1996; Pena et al., 1996):

- i) Steam reforming (SR)
- ii) Autothermal reforming
- iii) Non-catalytic partial oxidation with oxygen or air
- iv) Catalytic partial oxidation (CPO) with oxygen or air
- v) Combined reforming of methane

Table 2-2 summarizes the different technologies available for the production of syngas from methane commercially. It also provides the process description, operating conditions, hydrogen-to-carbon mono-oxide ratio in syngas, conversion etc. From Table 2-2, it is clear that by the catalytic partial oxidation route, more feed can be processed at a lower temperature and can produce syngas of required composition for downstream Fischer-Tropsch / Methanol processes. The packed bed reactor used for catalytic methane partial oxidation is a directly coupled adiabatic reactor.

2.3.2 Experimental Work on Catalytic Partial Oxidation of Methane

A number of experimental studies on the catalytic partial oxidation (CPO) of methane to syngas, at atmospheric pressure, in fixed beds, honey-comb monoliths, and fluidized beds are available in the literature (Pena et al., 1996). The mean residence times in these reactors are generally of the order of seconds. Chaudhary et al., 1993) and Schmidt's group (Hickman and Schmidt, 1992, 1993; Bharadwaj and Schmidt, 1994, 1995; Hohn and Schmidt, 2001) have studied the production of syngas in a millisecond contact time packed bed reactor and monolith reactor, respectively, at atmospheric conditions. The

production of syngas at higher operating pressure conditions is attractive to industry due to the ease of integration with the downstream processes and due to larger volumetric reactor productivity. However, only a limited amount of experimental work is available at higher operating pressure in the open literature (Poirier et al., 1992; Gomez et al., 1995; Basini et al., 2001). It is to be recognized, however, that at higher pressure, the conversion of methane is limited by the thermodynamic equilibrium and the homogeneous gas phase reactions also occur along with the heterogeneous reactions (de Smet et al., 2001; Bizzi et al., 2003).

The issue which is still much debated regarding CPO is the mechanism by which methane is converted to syngas. Although the possibility of performing the reaction via the direct route (in one step from methane to syngas) has been reported by several researchers, there seems to be an increasing consensus that the reaction occurs mainly via the indirect route. Only at very high temperatures the reaction may partially proceed through the direct route. It is to be noted that the hot spot could be eliminated if the reaction occurs via the direct route.

Because of the complexity of the processes involved and because of interactions of exothermic and endothermic reactions, a suitable mathematical model (both steady state and dynamic) is required for the optimization of the process and for reactor control.

Table 2-2: A brief review on technologies available for syngas Production
(Pena et al., 1996; Aasberg-Petersen, 2001).

Process and Technology licensors	Description	Operating Conditions	H ₂ /CO ratio	Remarks
Steam Reforming (Davy Process)	<ul style="list-style-type: none"> Multi-tubular catalytic reactor employed with exterior heat supply Catalyst: Ni/Al₂O₃ Main Reaction: $\text{CH}_4 + \text{H}_2\text{O} \rightarrow \text{CO} + 3\text{H}_2$ 	<ul style="list-style-type: none"> Press.: 15-30 atm Temp.: ~1200 K 	3 - 5	<ul style="list-style-type: none"> Residence time: order of seconds Excess steam required to reduce carbon deposition (H₂O / CH₄ mole ratio ~ 2-5) Conversion ~ 90-92% Capital Cost is High BP commercialized compact reformer (counter-current reactor coupling hydrogen combustion and steam reforming) in 2002
Auto thermal Reforming (Haldor-Topsoe, Lurgi)	<ul style="list-style-type: none"> Preheated feed streams are mixed in a burner, where partial oxidation takes place followed by steam reforming and equilibration in the catalyst bed Catalyst : Ni Main Reactions: $\text{CH}_4 + 0.5\text{O}_2 \rightarrow \text{CO} + 2\text{H}_2$ $\text{CH}_4 + \text{H}_2\text{O} \rightarrow \text{CO} + 3\text{H}_2$ 	<ul style="list-style-type: none"> Press.: 25 atm (exit) Temp.: <ol style="list-style-type: none"> catalyst zone - 1200 – 1400 K Combustion zone – ~2200K 	~ 2.5	<ul style="list-style-type: none"> Residence time: order of seconds Conversion ~ 90% Feasibility of operating at low steam-to-carbon ratio of 0.2-0.6 is demonstrated in pilot plants. Total annual cost 17-18% less than steam reforming
Non-Catalytic Partial Oxidation (Texaco, Shell)	<ul style="list-style-type: none"> Mixture of O₂ and CH₄ is preheated, mixed and ignited in a burner Main Reaction: $\text{CH}_4 + 0.5\text{O}_2 \rightarrow \text{CO} + 2\text{H}_2$ 	<ul style="list-style-type: none"> Temp.: ~ 1800 K Press.: 1–40 atm. 	~1.7-1.8	<ul style="list-style-type: none"> Residence time: order of seconds Addition of steam increases soot formation Expensive next to steam reforming

<p>Catalytic Partial Oxidation (Exxon Mobil, Conoco Philips) Not yet commercial-ized</p>	<ul style="list-style-type: none"> Mixture of O₂ / air and CH₄ with or without steam Catalyst: Ni /Pt, Rh Reactors: Packed beds, Monoliths, Fluidized beds. Reaction Scheme (still in debate): $\text{CH}_4 + 0.5\text{O}_2 \rightarrow \text{CO} + 2\text{H}_2$ Or $\text{CH}_4 + 2\text{O}_2 \rightarrow \text{CO}_2 + 2\text{H}_2\text{O}$ $\text{CH}_4 + \text{H}_2\text{O} \rightarrow \text{CO} + 3\text{H}_2$ 	<ul style="list-style-type: none"> Temp.: 1000-1500 K Press.: 1 – 40 atm. 	~ 2	<ul style="list-style-type: none"> Residence time : order of milliseconds to seconds Conversion : 90% Selectivity : 95% Offers best economic advantage
<p>Combined Reforming of Methane (ICI, Exxon, Uhde GmbH)</p>	<ul style="list-style-type: none"> Combines steam reforming and oxy-reforming In gas heated reforming (GHR) of ICI, the heat required for primary reforming is provided by heat exchange with the reformed gas from secondary oxy reformer. In combined autothermal reforming (CAR) of Exxon, steam reforming is combined with partial oxidation of natural gas in a single fluidized bed reactor (Catalyst – Ni). 	Similar to steam reformers / partial oxidation reactors	1-3	<ul style="list-style-type: none"> Residence time : order of seconds CO₂ reforming can also be combined with steam reforming to produce syngas composition. Total annual cost of GHR is less than ATR but more than Partial oxidation reactors

2.3.3 Modeling Work on Catalytic Partial Oxidation of Methane

A lot of research has been carried out in recent years in the development of steady state and dynamic models for the syngas process. This section reviews some of the most pertinent studies.

De Groote and Froment (1996) developed a steady state 1-D heterogeneous model to simulate the adiabatic fixed bed reactor (directly coupled reactor) based upon the kinetics of total combustion, steam reforming, water-gas shift on a Ni catalyst using methane/oxygen or methane/air mixtures as feed. The steam reforming reactions and water gas shift reaction are parallel or more or less consecutive to combustion, depending upon the degree of reduction of the catalyst, which is determined by the temperature and the gas phase composition. Their kinetic models are the Langmuir-Hinshelwood-Hougen-Watson (LHHW) type and have the partial pressure of hydrogen in the denominator and so the feed should have some amount of hydrogen. In their model, intraparticle diffusion limitations are expressed in terms of a constant effectiveness factor for each reaction. They had developed two sub-models to understand the reaction mechanisms. In the first sub-model, the catalyst has a varying degree of reduction (VDR), where the combustion and reforming reactions occur sequentially. In the second sub-model the catalyst is bivalent (BV), where the catalytic combustion and steam reforming operate in parallel. The exit and maximum temperatures are smaller in the BV model and hence the predicted conversion is lower. With the VDR model, a peak appears in the temperature profile after which endothermic reaction proceeds. But in the BV model, a plateau is observed in the temperature profile. De Groote and Froment (1996) also studied the effect of the addition of CO₂ / Steam to the feed mixture on product yield and temperature profile.

De Smet et al. (2001) developed a steady state one dimensional heterogeneous reactor model to simulate the syngas process for methanol production (high pressure process with oxygen as oxidant) and for fuel cell applications (atmospheric process with air as oxidant). They considered external concentration and temperature gradients as well as

intra particle concentration gradients. The catalyst particle is assumed to be isothermal. They used two models for reforming kinetics, one proposed by Xu and Froment (XF) (1989) and the other proposed by Numaguchi and Kikuchi (NK) (1988). De Smet et al. also showed that for a catalytic partial oxidation reactor for methanol production, gas phase reactions need to be considered because the time scale for complete conversion of oxygen is much lower in homogeneous systems than in heterogeneous systems.

Veser and Frauhammer (2000) developed a transient state 1-D two phase dispersion model of a Pt monolithic reactor. They neglected gas phase reactions and the mass transfer limitations in the catalyst boundary layer. Here, the coupling of the two phases is through the convective heat transfer. They used the full adaptive method of lines approach to solve the set of coupled partial differential equations. Their simulation shows that the syngas production occurs by direct oxidation method.

Deutschmann and Schmidt (1998 a,b) developed a steady state 2-D detailed flow model of a monolithic channel. They considered both the gas phase and the surface reactions and used the commercial software FLUENT to solve the governing equations. They observed that the time scale of flow and solid thermal response are decoupled. And, they used a time independent formulation for channel calculations and the transient heat conduction equation for the solid. In their model, the axial temperature profile was used as the boundary conditions for the channel calculations, which returns the heat flux for the monolith heat transfer calculations. The time required for convergence of the model is 20 minutes without gas phase reactions and more than 10 hours with the gas phase reactions. Hence, we need a simple and robust model for control and optimization purposes. They observed that at the reactor inlet, total oxidation dominates and CO formation starts much before H₂ formation. They demonstrated that at high pressures, homogeneous reactions are important and the syngas yield decreases.

Avci et al., (2001) studied the catalytic oxidation and steam reforming of methane using a 1-D steady state heterogeneous model at high and low pressure conditions for two cases – one with a mixed bed (physical mixture) of oxidation and reforming catalysts

and the other with a dual bed where the two catalyst beds (in SEQDCAR arrangement) are placed consecutively. They observed that the mixed bed configuration exhibited better performance compared to dual bed schemes. The transient behaviors of these reactors were not discussed. Recently, Bizzi et al., (2003, 2004) studied the partial oxidation of methane in short contact time packed bed reactors using the rhodium catalyst with and without detailed chemistry. They also observed that gas phase reactions do not affect the overall reactivity of the partial oxidation of methane in short contact time packed bed reactors.

In a nutshell, most of the reported modeling studies discuss the steady state behavior of this process, in particular, the focus of investigations has been on the effects of feed temperature, importance of gas phase reactions at higher operating pressure and the role of thermal conductivity of the catalyst bed and GHSV on the methane conversion and on the product pattern.

2.4 Roadmap of this Thesis

Our literature study shows that a detailed comparative performance study of various modes of coupling of exothermic and endothermic reactions has not been done. Also, the studies available in the literature have mainly focused on the steady state behavior of some of the reactor systems. The transient behavior of such systems is not available in the literature and is very important in the design of reactors-from a reactor startup, shut down, and a control point of view. Hence, we propose to investigate and then compare the performance of different reactor systems using steady state and transient state mathematical models.

The reactors for coupling exothermic and endothermic reactions received wide attention due to their potential to provide compact hydrogen generation systems for fuel cells. Hence, most of the studies, including the theoretical ones, were carried out at atmospheric operating conditions. The energy efficiency of syngas generation and the reduction in its associated production costs are very important for large process

industries like methanol synthesis plants, which operate at higher pressures. Also, the dynamic behaviors of the partial oxidation reactors are not analyzed in depth in the literature. Hence, we have attempted to develop a robust transient 1-D heterogeneous model of short contact time packed bed reactor using the kinetics reported in the literature (de Smet et al., 2001; Dupont et al., 2002) to analyze this process.

In summary, this thesis focuses on answering some of the following questions:

1. How does the performances of counter-current, co-current and directly coupled reactors compare to one another?
2. How can we select a mode of coupling for the application / reaction system of our choice?
3. What are the features exhibited if both exothermic and endothermic reactions occur within a catalyst particle?
4. How does the interaction of exothermic and endothermic reaction time scale affect the performance, in particular conversion, selectivity and hotspot, in the catalytic partial oxidation of methane to syngas process in a short contact time reactor?
5. Do short contact time reactors exhibit wrong way behavior and, if they do, how?
6. Is there a measure to quantify and compare the performance of these reactors?

Some of the following steady state and transient models are used, based on the level of complexities demanded by the problem, to analyze the various features exhibited by these reactor systems and to answer the above questions:

Pseudo homogeneous plug flow model: This model assumes that the interphase transport processes (gas-solid film heat and mass transfer rates) are much faster than reaction processes and the gas moves like a slug within the reactor. These assumptions result in the model consisting of a set of first order differential equations. The steady state solutions for co-current and directly coupled adiabatic reactors are obtained by integrating these equations using the commercially available stiff solver from Netlib libraries. For the counter-current reactor, a two point boundary value problem results

and can be solved by discretizing the spatial derivatives (convective terms) and solving the resulting non-linear algebraic equations using a Newton-Powell type algorithm. In this work, the pseudo-transient approach is used to obtain the steady state solution. In this approach, the transient model equations are integrated until the steady state solution is obtained. This method seems to be faster and more robust for this reactor scheme.

Heterogeneous Plug Flow Model: The use of highly active catalysts increases the importance of transport resistances between the gas and the solid. The heterogeneous model accounts for the gas-solid film transfer effects. Several criteria are available in the literature (Mears, 1971; Hudgins, 1972) that helps us decide when to use the heterogeneous model instead of the pseudo homogenous model. Some of these criteria are listed in Appendix A. The heterogeneous model results in a set of differential and algebraic equations (DAE), which are solved using the commercially available DAE solver, DASSL from Netlib. The heterogeneous model equations can also be solved by sequential approach, which is explained in Chapter 7.

Axial Dispersion Model: Heat and mass dispersion are added to the heterogeneous model to account for the species and thermal dispersion which occur at high temperature. Mears (1971) provided the necessary criteria for using the axial dispersion model compared to plug flow model. This model results in a second order differential algebraic boundary value problem. These second order ODEs can be solved directly using the commercially available BVP solver, like COLDAE, etc., or the problem can be converted to algebraic equations by discretizing the spatial derivatives and solving the resulting equations using any non-linear algebraic solver. Instead, we employed the pseudo transient approach to obtain steady state profiles. This is computationally fast and efficient compared to using any other steady state solver especially for a complex and stiff systems. The axial dispersion models can exhibit multiple steady states. A detailed analysis of these models for short reactors (Hlavacek and Hoffman, 1970; Varma and Amundson, 1973) and long reactors (Vortuba et al., 1972) can be found in the literature. The axial dispersion models are important in simulating the syngas

generation in short contact time reactors, since the dispersion effects have been observed experimentally in the reactor systems (Basini et al., 2001).

Transient Models: The unsteady state pseudo-homogeneous, heterogeneous plug flow and axial dispersion models are developed to study the dynamics of coupling exothermic and endothermic reactions. These models are important for studying the evolution of state variables during start-up and for studying control strategies and safe shut-down of these reactors. Several interesting non-intuitive behavior of these reactors, like multiplicity and stability of the solution profiles etc., can be unveiled by the transient models. The transient models result in stiff partial differential equations and are solved by the Method-of-Lines (Vande wouwer et al., 2001).

The appropriate mathematical model and the corresponding numerical procedure used to analyze the reactor systems are mentioned and dealt with in detail in the respective sections / chapters studying the particular reactor configuration.

Chapter 3

Recuperative Coupling of Exothermic and Endothermic Reactions

3.1 Scope

In this chapter, a one dimensional pseudo-homogeneous plug flow model is used to analyze and compare the performance of co-current and counter-current heat exchanger reactors. The numerical schemes used to solve the model equations are presented. A parametric analysis is carried out to address the vital issues, such as the exit conversion of the endothermic reaction, the temperature peak (hot spot) of the exothermic reaction and the reactor volumetric productivity. The measures to reduce the hot spot by different catalyst profiling techniques are also addressed. Some features of the dynamic behavior exhibited by these reactors, such as temperature evolution profiles and wrong-way phenomena, are presented. The design and operational flexibilities of the recuperative reactors over other possible reactor configurations are discussed.

3.1 Introduction

In the heat exchanger reactors, the spaces where exothermic and endothermic reaction take place simultaneously in time are separated by the walls of the tubes and heat transfer between the two sides occurs through the tube wall. For example, endothermic reactions can be carried out on one side (say, the tube side) and the exothermic reactions on the other side (say, the shell side) of the shell and tube reactor and heat is transferred between the exothermic and the endothermic reactions through the tube wall. These reactors can be operated either in counter-current or in co-current flow mode depending

on the relative direction of flow of the reactant streams for the exothermic and endothermic reaction.

The recuperative, or heat exchanger, reactor offers several advantages over the directly coupled adiabatic reactor and the reverse flow reactor. Here, the products of the endothermic reaction are always separated from the combustion products. Since the exothermic side is spatially separated from the endothermic side, air can also be used for combustion instead of oxygen and the challenge of nitrogen separation from the product mixture does not exist. This in turn avoids the capital cost resulting from the installation of an oxygen separation unit and / or the operational cost resulting from compressing the air (along with nitrogen) to the process pressure. Heat exchanger reactors offer other operational flexibilities since the operating parameters of exothermic and endothermic streams, such as the inlet velocity, feed concentration etc., can be adjusted independently without affecting the other stream.

A review on coupling of exothermic and endothermic reactions and some discussion of the merits and demerits of various modes of coupling are discussed by Kolios et al., (2000), Zafir and Gavriilidis (2003), Deshmukh and Vlachos, (2005). Most of the work on heat exchanger reactors for coupling exothermic and endothermic reactions, as mentioned earlier, was focused either on wall catalyst-coated reactors (Ismagilov et al., 2001; Venkataraman et al., 2002; Venkataraman et al., 2003; Zafir and Gavriilidis, 2001, 2003) or on monolith reactors (Kolios et al., 2001, 2002). Recently, there are several research activities directed towards developing micro-reactors for coupling exothermic and endothermic reactions (Kolios et al., 2005; Deshmukh and Vlachos, 2005). However, a full discussion of steady state and dynamic behavior exhibited by these reactor systems is not available in the literature. In this chapter, we have made an attempt to analyze and compare the performance of counter-current and co-current packed bed reactors. A parametric study showing the effects of the wall heat transfer coefficients and the Damkohler number for the exothermic reaction on the conversion of the endothermic reaction and on the temperature peak of the exothermic reaction is presented. Hot-spot formation and suitable measures to reduce the hot spot by catalyst

activity profiling are also discussed. The reactor length and the flow rate are treated, as the design and operational parameters, respectively, and their implications on the reactor performance are analyzed. Some of the key features of the transient behavior exhibited by the recuperative coupling of exothermic and endothermic reactions are also presented.

3.2 One Dimensional Pseudo-homogeneous Plug Flow Model

This section presents the pseudo-homogeneous plug flow model for counter-current and co-current reactors with irreversible first order exothermic and endothermic reactions. These model equations are used to examine the richness of the behavior exhibited by these reactors. The following assumptions are made in the development of the model:

- i) The resistance across the gas-solid film for heat and mass transfer is assumed to be negligible.
- ii) Axial mass and heat dispersions are neglected.
- iii) Axial conduction in the wall is not included, and a constant heat transfer coefficient has been assumed along the length of the reactor.
- iv) Physical properties of fluids and the heat of reactions are assumed to be independent of temperature, and the total pressure of the system is constant.

The dimensionless governing equations are:

- a) for the endothermic side,

Mass Balance:

$$\frac{\partial x_g^c}{\partial \tau} + \frac{1}{Da^c} \frac{\partial x_g^c}{\partial \xi} - \eta(\xi)(1 - \varepsilon_b^c) e^{\gamma^c \left(\frac{\theta_g^c}{1 + \theta_g^c} \right)} (1 - x_g^c) = 0 \quad (3.1)$$

Energy Balance:

$$\begin{aligned}
 (\varepsilon_b^c + (1 - \varepsilon_b^c) \frac{\rho_s^c C_{ps}^c}{\rho_g^c C_{pg}^c}) \frac{\partial \theta_g^c}{\partial \tau} + \frac{1}{Da^c} \frac{\partial \theta_g^c}{\partial \xi} + \frac{4U^{*c}}{Da^c} (\theta_g^c - \theta_g^h) \\
 - \eta(\xi) \beta^c (1 - \varepsilon_b^c) e^{\gamma^c \left(\frac{\theta_g^c}{1 + \theta_g^c} \right)} (1 - x_g^c) = 0
 \end{aligned} \tag{3.2}$$

b) for the exothermic side,

Mass Balance:

$$\psi \frac{\partial x_g^h}{\partial \tau} \pm \frac{1}{Da^h} \frac{\partial x_g^h}{\partial \xi} - \alpha(\xi) (1 - \varepsilon_b^h) e^{\gamma^h \left(\frac{\theta_g^h}{1 + \theta_g^h} \right)} (1 - x_g^h) = 0 \tag{3.3}$$

Energy Balance:

$$\begin{aligned}
 (\varepsilon_b^h + (1 - \varepsilon_b^h) \frac{\rho_s^h C_{ps}^h}{\rho_g^h C_{pg}^h}) \psi \frac{\partial \theta_g^h}{\partial \tau} \pm \frac{1}{Da^h} \frac{\partial \theta_g^h}{\partial \xi} - \frac{4U^{*h}}{Da^h} (\theta_g^c - \theta_g^h) \\
 - \alpha(\xi) \beta^h (1 - \varepsilon_b^h) e^{\gamma^h \left(\frac{\theta_g^h}{1 + \theta_g^h} \right)} (1 - x_g^h) = 0
 \end{aligned} \tag{3.4}$$

In Eqs. 3.3 and 3.4, the positive sign is used for the co-current reactor and the negative sign for the counter-current reactor. Here, $\eta(\xi)$ and $\alpha(\xi)$ are the position dependent catalyst activity for the endothermic and exothermic reactions, respectively. Both $\eta(\xi)$ and $\alpha(\xi)$ are set as unity for the cases with no catalyst activity profiling. The boundary conditions and initial conditions used for solving Eqs. 3.1-3.4 are given below.

Co-current reactor:

at $\xi = 0$,

$$x_g^c = x_{g,in}^c = 0; \theta_g^c = \theta_{g,in}^c = 0; x_g^h = x_{g,in}^h = 0; \theta_g^h = \theta_{g,in}^h = 0, \tau \geq 0$$

at $\tau = 0$,

$$x_g^c = \theta_g^c = x_g^h = \theta_g^h = 0, \forall \xi$$

Counter-current reactor:

at $\xi = 0$,

$$x_g^c = x_{g,in}^c = 0; \theta_g^c = \theta_{g,in}^c = 0, \tau \geq 0$$

at $\xi = 1$,

$$x_g^h = x_{g,in}^h = 0; \theta_g^h = \theta_{g,in}^h = 0, \tau \geq 0$$

at $\tau = 0$,

$$x_g^c = \theta_g^c = x_g^h = \theta_g^h = 0, \forall \xi$$

The other dimensionless parameters used in the model are given below with $j = c$ and h for the cold and hot side respectively:

$$x_g^j = \frac{C_0^j - C^j}{C_0^j}, \quad \xi = \frac{z}{L}$$

$$Da^j = \frac{k^j(T_{ref})L}{u_g^j}, \quad \tau = k^c(T_{ref})t$$

$$\gamma^j = \frac{E^j}{R_g T_{ref}}, \quad \theta_g^j = \frac{T^j - T_{ref}}{T_{ref}}$$

$$U^{*c} = \frac{UL}{\rho_g^c C_{pg}^c d_i u_g^c}, \quad \beta^j = \frac{-\Delta H^j C_0^j}{\rho_g^j C_{pg}^j T_{ref}}, \quad \psi = \frac{k^c(T_{ref})}{k^h(T_{ref})} = \frac{Da^c}{Da^h}$$

$$U^{*h} = U^{*c} * \Omega, \quad \Omega = \frac{\rho_g^c C_{pg}^c u_g^c}{\rho_g^h C_{pg}^h u_g^h}$$

The parameters considered in the sensitivity analysis are the Damkohler number (Da^j , the ratio of flow time to the reaction time), dimensionless wall heat transfer coefficient (U^{*j}), dimensionless heat of reaction (β^j), and dimensionless activation energy (γ^j). Some of the correlations used to estimate the wall heat transfer coefficient are provided in Appendix B. For the counter-current reactor, the feed for the endothermic reaction

enters at the axial position, $\xi=0$, and the feed for the exothermic reaction enters at the opposite end of the reactor, i.e. at the axial position, $\xi=1$ (position-1). For the co-current reactor, the feed for both exothermic and endothermic reactions enter at the axial position, $\xi=0$ (position-0).

3.3 Solution Procedure

The transient model equations (Eqs. 3.1-3.4) are solved by the Method-Of-Lines (MOL) approach (van de Wouwer et al., 2001). In the MOL approach, partial differential equations (PDE) are converted to a set of ordinary differential equations (ODE) by suitable discretization of spatial derivatives and the resulting ODEs in time are integrated by stiff solvers. Here, we have used a second order upwind finite difference scheme for the discretization of spatial derivatives. The discretization scheme used is modified to have the Total Variation Diminishing (TVD) property to avoid spurious oscillations (Tannehill et al., 1997) and is explained in the Section 3.4.1. The grid independence of the solution is verified and the number of nodes used for the simulation in this work is 250, unless otherwise stated. The ODEs are integrated using LSODE solver from the Netlib libraries.

3.4.1 Total Variation Diminishing Scheme (TVD)

The numerical solution to the hyperbolic partial differential equations employing higher order spatial discretization schemes results in artificial oscillations. This is called the Gibbs phenomenon. Godunov (1959) has shown that the monotone behavior of a solution cannot be assured for finite-difference methods with more than first order accuracy. This monotone property is very desirable when discontinuities are computed as part of the solution. Though the first order discretization schemes avoid the oscillations, they suffer from poor solution accuracy (highly dissipative). Harten (1983) proved that if higher order schemes can be modified using total variation diminishing algorithms then those schemes will be, in turn, monotonicity preserving and then the higher-order method will avoid spurious oscillations.

Lax (1973) defined total variation (TV) of a variable, $u = f(x)$ as,

$$TV = \int \left| \frac{\partial u}{\partial x} \right| dx$$

A numerical method is said to be total variation diminishing, or TVD, if

$$TV(u^{n+1}) \leq TV(u^n)$$

Here x is the independent variable and n refers to the instant of time (second independent variable). For TVD preserving high order discretization schemes, the solution is first order near discontinuities and higher order in smooth regions. The transition to higher order is accomplished by the use of slope limiters on the dependent variables or flux limiters. We have employed the guidelines provided by Harten (1984) to make our second order discretization scheme, TVD preserving. We have also used the van Leer limiter (1982) in the above scheme. The numerical first derivatives calculated with and without TVD algorithm are presented below.

First derivatives based on II order upwind discretization scheme without TVD preserving algorithm are:

$$\left. \frac{du}{dx} \Big|_i = \begin{cases} \frac{3u_i - 4u_{i-1} + u_{i-2}}{2h}, i = 3, \dots, N \\ \frac{u_3 - u_1}{2h}, i = 2 \\ \frac{-3u_1 + 4u_2 - u_3}{2h}, i = 1 \end{cases} \right\}$$

with

$$h = \frac{x_{final} - x_{initial}}{N - 1}.$$

The first derivatives based on TVD preserving II order upwind discretization scheme are:

$$\left. \frac{du}{dx} \Big|_i = \begin{cases} \frac{F_1 - F_2}{h}, i = 3, \dots, N-1 \\ \frac{u_i - u_{i-1}}{h}, i = 2 \text{ \& } N \\ \frac{u_2 - u_1}{h}, i = 1 \end{cases} \right\}$$

where,

$$F_1 = u_{i-1} + \frac{\psi_{i-1}}{2}(u_{i-1} - u_{i-2})$$

$$F_2 = u_i + \frac{\psi_i}{2}(u_i - u_{i-1})$$

$$h = \frac{x_{final} - x_{initial}}{N-1}$$

$$\psi_i = \begin{cases} \frac{r_i + |r_i|}{1 + |r_i|}, u_i - u_{i-1} > \delta \\ 0, u_i - u_{i-1} \leq \delta \end{cases}$$

$$r_i = \frac{u_{i+1} - u_i}{u_i - u_{i-1}}$$

In the above formulation N refers to number of nodes used for the discretization and δ is arbitrarily set as 1.0e-5.

Different discretization schemes, such as first order, second order and fourth-order, and the second order with TVD preserving discretization scheme, were tested for standard steady state and transient problems such as: the analytical solutions of the hyperbolic Burger equations, propagation front of the combustion flame, temperature profiles in a methanator (tubular reactor carrying out combustion of methane). It was found that first order discretization schemes could capture the solution only with larger number of nodes.

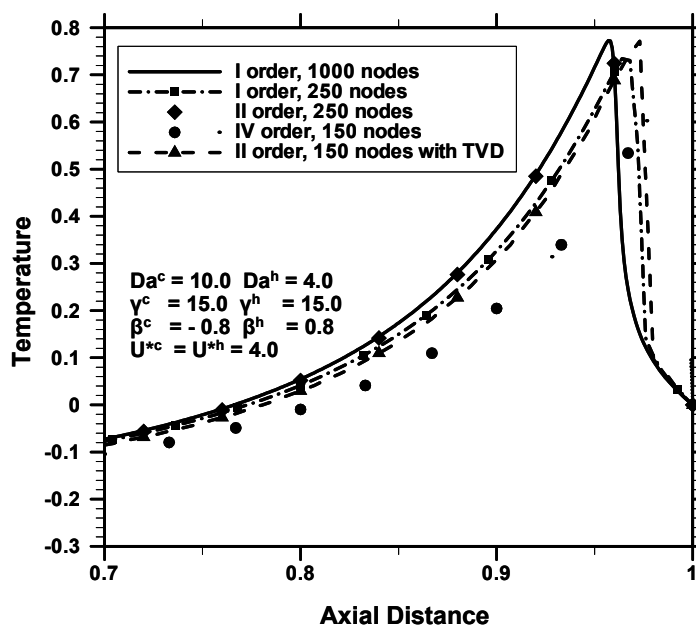


Figure 3-1: Effect of Different Discretization Schemes on Exothermic Temperature Profiles in Counter-current Reactors (Parameters as shown in Table 3-1)

Higher order discretization schemes capture the solution with lower number of nodes but suffer from Gibb's oscillations near the shock or wave/reaction front. On the other hand, the second order discretization scheme with TVD preserving algorithm avoids the spurious oscillations with lower number of nodes. The spurious oscillations mask the real solution especially during the transients (wrong-way in packed beds).

All the above schemes were tested for the counter-current heat exchanger reactor for the parameters shown in Table 3-1 and the temperature profile at the exothermic side simulated with different discretization schemes are presented in Figure 3-1. The profile simulated with 1000 nodes (minimum number of nodes to produce the grid independent solution) and first order discretization scheme is used as the bench-mark (Kulkarni, 1996). The profiles obtained with 250 nodes closely match the bench-mark for all the discretization schemes (with and without TVD algorithm) except for the first order discretization (with 250 nodes) scheme. With lower number of nodes, say 150 nodes, there is a discrepancy between the bench-mark case and the profiles simulated with

other discretization schemes. The fourth order backward upwind discretization scheme, with 150 nodes, results in a wrong (unconverged) profile (with lower temperature peak and lower conversion for endothermic reaction). This may be due to the propagation of error as the exothermic and the endothermic sides are coupled and the convection direction is opposite to each other, in the counter-current reactor. It is found that for TVD preserving II order scheme, with 150 nodes, the calculated temperature peak, as well as the exit conversion for endothermic reaction, closely match that of the benchmark case.

As TVD schemes are important to capture the transients accurately, they are used in this work, and the number of nodes chosen for the simulation of the counter-current reactor is 250. For the co-current reactors 150 nodes were sufficient to produce the grid-independent solution.

Table 3-1: The Parameters Used for Base Case Simulation (For 1-D Models)

Parameters	Endothermic	Exothermic
Da	10	4
β	-0.8	0.8
γ	15	15
U*	4	4
Activity	$\eta = 1$	$\alpha = 1$

3.4.2 Arrangement of Variables

The partial differential transient model equations are converted to ordinary differential equations by the method-of-lines. The resulting ordinary differential equation in time can be integrated using Adam's explicit solver (using the option, MF=10, in LSODE) or by the implicit solver (option MF = 22 in LSODE). While using the explicit solver, the spatial and temporal steps are chosen such that the Courant criterion (Tannehill et al., 1997) is satisfied. The implicit solvers have an infinite domain of stability and, hence, a larger spatial and/or time step could be used. Often, in such situation, the time step is

limited by the fastest time scale in the problem. The implicit solver used in LSODE is a modified Gear's algorithm for stiff differential equations. The Gear's algorithm involves matrix inversion / LU decomposition and, hence, is prone to longer computation time especially if the matrix becomes very sparse.

A proper strategy of arranging the differential equations and the variables reduces the total time for computation with the implicit solving procedure. The total number of variables in the discretized transient model (discretized partial differential equations) is the product of the number of nodes and the number of variables in the governing equations / model ($N_{tot} = N_{node} * N_{model}$) and all these differential equations are solved simultaneously.

$n:$	<i>1</i>	<i>2</i>	<i>3</i>	N_{model}	$N_{model}+1$	N_{tot}
$u_{ij}:$	$u_{1,1}$	$u_{1,2}$	$u_{1,N_{model}}$	$u_{2,N_{model}}$	$u_{N_{node},N_{model}}$

Scheme-i

$n:$	<i>1</i>	<i>2</i>	<i>3</i>	N_{node}	$N_{node}+1$	$N_{node}+2$	N_{tot}
$u_{ij}:$	$u_{1,1}$	$u_{2,1}$	$u_{N_{node},1}$	$u_{1,2}$	$u_{2,2}$	$u_{N_{node},N_{model}}$

Scheme-ii

Figure 3-2: Two different schemes to arrange the variables (u_{ij}) and the differential equations ($i (= 1 \text{ to } N_{node})$ – node index, $j (=1 \text{ to } N_{model})$ – variable index, $n (=1 \text{ to } N_{tot})$ – running index of all the variables in the system with $N_{tot}=N_{node} * N_{model}$)

There are two ways by which the variables are arranged (numbered): (i) All the model variables at first node are arranged first (numbered) and then the model variables at the second node are numbered. This procedure is repeated until the last node of the domain is covered. Once the variables and the equations are numbered in this fashion, then they are integrated in time. (ii) In the second approach, the first variable of the governing equations at all the nodes is arranged first. Then the second variable of the governing equations is numbered for all the nodes. This procedure is repeated until all the

variables of the governing equations (and for all the nodes) are arranged. The schematic of these two schemes, with the positioning and numbering of the variables, are shown in Figure 3-2.

It is observed that the second scheme (Scheme-ii) of arranging the variables / equations results in larger computation time. This is due the fact that sparseness is scattered throughout the domain of the matrix in the second scheme and, hence, takes more time. It is to be noted that the model equations at node i relate all the variables at the node i strongly compared to the variables in the neighboring nodes. And usually in physical systems the number of model variables is much less than the number of nodes. Hence, the first scheme (Scheme-i) of arranging the variables brings the dependent variables close together in the matrix representation and reduces the computation time. This phenomenon of reduction in the computation time is similar to that observed in solving the steady state models for crude distillation columns by the Newton method. The model equations for the crude distillation columns result in a block tri-diagonal matrix. The numbering and positioning of pump-arounds and side strippers (extra features of the distillation column) determine the placement of variables near the diagonal elements. It is observed that if variables corresponding to pump-arounds and side-strippers are placed close to the diagonal variables, then the computation time decreases. More details on the variable placement and the effect of computation time can be found in Ramaswamy (1999). We have used Scheme-i for all our computations in this work.

3.4 Results and Discussions

In this section, steady state (Section 3.5.1) and dynamic behavior (Section 3.5.2) observed in the counter-current and co-current reactors are analyzed and the predicted conversion, temperature profiles and the volumetric productivity are presented. The effects of design and operational parameters on the performance of these reactors and in reducing the hot spot are discussed. The role of inert packing in some sections of the reactor is also addressed with reference to improving the efficiency of these reactors.

3.5.1 Steady State Behavior

Temperature Profiles: The computed temperature profiles in the counter-current and co-current heat exchanger reactors, for the base case, are presented in Figure 3-3. The parameters used for this base case simulation are reported in Table 3-1. The counter-current reactor exhibits a phenomenon termed here as cold pinch and hot pinch cross-over points. At these cross-over points both the exothermic and endothermic streams have identical temperature.

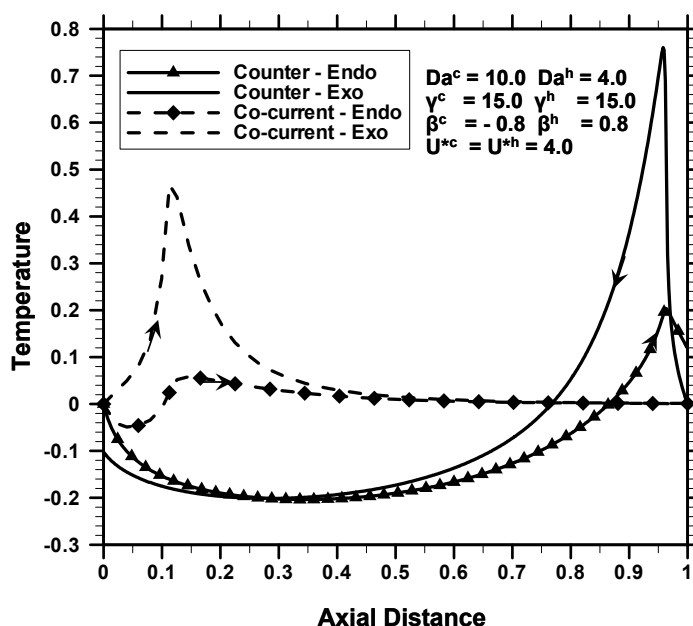


Figure 3-3: Temperature Profiles in Counter-current and Co-current Reactors

The cold pinch cross-over point occurs near the inlet for the endothermic feed (position-0) because of two simultaneous phenomena – (i) heat exchange between exothermic and endothermic stream, and (ii) the endothermic chemical reaction. Here, the reactants for the endothermic reaction transfer heat to the effluent of the exothermic reaction from the inlet (position-0) up to the cold pinch cross over point. In addition to this, the endothermic reaction occurs in this region and, hence, a drop in the temperature (from the inlet value) is observed in the temperature profile on the endothermic reaction side.

There is also a hot pinch cross-over point near the inlet of the feed for the exothermic reaction (position-1). From this hot pinch cross-over point to position-1, the effluent of the endothermic reaction heats the reactants for the exothermic reaction.

In some of the experimental and modeling studies published in the literature, the cold-pinch cross over point is not mentioned. This may be attributed to a number of reasons such as dissimilar reaction rates and heats of exothermic and endothermic reactions, the use of shorter reactors, etc. One way of eliminating this cold pinch cross-over is by reducing the activity of the catalyst (by using inert packing in a section of the reactor, etc) for the endothermic reaction near position-0, which alters the effective length of the catalyst bed. The effect of the length of the reactor on the cold pinch cross-over point and the hot spot are discussed in a later section. The second way of avoiding the cold pinch cross-over point is by using non-similar feed temperature for the exothermic and endothermic streams. Figure 3-4 shows a case where the cold pinch cross-over is not observed. Here the inlet temperature of the exothermic stream is higher than the inlet temperature for the endothermic stream. This arrangement requires the pre-heating of the exothermic stream and that can be carried out by utilizing the sensible heat of the endothermic stream leaving the reactor.

Figure 3-3 shows that the temperature peak observed in the counter-current reactor is higher than that of the co-current reactor. This higher peak on the exothermic side in the counter-current reactor, near position-1, is due to the increase in the rate of the exothermic reaction because of heating of its feed by the hot effluent of the endothermic reaction.

The above observation is in line with that of Venkataraman et al. (2002) where it was shown that the counter-current operation results in a higher temperature peak compared to the co-current reactor (for catalytic wall coated reactor).

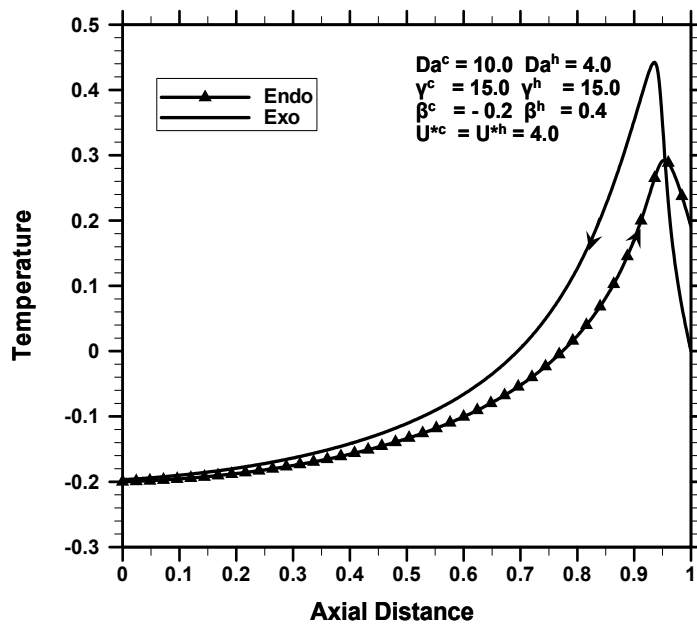


Figure 3-4: Temperature Profiles in Counter-current Reactor without Cold Pinch Cross-Over Point

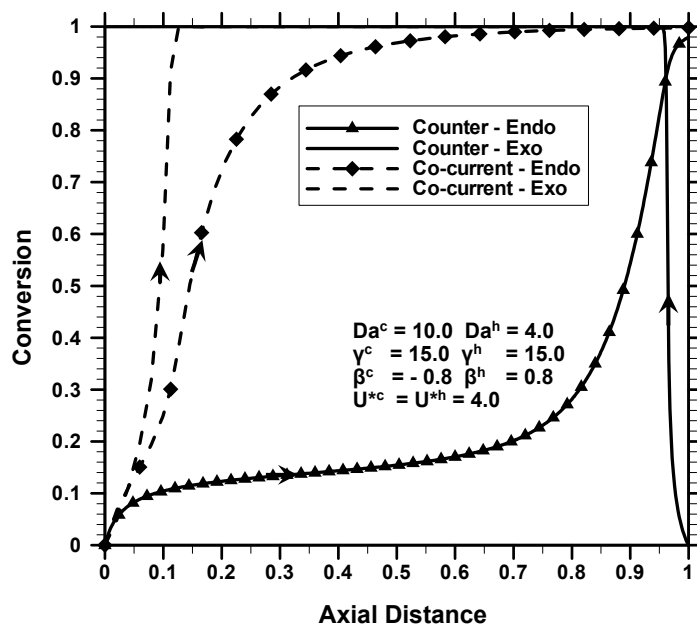


Figure 3-5: Conversion Profiles in Counter-current and Co-current Reactors

Conversion Profiles: Figure 3-5 shows the conversion profiles for the co-current and counter-current reactors. The exit conversion of the endothermic reaction in the co-current reactor is greater than that in the counter-current reactor. This higher conversion in the co-current reactor is due to the endothermic stream spending more time in the reactor at higher temperature than in the counter-current reactor. The conversion for the endothermic reaction in the adiabatic reactor is also calculated (by setting $U^{*c} = U^{*h} = 0$, in the model) for similar parameters used in Table 3-1. It is found that the recuperative reactors results in higher exit conversion for the endothermic reaction compared to that in the adiabatic reactor because of coupling with the exothermic reaction. The percentage increase in the volumetric productivity (the rate of product produced per unit reactor volume, based on products of the endothermic reaction) is 262 % in the co-current reactor with respect to the adiabatic reactor. Similarly the percentage increase in the volumetric productivity between the adiabatic and the counter-current reactor is 252 %, which is less than that observed with co-current reactor for the parameters reported in Table 3-1.

The simulation studies with an irreversible exothermic reaction and a reversible endothermic reaction are also carried out, and the temperature and conversion profiles obtained were qualitatively similar to those being discussed in this chapter for the identical conditions. The thermodynamic equilibrium becomes favorable at higher temperatures for the endothermic systems and this is one reason for obtaining the similar qualitative behavior with reversible kinetics.

Effect of Damkohler Number (Da^h) for Exothermic Reaction: We carried out the parametric sensitivity analysis to determine the effect of Da^h on the temperature peak and on the exit conversion of the endothermic reaction.

Co-current Reactor: Figure 3-6a shows the temperature peak on the exothermic side and the conversion for the endothermic reaction, for the co-current reactor. With an increase in Da^h , the rate of exothermic reaction increases, hence the temperature peak on the exothermic side and the conversion for the endothermic reaction increase. Above

a critical value of Da^h (~ 4 for this case) conversion for the endothermic reaction remains at unity. A further increase in Da^h , increases the temperature peak of the exothermic reaction and the corresponding exit temperature of both streams. Hence, in a real system, if an excessive hot spot is anticipated in the co-current reactor, an effort could be made to reduce it (by either diluting the catalyst bed or by increasing the inlet velocity, both of which reduces the Damkohler number), without sacrificing the conversion for the endothermic reaction.

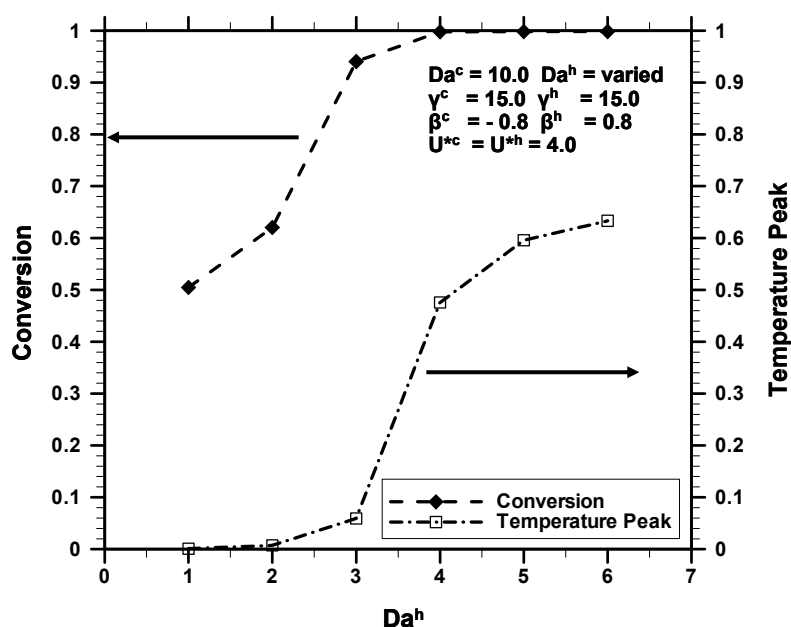


Figure 3-6a: Effect of Damkohler Number for the Exothermic Reaction on Conversion of the Endothermic Reaction and Temperature Peak of the Exothermic Reaction in the Co-current Reactor

Counter-current Reactor: In counter-current reactor, the effect of Da^h is more complex and the system exhibits multiple steady states for the parameter range studied. Kolios et al. (2002) have also observed multiple steady states in the counter-current reactors. The typical ignition (cold bed) and extinction branch (hot bed) for the exit conversion of the endothermic reaction is shown in Figure 3-6b. It is seen that beyond the parametric range where hysteresis occurs, an increase in Da^h gradually decreases the conversion for the endothermic reaction. At higher Da^h , the temperature peak for the

exothermic reaction (and also for the endothermic reaction) and the hot pinch cross-over occur very near the inlet for the exothermic feed (position-1).

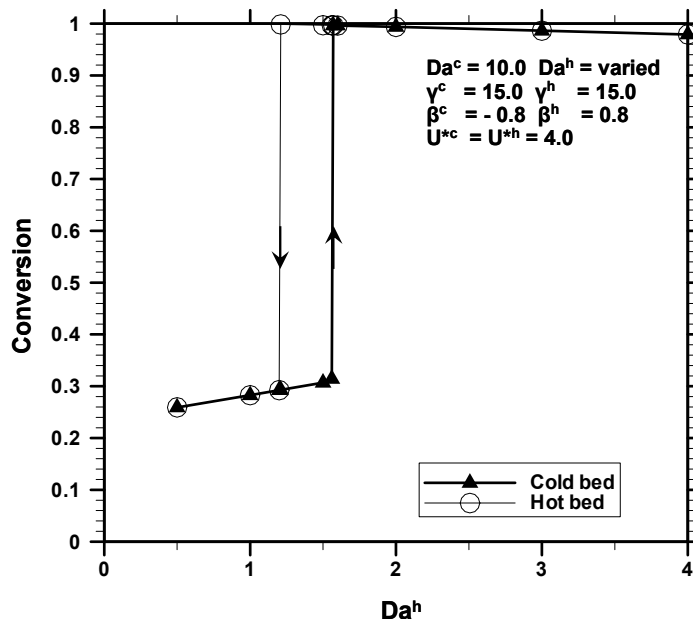


Figure 3-6b: Effect of Damkohler Number for the Exothermic Reaction on Conversion of the Endothermic Reaction in the Counter-current Reactor

Hence, the endothermic stream leaves the reactor at a higher temperature. The residence time between the position of the endothermic peak and the endothermic exit decreases for high Da^h , and hence, the exit conversion for the endothermic reaction decreases. For lower Da^h , the temperature peak for the exothermic reaction (and hence that of the endothermic reaction) occurs further away from the feed inlet for the exothermic reaction (position-1). This increases the conversion of the endothermic reaction. Frauhammer et al. (1999) have also observed a similar trend in a monolith reactor, where they have shown that by decreasing the length of the combustion catalyst bed, the temperature peak for the exothermic reaction and the conversion for the endothermic reaction increase in the counter-current reactor.

Effect of Wall Heat Transfer Coefficient: The effect of wall heat transfer coefficient on the heat exchanger reactor performance is reported below.

Co-current Reactor: The exit conversion for the endothermic reaction and the temperature peak on the exothermic side of the co-current reactor are plotted in Figure 3-7 for different dimensionless wall heat transfer coefficients, U^* ($=U^{*c} = U^{*h}$). The parameters reported in Table 3-1 were used for the simulation except for U^* . The magnitude of the temperature peak on the exothermic side is the largest when $U^* = 0$ and is equal to the adiabatic temperature of the exothermic reaction, β^h . As U^* increases, the magnitude of the temperature peak on the exothermic side decreases and the exothermic reaction is suppressed at a critical U^* . Figure 3-8 shows the temperature profiles for the exothermic reaction side along the reactor length for different U^* . The conversion of the endothermic reaction increases for lower U^* (< 4) and reaches a plateau at complete conversion. Further beyond the plateau, the conversion decreases with an increase in U^* . The thermal coupling supplies the heat to the endothermic reaction and, hence, the conversion increases for lower U^* . For sufficiently higher U^* , the exothermic reaction is strongly affected by the endothermic reaction, and since the rate of heat consumption by the endothermic reaction is greater than the rate of heat generation ($\beta^c Da^c > \beta^h Da^h$), the exothermic reaction is quenched (Figure 3-8).

This results in lower temperature along the reactor on both sides. This in turn yields lower conversions for the endothermic and exothermic reactions at very high U^* . The suppression of the exothermic reaction is largely pronounced at higher U^* , say $U^* = 10$ in Figure 3-8. This suppression of the exothermic reaction by the endothermic reaction is similar to that observed in a directly coupled adiabatic reactor (Ramaswamy et al., 2005a) and is discussed in Chapter 5.

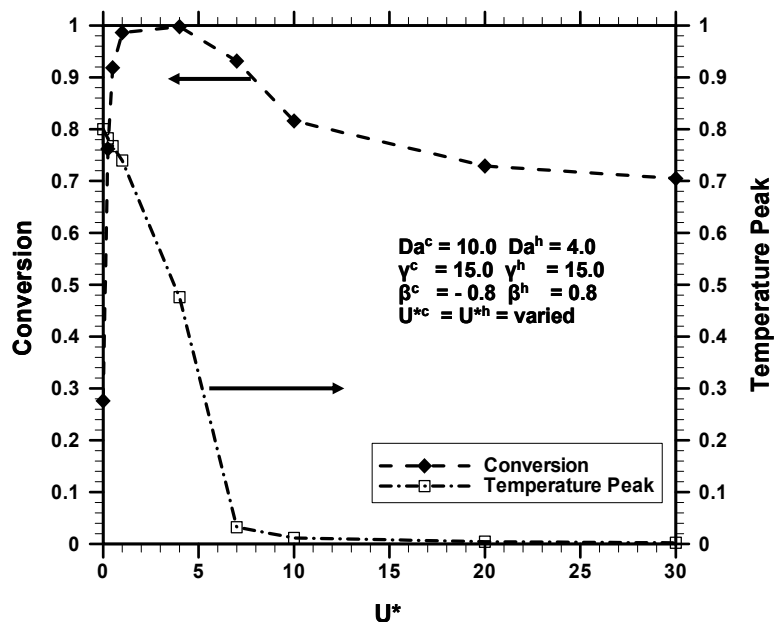


Figure 3-7: Effect of Dimensionless Wall Heat Transfer Coefficient on the Conversion of Endothermic Reaction and the Temperature Peak of the Exothermic Reaction in the Co-current Reactor

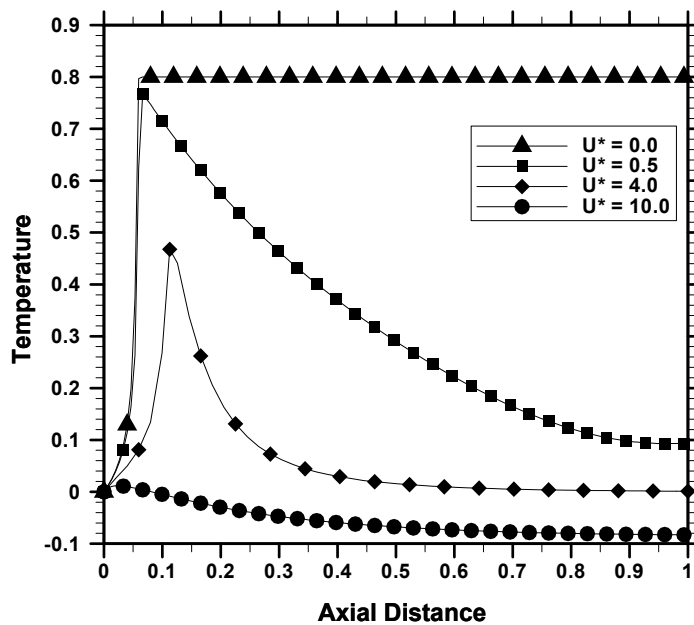


Figure 3-8: Effect of Dimensionless Wall Heat Transfer Coefficient on the Temperature Profiles for the Exothermic Reaction (Parameters same as Figure 3-7)

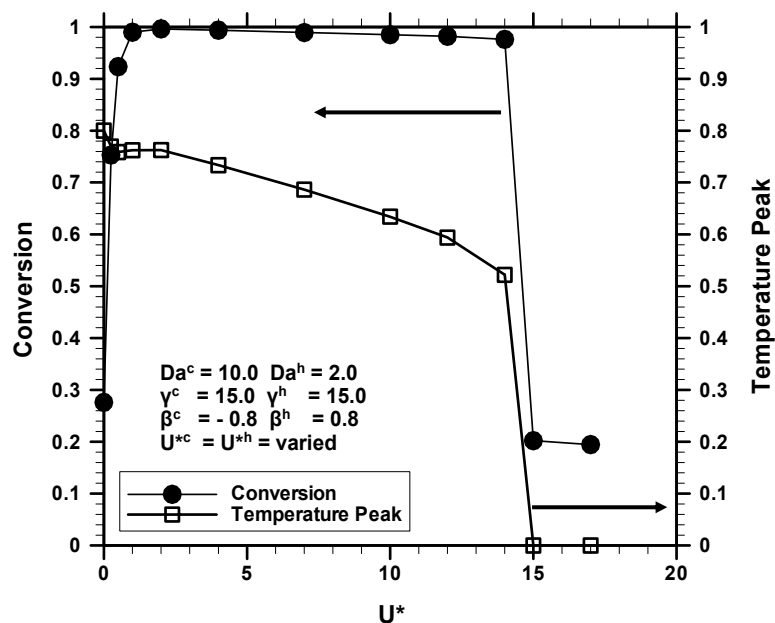


Figure 3-9: Effect of Dimensionless Wall Heat Transfer Coefficient on Temperature Peak of Exothermic Reaction and Conversion of the Endothermic Reaction in the Counter-current Reactor

Counter-current Reactor: For the counter-current reactor (Figure 3-9), the temperature peak on the exothermic side gradually decreases with increase in U^* and falls drastically upon reaching a critical U^* (exothermic reaction is extinguished). The conversion (Figure 3-9) of the endothermic reaction increases with U^* for lower heat transfer coefficients, plateaus and then decreases for higher heat transfer coefficients. At higher wall heat transfer coefficients, the exothermic reaction is suppressed, yielding poor conversion for the endothermic reaction, and beyond the critical U^* , the conversion is even less than that observed in the adiabatic reactor (corresponding to $U^* = 0$). This is due to the counter-current mode of heat exchange and the resulting cold pinch cross-over. The temperature and conversion profiles for the case with $U^* = 17$ are compared with those of the equivalent adiabatic reactor in Figures 3-10a and 3-10b. It is to be noted that for this case, the magnitude of the cold pinch cross-over point is not only less than the feed temperature but also less than the exit temperature of the equivalent adiabatic reactor and this cross-over point occurs close to the centre of the

reactor. From the position-0 to the cold pinch cross-over point, the endothermic stream heats the exothermic stream while exactly the opposite occurs in the next half of the reactor. This additional heat loss along with the heat loss due to endothermic reaction lowers the temperature of the cold pinch-cross over point below the exit temperature of the adiabatic reactor. Hence, the rate of the endothermic reaction is reduced in the first part of the reactor and this in turn lowers the conversion at the exit. This case has been simulated with $Da^h = 2$ and the other parameters as reported in Table 3-1. The results obtained with $Da^h = 4$ follow the same trend but the critical U^* is larger than the one observed with $Da^h = 2$.

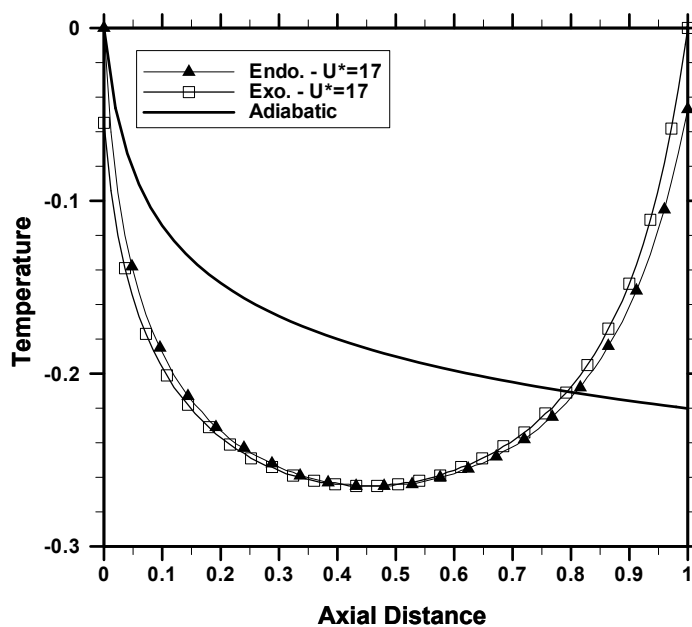


Figure 3-10a: Temperature Profiles in the Counter-current Reactor (for $U^* = 17$ and other parameters as reported in Table 3-1) compared to Temperature Profile in the Adiabatic Endothermic Reactor

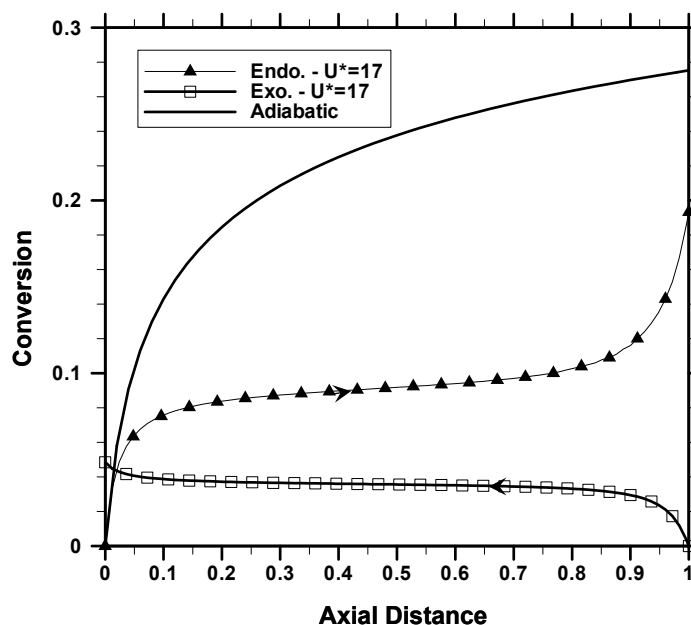


Figure 3-10b: Conversion Profiles in the Counter-current Reactor (for $U^* = 17$ and other parameters as reported in Table 3-1) compared to that in the Adiabatic Endothermic Reactor

Effect of Catalyst Activity Profiling: We have carried out simulations with a position dependent catalyst activity profile for the exothermic reactions, in an attempt to reduce the hot spot temperature without sacrificing the exit conversion for the endothermic reaction. A simple exponential catalyst profiling was assumed. This can be modeled by setting $\alpha = 1 - \exp(-k_1 \xi)$, where k_1 is set to 20. The observed temperature profile is plotted in Figure 3-11 for the co-current and counter-current reactors. The effect of activity profiling on reducing the peak temperatures are discussed below. The implementation of a spatially varying activity profiling may be difficult from the practical point of view, but this study provides an insight into such possibilities. An easier way of activity profiling, using inert packing is discussed later.

Co-current Reactor: The activity profiling reduces the steady state temperature peak of the exothermic reaction by around 58% (compare Figures 3-3 and 3-11), while the

exit conversion for the endothermic reaction remains constant, for the co-current reactor.

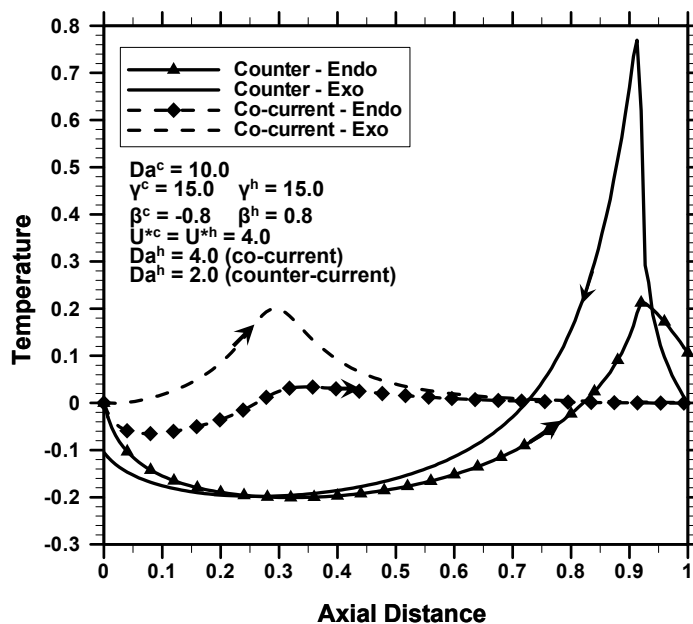


Figure 3-11: Effect of Catalyst Activity Profiling on the Temperature Profile in the Co-current and Counter-current Reactors

The reduction in catalyst activity near the reactor inlet, on the exothermic side, delays the ignition of the exothermic reaction. As the activity of the catalyst for the endothermic reaction and the progress of the endothermic reaction are unaltered, temperature drops more rapidly in the endothermic section compared to the base case. This phenomenon reduces the temperature peak and the magnitude of the temperature profile along the exothermic section. A proper balance of the rate of heat generation and the heat consumption rate by the exothermic and exothermic reaction, respectively, is to be ensured while altering the catalyst activity to avoid either a fall in conversion or the extinction of the exothermic reaction.

Counter-current Reactor: For the counter-current reactor no significant effect of catalyst profiling is observed. The response of counter-current reactors to the reduction in catalyst activity is best explained by analogy to a decrease in Da^h . Reducing the catalyst activity (equivalent to a decrease in Da^h) near the inlet for exothermic reaction

pushes the temperature peak inward into the reactor and the temperature peak and the conversion of the endothermic reaction are higher (till the extinction point).

Design and Operational Implications: For the co-current and counter-current reactors, the design issues such as the selection of tube material with desired heat transfer coefficients and the size and spacing between the tubes are to be addressed as these parameters affect the conversion of the desired reactions. A two dimensional model is required to address the effect of some of these parameters, and this is investigated in the next chapter. This section is limited to the analysis of the effect of two of the design and operational parameters, namely, the length of the reactor and the velocity of the feed streams.

In the model, varying the reactor length is equivalent to varying the Damkohler numbers of both reactions and the dimensionless heat transfer coefficients correspondingly. Table-3-2 reports the results for the key properties of interest in counter-current and co-current reactors for the parameter set mentioned. The first row in the table corresponds to the base case simulation. The reactor length is 'L' for the base case. The results corresponding to the reduced reactor length are reported in rows 2-4 in Table 3-2. The length of the reactor and the velocities of individual streams for each case are also tabulated in parenthesis. For the co-current reactors, with decrease in the reactor length, the conversion of endothermic reaction decreases. This is because of the corresponding reduction in the residence time. The maximum temperature on the exothermic side remains the same for co-current reactors for the range of parameters investigated. On the other hand, for the counter-current reactor, the maximum temperature on the exothermic side varies. For the cases investigated, with decrease in reactor length, the conversion for the endothermic reaction decreases but is higher than that of the co-current reactor for most of the cases. The temperature peak on the exothermic side is always higher than that in the co-current reactor and is close to the adiabatic temperature. The product temperature at the exit of the endothermic side is also reported in Table 3-2. This exit temperature decreases with decrease in reactor length for the counter-current reactors whereas it increases for the co-current reactors. It

is to be noted that for the case corresponding to Row 4 in Table 3-2, no cold pinch cross over point is observed in the counter-current reactor.

Table 3-2: Design and Operational Implications (Recuperative Reactors)

No.	Parameters	Counter-Current Reactor			Co-Current Reactor		
		Temperature Peak on the Exo. side	Exit Conversion for Endo. Reaction	Exit Temperature of the Endo. Stream	Temperature Peak on the Exo. side	Exit Conversion for Endo. Reaction	Exit Temperature of the Endo. Stream
1	$Da^c=10, Da^h=4$ $U^{*c}=U^{*h}=4$ (L, u_g^c, u_g^h)	0.78	0.970	0.130	0.48	0.998	0.000
2	$Da^c=5, Da^h=2$ $U^{*c}=U^{*h}=2$ $(0.5L, u_g^c, u_g^h)$	0.78	0.974	0.106	0.48	0.968	0.010
3	$Da^c=3.75,$ $Da^h=1.5$ $U^{*c}=U^{*h}=1.5$ $(0.375L,$ $u_g^c, u_g^h)$	0.77	0.964	0.090	0.48	0.932	0.020
4	$Da^c=1.875,$ $Da^h=0.75$ $U^{*c}=U^{*h}=0.75$ $(0.1875L,$ $u_g^c, u_g^h)$	0.71	0.850	0.024	0.48	0.680	0.050
5	$Da^c=10, Da^h=2$ $U^{*c}=4, U^{*h}=2$ $(L, u_g^c, 2u_g^h)$	0.97	1.000	0.640	0.48	1.000	0.270
6	$Da^c=5, Da^h=4.0$ $U^{*c}=2, U^{*h}=4$ $(L, 2u_g^c, u_g^h)$	0.65	0.540	0.003	0.50	0.710	-0.113

The heat exchanger reactors offer significant operational flexibility, better than directly coupled adiabatic reactors. The operating parameters such as velocity, feed concentration (and hence Da , β) etc., of any stream can be changed independently without affecting the other stream. Rows 5 and 6 in Table 3-2 report the effect of varying individual stream velocity on the performance of the heat exchanger reactors. With doubling the velocity of the exothermic stream, the conversion and the exit temperature of the endothermic stream increase in both the reactors (compare Row 1 and

Row5 in Table 3-2). This is due to higher rate of consumption of the fuel for combustion. In the counter current reactor, the maximum temperature on the exothermic side is higher than the base case and it exceeds the adiabatic temperature of the exothermic reaction. This is because of heating up of the exothermic feed by the endothermic effluent, which leaves the reactor at very high temperature. Not much change in the maximum temperature is observed in the co-current reactor when doubling the velocity of the reactants for the exothermic reaction. On the other hand, doubling the velocity of the endothermic stream decreases its exit conversion, and the temperature of the endothermic effluent in both co-current and counter-current reactors. In this case, the temperature peak for the exothermic reaction decreases in the counter-current reactor but it increases slightly in the co-current reactor. These studies show that the flow rates of individual streams can be optimized to get a desired performance in these reactors.

The concentration of the individual feed streams, and hence the dimensionless heat of reaction, can also be varied independently to obtain the desired temperature peak and conversion. In all the cases investigated, the counter current reactor gives a higher temperature peak than the equivalent co-current reactor, whereas the counter-current reactor can yield higher conversion with shorter reactor length. These findings are similar to those in counter-current and co-current cooling of exothermic reactions in a fixed bed reactor (de Morais et al., 2004).

Role of Inert Packing: The temperature profiles of the counter-current heat exchanger show the presence of a cold pinch cross-over point near the inlet of the endothermic stream. As mentioned earlier, the cold pinch cross-over point occurs because of the additional heat loss due to the endothermic reaction encountered in the counter-current heat exchanger reactor. The elimination of the cold pinch cross-over without sacrificing the desired volumetric productivity for endothermic reaction may reduce the amount of catalyst requirement. From the earlier discussion, it is clear that a reasonable reduction in the reactor length does not eliminate the cold pinch cross-over point. A drastic reduction in reactor length could eliminate the cold pinch cross-over but at the expense

of the exit conversion for the endothermic reaction and the exothermic one as well. Therefore, there is a need to improve the design of these reactors so that this cross over point can be eliminated. Such improved design should incorporate the following criteria : i) The exothermic and endothermic reaction zones should overlap (occur at the same axial position in both sides, (Frauhammer et al.,1999)). ii) The endothermic reaction should be avoided near the inlet section.

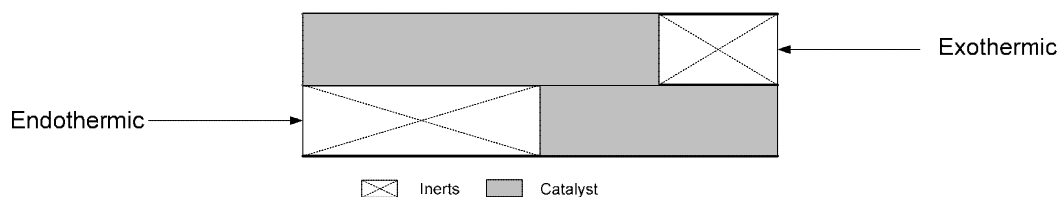


Figure 3-12: Counter-current Heat Exchanger Reactor with Inert Packing

For the counter-current heat exchanger reactor, inert packing is placed from the dimensionless position 0 to 0.5 on the endothermic side. Similarly, inert packing is placed on the exothermic side from position 0.75 to 1.0. Figure 3-12 shows the schematic for this arrangement. This arrangement can be simulated by setting proper values for the activity parameters in the model. Here, $\eta = 0$ when $0 \leq \xi \leq 0.5$ or unity otherwise. Similarly, α is set to zero when $0.75 \leq \xi \leq 1.0$ and is set to unity otherwise. The position and the length of the inert packing should be carefully chosen so that the optimal conversion and temperature peak are obtained. Figures 3-13a and 3-13b compare the temperature and conversion profiles obtained in the reactor of new design with those of original design without inert packing. For both the cases, $\beta^c = -0.4$ and $\beta^h = 0.4$, and the other parameters are the same as those reported in Table 3-1. This particular set of heats of reaction is used in this part of the work so that the role of inert packing is explained in a better way. From Figure 3-13a it is clear that the cold pinch cross-over point is not observed for the reactor design with inert packing. The magnitude of maximum temperature on the exothermic side is reduced and the endothermic effluent leaves the reactor at much lower temperature. From Figure 3-13b it is seen that conversion for the endothermic reaction is almost the same in both reactor designs but the reaction front for the exothermic reaction is pushed inside the reactor for the case with inert packing.

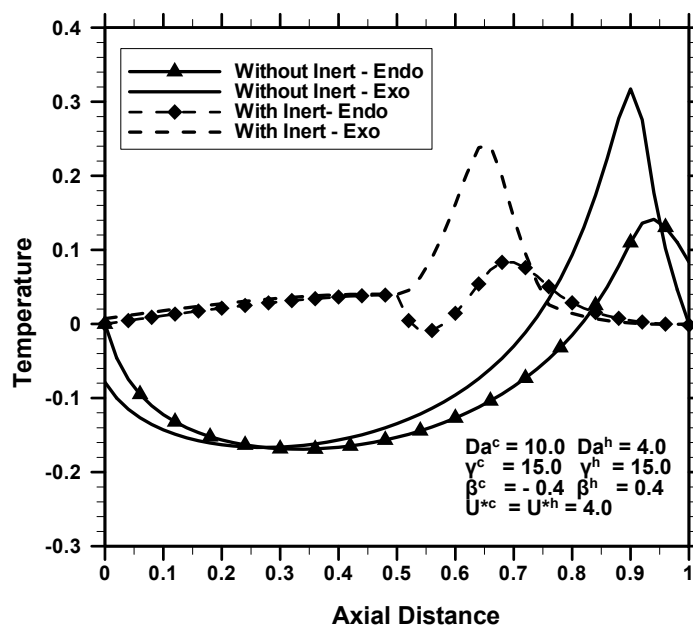


Figure 3-13a: The Role of Inert Packing on the Temperature Profiles of the Counter-current Reactor

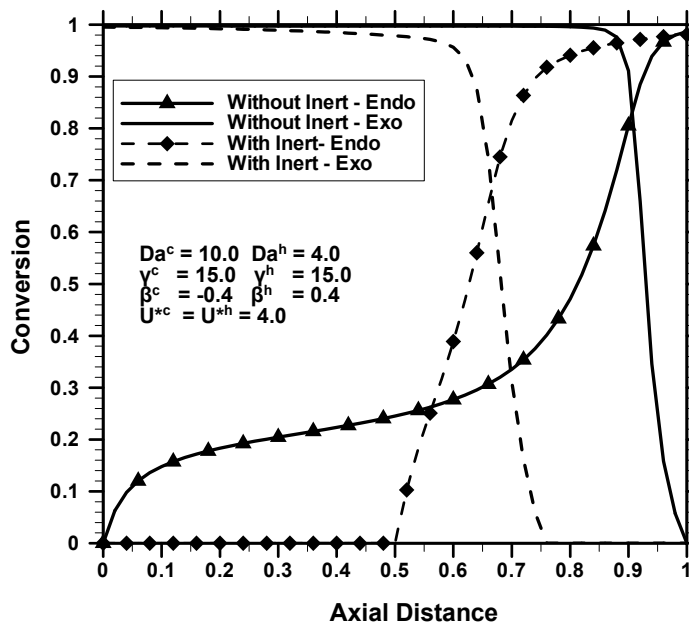


Figure 3-13b: The Role of Inert Packing on the Conversion Profiles of the Counter-current Reactor

The percentage increase in the productivity per unit mass of catalyst (endothermic), in the new design with inert packing, is 99% compared to the case without inert packing. In other words, the same productivity can be achieved with 50% lower catalyst loading in the new design. Thus, by using the inert packing in a part of the counter-current reactor, the length of the catalyst bed and, hence, the amount of catalyst required can be reduced without sacrificing the volumetric productivity.

3.5.2 Dynamic Behavior

This section discusses the key transient features exhibited by heat exchanger reactors.

Evolution of the Temperature Profiles for the Co-current Reactor: The evolution of temperature profiles (at different dimensionless times) at the side of the exothermic reaction for the co-current reactor without catalyst activity profiling is shown in Figure 3-14a. Here, the transient profiles are bounded by the steady state profile. Similarly, the temperature profiles for the case with catalyst activity profiling (exponential activity profile mentioned earlier) is shown in Figure 3-14b and in this case, the transient temperature peaks are no longer bounded for the parameters studied and are greater than the steady state temperature peak. For the catalyst bed with activity profiling, the reduced activity in the initial section of the reactor curtails the exothermic reaction. As a consequence, the concentration of the reactants for the exothermic reaction is high, in this section, and these reactants are convected into the reactor. These reactants, upon contacting the highly active catalyst further downstream, react vigorously resulting in high temperature peaks. With the passage of time, the temperature peak decreases due to convection and cooling by the endothermic reaction. Hence, a careful protocol for the start-up of the reactor has to be established to avoid, for example, catalyst sintering etc.

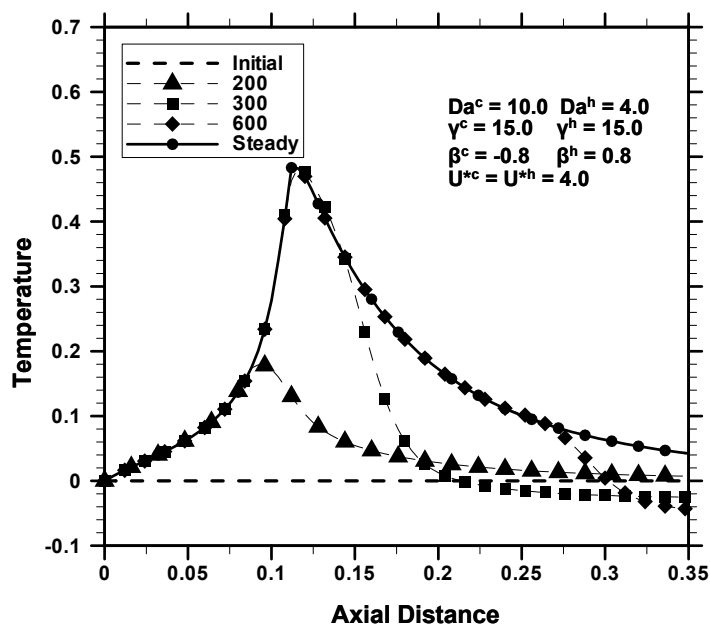


Figure 3-14a: Evolution of the Temperature Profiles of the Exothermic Reaction in a Co-current Reactor (without Activity Profiling)

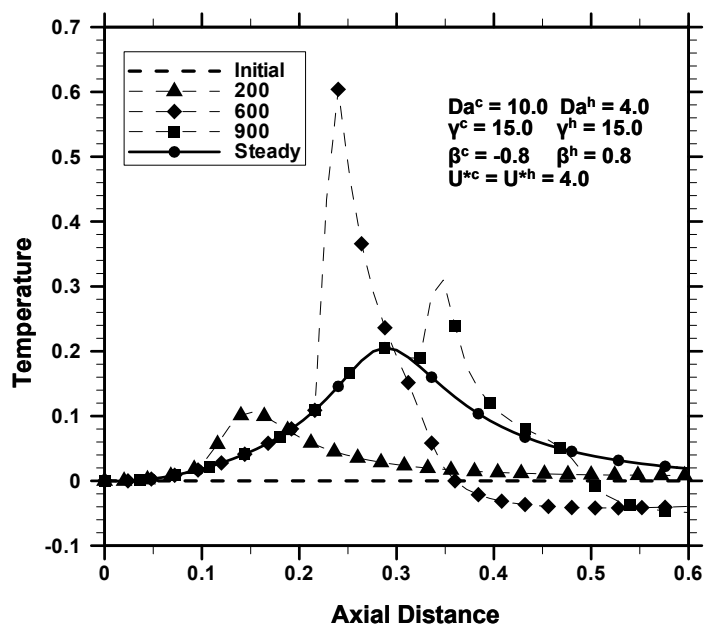


Figure 3-14b: Evolution of the Temperature Profiles of the Exothermic Reaction in a Co-current Reactor (with Catalyst Activity Profiling)

Evolution of the Temperature Profiles for the Counter-current Reactor: The temperature profiles for the exothermic reaction, during the start-up of the counter-current reactor are presented in Figure 3-15. For the parameters used in this simulation, the transient profiles exceed the final steady temperature. This is due to the wrong-way behavior which arises due to coupling of exothermic and endothermic reactions. The temperature peak in this case initially moves from right to left and then moves back to right. Activity profiling does not help in reducing the temperature peak in counter-current reactors.

Wrong-Way Behavior: Wrong-way behavior in the packed bed reactors is well studied for exothermic reactions (Pinjala et al., 1988; Chen and Luss, 1989). The wrong-way is caused by a sudden drop in feed temperature which results in the temperature excursion leading to higher temperatures in the bed due to the different propagation speeds of the concentration and the temperature profiles (for exothermic reaction). In this work, we have studied the wrong way behavior in the heat exchanger reactor where the coupling of exothermic and endothermic reactions takes place. Two examples showing the effect of reducing the feed temperature of the endothermic and exothermic streams in a co-current reactor (without catalyst activity profiling) are presented.

The effect of reducing the feed temperature for the exothermic reaction on the exothermic temperature profile is shown in Figure 3-16a. The initial steady state temperature profile is generated with $\theta^h = 0.0323$ and $\theta^c = 0.0$ (all other parameters are the same as shown in Table 3-1). The reduction in the feed temperature of exothermic reactants (to $\theta^h = 0.0$), results in the temperature excursions due to wrong-way behavior and the corresponding temperature profiles for different dimensionless time (τ) are shown in Figure 3-16a. The temperature peak during these excursions may be as high as the adiabatic temperature. The final steady state, in Figure 3-16a, corresponds to the base case shown in Figure 3-3. It is also to be noted that with the increase in the feed temperature, the temperature peak increases and moves towards the reactor inlet.

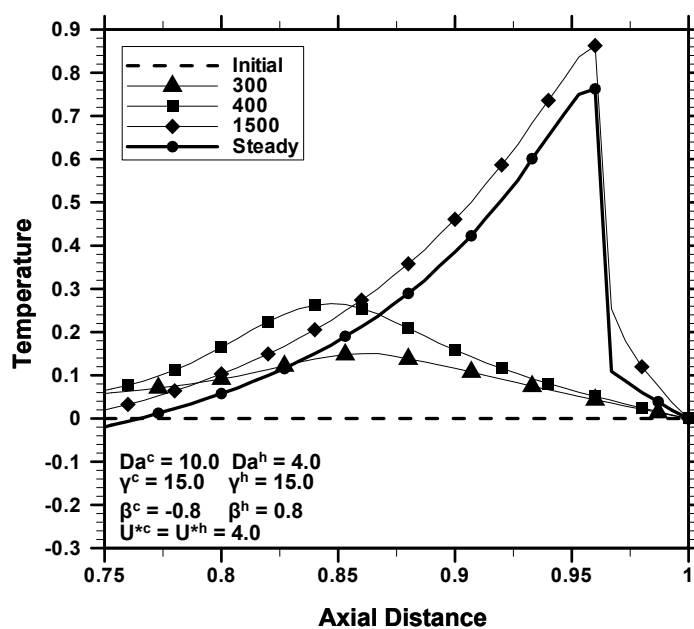


Figure 3-15: Evolution of the Temperature Profiles of the Exothermic Reaction in a Counter-current Reactor (without Catalyst Activity Profiling)

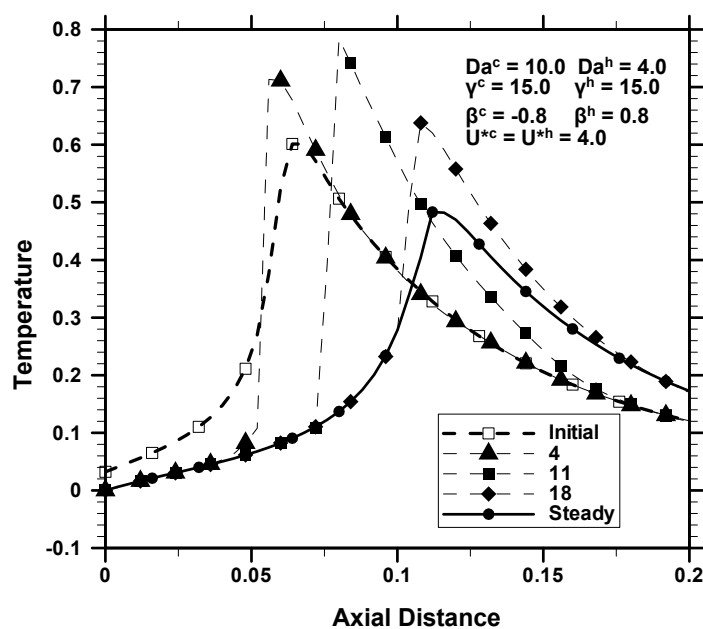


Figure 3-16a: Wrong-way Behavior in the Co-current Reactor due to the Drop in the Feed Temperature on the Exothermic Side (Temperature Profiles for Exothermic Reaction)

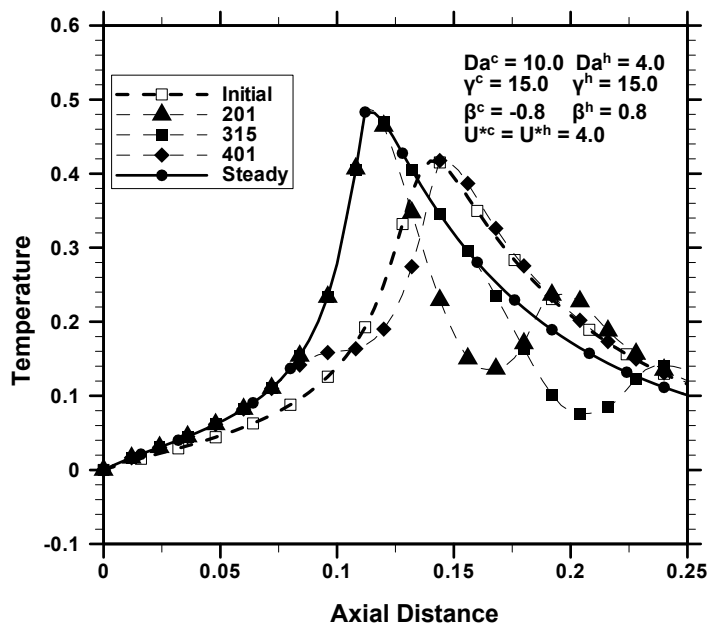


Figure 3-16b: Thermal Waves on the Exothermic Side of the Co-current Reactor due to the Rise in the Temperature of the Feed for the Endothermic reaction

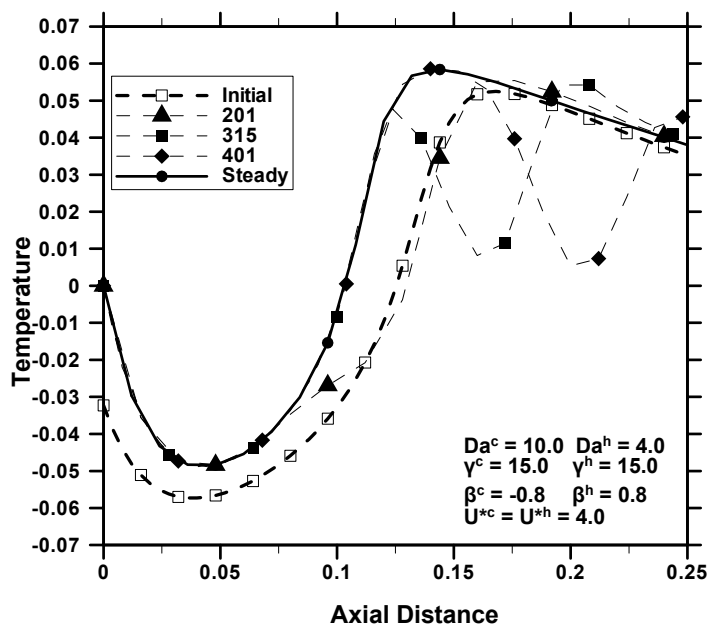


Figure 3-16c: Thermal Waves on the Endothermic Side of the Co-current Reactor due to the Rise in the Temperature of the Feed for the Endothermic reaction

Similar temperature peaks and excursion profiles are observed on the endothermic side because of coupling with exothermic reaction and are not shown here. Figures 3-16b and 3-16c show the transient temperature profiles for the exothermic and endothermic side, respectively, in a co-current reactor for the case where the feed temperature for the endothermic reaction is increased. Here, the initial steady state temperature profile is generated with $\theta^h = 0.0$ and $\theta^c = -0.0323$. The wrong-way behavior is observed in this case when the temperature of the feed to the endothermic side is increased. The transient temperature profiles exhibit wavy patterns, for this case. With an increase in the feed temperature of the endothermic reaction, the temperature gradient between the exothermic and endothermic side decreases, resulting in a higher temperature peak for the exothermic reaction. The temperature peak for the exothermic reaction moves towards the reactor inlet. The temperature profiles also show troughs and the temperature troughs on the endothermic side are observed due to an increase in the rate of endothermic reaction as the reactants are hotter (due to the rise in the feed temperature) compared to the initial state. Similar troughs are also seen on the exothermic temperature profiles because of thermal coupling. Some of these troughs / peaks disappear with time but during the transient these traveling thermal waves show two temperature peaks / troughs because of the different time scales of convection and heat transfer between the exothermic and endothermic sides.

The counter-current reactor also exhibits similar wrong-way behavior. These transient thermal patterns are important in developing suitable control systems for these reactors. The transient studies also aid in understanding the possible catalyst sintering and deactivation during the evolution / perturbation.

3.6 Summary

The steady state and dynamic behavior of counter-current and co-current heat exchanger reactors coupling exothermic and endothermic reactions are analyzed using the pseudo-homogeneous plug flow model. In general, the heat exchanger reactors yield higher exit conversion for the endothermic reaction than the adiabatic reactor. The temperature

peak on the exothermic side is lower in co-current reactor than that in the counter-current reactor. The hotspot on the exothermic side is a major concern in these reactors and we observed that these hot-spots could be reduced drastically by suitable catalyst activity profiling in the co-current reactors. By activity profiling, the reaction front spreads over the reactor providing a more uniform heat source to the endothermic side. However, during the transient mode of operation the temperature peaks on the exothermic side exceed the steady state temperature peak. This may have adverse impact on the catalyst used. Hence, a suitable protocol has to be established for the safe start-up of these reactors especially for the case with activity profiling.

The counter-current reactor exhibits a phenomenon termed here as hot pinch and cold pinch cross-over points. At these points, both the exothermic and endothermic streams have identical temperatures. The counter-current reactors exhibit multiple steady states for the range of parameters investigated. The hot spot is also an issue in the counter-current reactor and the exponential catalyst activity profiling did not help much in reducing it. One way of reducing the hot-spot is by using the inert packing in some section of the reactor. It is found that the inert packing reduces the magnitude of the cold pinch cross-over point temperature in the counter-current reactor and also the catalyst requirement. It is also observed that the counter-current configuration yields higher conversion for the endothermic reaction than the co-current configuration in shorter reactors. This may be advantageous for some equilibrium limited reactions.

Compared to directly coupled adiabatic reactors, the heat exchanger reactors offer operational flexibility. This is demonstrated by showing that the flow rates of individual streams can be adjusted independently to obtain the desired conversion with lower temperature peak. More detailed analyses of the heat exchanger reactors, especially the variation of temperature profiles and hot spots radially, are presented in the next chapter.

Chapter 4

Analysis of Recuperative Reactors using Two Dimensional Models

4.1 Scope

In this chapter, a two dimensional mathematical model was used to analyze the coupling exothermic and endothermic reactions in co-current and counter-current heat exchanger reactors. Some of the features of the recuperative reactors identified using 1-D, in the previous chapter, are verified with the 2-D model. The effects of design parameters like tube spacing and the operational parameters, like concentration of the reactants on the maximum temperature within the reactor and on the exit conversion are discussed. The role played by the radial dispersion on the hot-spot is also investigated. The need to use 2-D model instead of 1-D model, for the recuperative reactors, is also discussed.

4.2 Introduction

As discussed earlier, the heat exchanger or recuperative reactor is one of the good choices for coupling exothermic and endothermic reactions. In this reactor, the exothermic (combustion) and the endothermic reactions are separated in space and the heat transfer occurs through the wall. The separation of exothermic and endothermic reaction spaces in this reactor offers several design and operational flexibilities. Some of the advantages of the heat exchanger reactor over the directly coupled adiabatic reactors or the reverse flow reactors are the steady state operation of the process, flexibility to use different catalysts for the exothermic and endothermic reactions, etc. The flow rates and the reactant composition of any stream can be adjusted independently of the other stream. It is also to be noted that, in the future, by wise

selection of the exothermic and the endothermic reactions, two different valuable products – respectively from the exothermic and the endothermic reactions – can be produced using a single reactor in an energy efficient manner. A detailed analysis and the comparison of the performance of the heat exchanger reactors, using a 1-D mathematical model has been presented in Chapter 3 (see also Ramaswamy et al., 2006). It is also seen that between the co-current and the counter-current heat mode of coupling, for the parameters investigated, the co-current reactors result in the desired conversion with lower temperature peak. The comparison of the performance of the heat exchanger reactors and the directly coupled adiabatic reactors are taken up in the next chapter.

Two dimensional models are often required for a detailed design of heat exchanger reactors and to gain further insight into their performance. The important design parameters like the tube diameter and the optimized spacing of the tubes, etc., are selected based on the predictions of the higher dimensional models. Though 1-D models predict the cross sectional averaged concentration and temperature profiles, they do not provide a comprehensive understanding of the transverse variation of these profiles. The radial temperature profiles, predominantly dictate the heat transfer between the exothermic side and the endothermic side. Also the presence of hotspot at any stream line within the tube and/or shell side of the heat exchanger reactor can be identified using the 2-D model, thus enabling one to adopt proper corrective measures for control.

In this chapter, a two dimensional homogeneous model is used to the study and compare coupling exothermic and endothermic reactions in the co-current and counter current packed bed reactors. In this reactor, the rate of heat generation and the rate of heat consumption can also be balanced by optimization of the tube spacing (at constant stream velocity). Hence, in this chapter, the effects of tube diameter / tube spacing on the radial temperature profiles, the hot spot and on the endothermic conversion are presented. The effect of varying the inlet concentration of the exothermic stream to minimize the hot spot within the reactor is also discussed. The effect of radial dispersion on the temperature profiles is also presented.

4.3 Two Dimensional Pseudo-Homogeneous Model for a Recuperative Reactor

In this section, the governing equations for the two dimensional pseudo-homogeneous model of the heat exchanger reactors, used in this work are presented. A schematic of the domain of the heat exchanger reactor used in the modeling is shown in Figure 4-1. In this model, the axial thermal and mass dispersions are not included, to restrict our attention to the radial effects. A first order irreversible kinetics has been assumed for both the exothermic and endothermic reactions. Though we could use any kinetics in our model, we have restricted our analyses to first order irreversible kinetics in an attempt to understand the overall performance of coupling of exothermic and endothermic reactions. We have also shown that use of reversible kinetics did not change the qualitative trends of the profiles obtained. The equivalent 1-D model, without radial dispersions, can be found in the previous chapter.

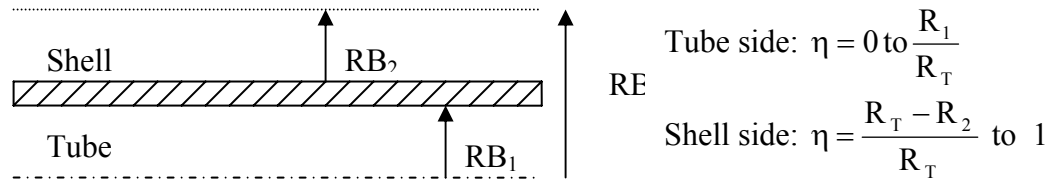


Figure 4-1: Schematic of the Reactor Domain used for the Development of the Model

The transient dimensionless governing equations for the counter-current and the co-current reactors are given below:

For the tube side,

Mass Balance:

$$\frac{\partial x_g^c}{\partial \tau} + \frac{1}{Da^c} \frac{\partial x_g^c}{\partial \xi} - \frac{1}{\Phi_{Mrc}^2} \frac{1}{\eta} \frac{\partial}{\partial \eta} \eta \frac{\partial x_g^c}{\partial \eta} - (1 - \varepsilon_b^c) e^{\gamma^c \left(\frac{\theta_g^c}{1 + \theta_g^c} \right)} (1 - x_g^c) = 0 \quad (4.1)$$

Energy Balance:

$$\begin{aligned}
 & (\varepsilon_b^c + (1 - \varepsilon_b^c) \frac{\rho_s^c C_{ps}^c}{\rho_g^c C_{pg}^c}) \frac{\partial \theta_g^c}{\partial \tau} + \frac{1}{Da^c} \frac{\partial \theta_g^c}{\partial \xi} - \frac{1}{\Phi_{Trc}^2} \frac{1}{\eta} \frac{\partial}{\partial \eta} \eta \frac{\partial \theta_g^c}{\partial \eta} \\
 & - \beta^c (1 - \varepsilon_b^c) e^{\gamma^c \left(\frac{\theta_g^c}{1 + \theta_g^c} \right)} (1 - x_g^c) = 0
 \end{aligned} \tag{4.2}$$

For the shell side,

Mass Balance:

$$\psi \frac{\partial x_g^h}{\partial \tau} \pm \frac{1}{Da^h} \frac{dx_g^h}{d\xi} - \frac{1}{\Phi_{Mrh}^2} \frac{1}{\eta} \frac{\partial}{\partial \eta} \eta \frac{\partial x_g^h}{\partial \eta} - \alpha(\xi) (1 - \varepsilon_b^h) e^{\gamma^h \left(\frac{\theta_g^h}{1 + \theta_g^h} \right)} (1 - x_g^h) = 0 \tag{4.3}$$

Energy Balance:

$$\begin{aligned}
 & (\varepsilon_b^h + (1 - \varepsilon_b^h) \frac{\rho_s^h C_{ps}^h}{\rho_g^h C_{pg}^h}) \psi \frac{\partial \theta_g^h}{\partial \tau} \pm \frac{1}{Da^h} \frac{d\theta_g^h}{d\xi} - \frac{1}{\Phi_{Trh}^2} \frac{1}{\eta} \frac{\partial}{\partial \eta} \eta \frac{\partial \theta_g^h}{\partial \eta} \\
 & - \alpha(\xi) \beta^h (1 - \varepsilon_b^h) e^{\gamma^h \left(\frac{\theta_g^h}{1 + \theta_g^h} \right)} (1 - x_g^h) = 0
 \end{aligned} \tag{4.4}$$

In Eqs. 4.3 and 4.4, the positive sign in the convection term is used for the co-current reactor and the negative sign for the counter-current reactor. Here $\alpha(\xi)$ is the position dependent catalyst activity for the exothermic reaction and is set as unity for the cases with no catalyst activity profiling. The boundary conditions and initial conditions used for solving Eqs. 4.1-4.4 are given next.

Radial Boundary Conditions:

$$\frac{d\theta_g^c}{d\eta} = 0, \eta = 0$$

$$\frac{d\theta_g^c}{d\eta} = \frac{K_{wall} R_T}{t_{wall} \lambda^c} (\theta_g^h - \theta_g^c), \eta = \frac{R_1}{R_T}$$

$$\frac{d\theta_g^h}{d\eta} = 0, \eta = 1$$

$$\frac{d\theta_g^h}{d\eta} = \frac{K_{wall} R_T}{t_{wall} \lambda^h} (\theta_g^h - \theta_g^c), \eta = \frac{R_1 + t_{wall}}{R_T}$$

$$\frac{dx_g^c}{d\eta} = 0, \eta = 0$$

$$\frac{dx_g^c}{d\eta} = 0, \eta = \frac{R_1}{R_T}$$

$$\frac{dx_g^h}{d\eta} = 0, \eta = 1$$

$$\frac{dx_g^h}{d\eta} = 0, \eta = \frac{R_1 + t_{wall}}{R_T}$$

Axial Boundary Conditions:

Co-current reactor:

at $\xi = 0$,

$$x_g^c = x_{g,in}^c = 0; \theta_g^c = \theta_{g,in}^c = 0; x_g^h = x_{g,in}^h = 0; \theta_g^h = \theta_{g,in}^h = 0, \tau \geq 0$$

Counter-current reactor:

at $\xi = 0$,

$$x_g^c = x_{g,in}^c = 0; \theta_g^c = \theta_{g,in}^c = 0, \tau \geq 0$$

at $\xi = 1$,

$$x_g^h = x_{g,in}^h = 0; \theta_g^h = \theta_{g,in}^h = 0, \tau \geq 0$$

Initial conditions (for both counter-current and co-current reactors):

at $\tau = 0$,

$$x_g^c = \theta_g^c = x_g^h = \theta_g^h = 0, \forall \xi$$

The other dimensionless parameters used in the model are given below with $j = c$ and h for the cold and hot side respectively:

$$x_g^j = \frac{C_0^j - C^j}{C_0^j}, \quad \xi = \frac{z}{L}, \quad \eta = \frac{r}{R_T}$$

$$Da^j = \frac{k^j(T_{ref})L}{u_g^j}, \quad \tau = k^c(T_{ref})t$$

$$\gamma^j = \frac{E^j}{R_g T_{ref}}, \quad \theta_g^j = \frac{T^j - T_{ref}}{T_{ref}}$$

$$\beta_j = \frac{-\Delta H^j C_0^j}{\rho_g^j C_{pg}^j T_{ref}}, \quad \psi = \frac{k^c(T_{ref})}{k^h(T_{ref})} (= \frac{Da^c}{Da^h}, \text{ when } u_g^c = u_g^h)$$

$$\Phi_{Trj}^2 = \frac{R_T^2 k^j(T_{ref}) \rho_g^j C_{pg}^j}{\lambda_g^j} = Pe_{Tr}^j Da^j \frac{R_T}{L} = Pe_{Tr}^j Da^j \frac{R_T^2}{d_p L}$$

$$\Phi_{Mrj}^2 = \frac{R_T^2 k^j(T_{ref})}{De_m^j} = Pe_{Mr}^j Da^j \frac{R_T}{L} = Pe_M^j Da^j \frac{R_T^2}{d_p L}$$

The parameters considered in the model are the Damkohler number (Da^j , the ratio of flow time to the reaction time), the radial mass and thermal Peclet numbers (Pe_{Mr}^j , Pe_{Tr}^j), dimensionless heat of reaction (β^j), and dimensionless activation energy (γ^j). Here, Pe_M^j and Pe_T^j are the mass and thermal Peclet number based on the catalyst particle size and the correlations used to calculate them are presented in Appendix B (Iordanidis, 2002). For the counter-current reactor, the feed for the endothermic reaction enters at the axial position, $\xi=0$, and the feed for the exothermic reaction enters at the axial position, $\xi=1$ (position-1). For the co-current reactor, the feed for both exothermic and endothermic reactions enter at the axial position, $\xi=0$ (position-0).

4.4 Solution Procedure

The transient model equations (Eqs. 4.1-4.4) are solved by the method-of-lines (MOL) (van de Wouwer et al., 2001) where the partial differential equations (PDE) are converted to a set of ordinary differential equations (ODE) by suitable discretization of the spatial axial (convection term) and radial derivatives (dispersion terms). The resulting ODEs in time are integrated by stiff solvers. We have used a second order upwind finite difference scheme for the discretization of the axial derivatives and the second order central differencing scheme for the discretization of the radial derivatives. The ODEs are integrated using LSODE solver from the NETLIB libraries. The two dimensional steady state model equations can be derived by setting the time derivatives in the above equations (Eqs. 4.1-4.4) to zero. The steady state model equations of the co-current reactor are solved using PDEPE solver in the MATLAB by the method of lines. The steady state model for the co-current reactor is slightly modified so that it can be implemented easily in the MATLAB. The procedure for scaling and the resulting set of modified equations are presented in Appendix C. For the counter-current reactor, the steady state model results in a boundary value problem, with a set of coupled non-linear algebraic equations. These equations are to be solved either by shooting algorithm or by Newton-Raphson type algorithm and the solutions of which highly depends on the initial guesses used. Hence, the MOL approach is used to obtain the steady state solution (from the transient model) for the counter-current reactor, which is fast and robust. The transient model equations are solved in an explicit fashion. The time step required for the integration is chosen based on the Courant criterion.

4.4.1 Arrangement of Variables

As discussed in Chapter 3, the arrangement of variables plays an important role in determining the computation time of the model, especially while solving the differential equations implicitly. We have used the scheme shown in Figure 4-2 to arrange the variables / differential equations. In this scheme, the indexing of variables / equations starts from the first axial node (reactor inlet, $i = 1$) and the first radial node (center of

the tube, $j = 1$). First, all the model variables corresponding to the chosen axial node and the first radial position are numbered sequentially. Then the model variables at the next radial position (but at the same axial position) are numbered subsequently. This procedure is repeated until all the model variables in all the radial positions of the first axial node are numbered. Then the numbering is carried out for the variables in the next (second) axial node, starting again from the first radial position. This procedure is repeated until all the variables are numbered (i.e. all the model variables in the last axial node and the last radial node, $i = N_{node-axi}$, $j = N_{node-rad}$ are accounted for).

$n:$	1	2	...	N_{model}	$N_{model}+1$...	N_{model}^*	N_{model}^*	...	$N_{tot}(N_{node-}$...	N_{tot}
							$N_{node-rad}$	N_{node-}		rad^*	$N_{model}+1$	
							$rad+1$					
$u_{i,j,k}:$	$u_{1,1,1}$	$u_{1,1,2}$...	$u_{1,1,N_{model}}$	$u_{1,2,1}$...	$u_{1,N_{node-}}$	$u_{2,1,1}$...	$u_{N_{node-axi},1,1}$...	$u_{N_{node-}}$
							rad,N_{model}					axi,N_{node-}
												rad,N_{model}

Figure 4-2: Variables (u_{ij}) Arrangement Scheme (i (= 1 to $N_{node-axi}$) – axial node index, j (=1 to $N_{node-rad}$) – radial node index, k (=1 to N_{model}) – variable index, n (=1 to N_{tot}) – running index of all the variables in the system with $N_{tot}=N_{node-axi}^* N_{node-rad}^* N_{model}$). Here the variables of the model correspond to the variables in respective sides (exothermic or endothermic side) of the recuperative reactor.

4.5 Results and Discussions

A detailed analysis of the steady state and dynamic behavior, and the comparison of the performance of co-current and counter-current heat exchanger reactors using the 1-D model were shown earlier. In this chapter, some case studies illustrating the importance of 2-D model in the design of these reactors are carried out. These include the effect of tube diameter, tube spacing, radial dispersion and the feed concentration on the radial temperature profiles and exit conversion. These studies primarily focus on avoiding or minimizing the hot spot in the heat exchanger reactors.

4.5.1 Co-current Reactor

Base Case: Figure 4-3 shows the axial temperature profiles observed in a co-current reactor at various radial positions for the parameters reported in Table 4-1. Here, the wall of the heat exchanger reactor tubes has been assumed to be highly conductive and, hence, a large value of the wall heat transfer coefficient (~ 500) is used in the model. From Figure 4-3 it is clear that, for the value of the heat transfer coefficient used, the endothermic and the exothermic temperature profiles at the tube wall almost overlap with each other. On the exothermic side (shell side), the temperature profile corresponding to the centre stream line is higher than that of the wall. Also the maximum temperature on the stream line corresponding to the centre of the shell side (exothermic side) is higher than the maximum temperature predicted at the wall. The maximum temperature observed in the heat exchanger reactors plays a great role in the selection of the tube material and the catalyst used. The magnitude of the maximum temperature can be minimized by introducing some inert materials / packing on the exothermic side near the reactor inlet.

Table 4-1: Parameters used for the simulation (Base Case – 2D Model)

Da^h	10.0	Pe_M^h	2.0
Da^c	4.0	Pe_T^h	2.0
β_h	-0.8	L, m	5.0
β_c	0.8	d_p, m	0.001
γ^h	15.0	$\varepsilon_b^h = \varepsilon_b^c$	0.5
γ^c	15.0	R_1, m	0.0256
Pe_M^c	2.0	R_2, m	0.0256
Pe_T^c	2.0	t_{wall}, m	0.003

Effect of Tube Spacing: Figure 4-4 shows the cross sectional area averaged temperature profiles on the exothermic and the endothermic sides of the co-current reactors for two cases of different tube spacing – one with $R_2 = 0.0126$ m and the

second with $R_2 = 0.02\text{m}$. With increase in the tube spacing ($R_2 = 0.02\text{ m}$), the cross sectional averaged maximum temperature and the exit temperature increase. This is due to increase in the amount of the feed processed at shell side (as the velocity of the exothermic stream (Damkohler Number) is constant in both the cases). The temperature profiles corresponding to $R_2 = 0.0126\text{m}$, qualitatively resemble those obtained using the 1-D model (refer Figure 3-3) (It is to be noted that the one dimensional model predicts higher maximum temperature for the counter-current reactor than that of the co-current reactor. Also, the conversion of the endothermic reaction, predicted by the 1-D model, is 98% for the counter-current reactor and 100% for the co-current reactor.).

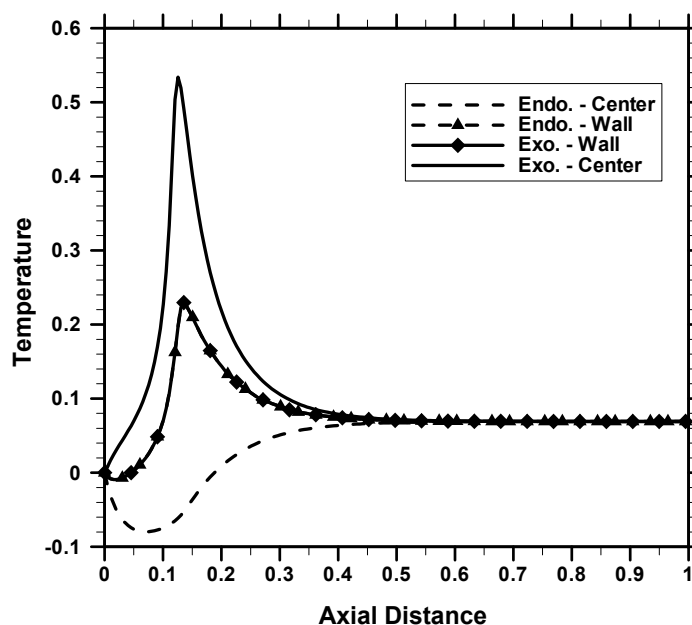


Figure 4-3: Axial Temperature Profiles of Endothermic and Exothermic Reactions at Different Radial Positions within the Co-current Reactor (Parameters as reported in Table 4-1)

Figure 4-5 shows the cross sectional area averaged point conversion for the exothermic and endothermic reactions in the co-current reactor, predicted by the 2-D model, for the two cases of different tube spacing. The exit conversion goes to completion for these two cases.

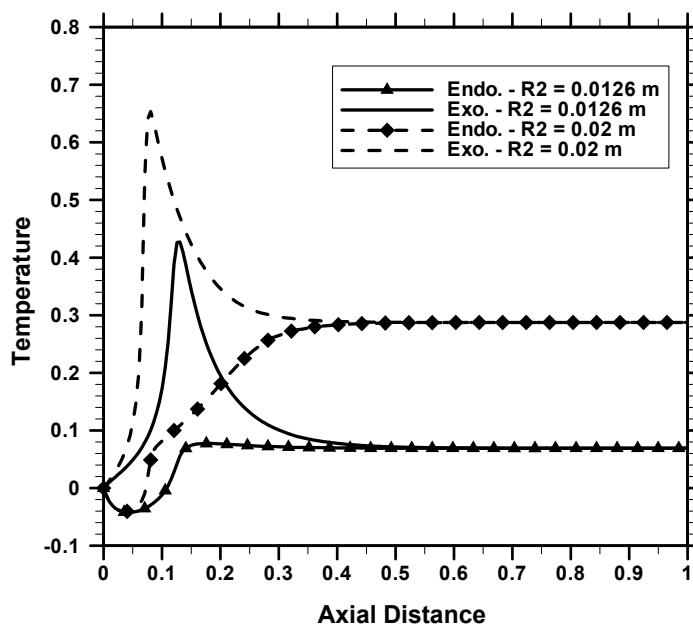


Figure 4-4: Cross-sectional Area Averaged Axial Temperature Profiles of Endothermic and Exothermic Reactions in the Co-current Reactor for Two Different Tube Spacing (other parameters as reported in Table 4-1)

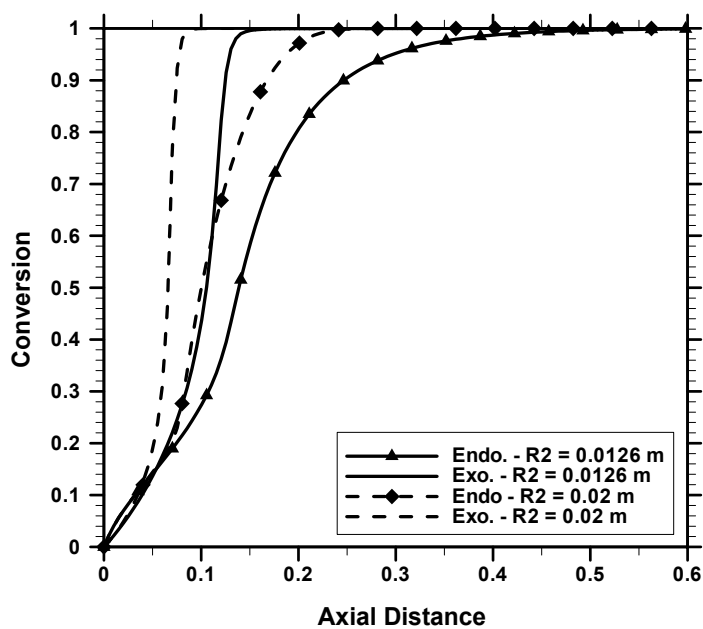


Figure 4-5: Cross-sectional Area Averaged Point Conversion Profiles of Endothermic and Exothermic Reactions in the Co-current Reactor for Two Different Tube Spacing (other parameters as reported in Table 4-1)

This study shows that, at constant velocity, increase in the tube spacing (exothermic side) increases the flow rate of the feed for exothermic reaction which in turn increases the magnitude of temperature peak and the exit temperature. Hence, it is clear that to reduce the magnitude of temperature peak, the rate of heat generation by the exothermic reaction has to be balanced by the rate of heat consumption by the endothermic reactions. One way of balancing the heat of these reactions is by using the optimized tube spacing and/or by using the reduced fuel rate in the heat exchanger reactors (reducing the cross sectional area of the exothermic side reduces the fuel consumption and the magnitude of the temperature peak). Other ways to reduce the exothermic temperature peak by using activity profiling of the catalysts, etc., are discussed in the previous chapter.

Effect of Feed Concentration for Exothermic Reaction / Heat of Exothermic Reaction: The concentration of the feed for the exothermic reaction and, in turn, the dimensionless heat of reaction is varied to study its effect on the conversion of the endothermic reaction and on the hotspot within the reactor. Figure 4-6 shows the temperature profiles corresponding to the wall and the center (shell center) for the exothermic side with $\beta^h = 0.4$ (this is also equivalent to decreasing the heat of exothermic reaction) for two different tube spacing. For this case, the amount of heat released by the exothermic reaction is reduced and is less than that shown in Figure 4-4 and, hence, the predicted temperature rise is also low. It is observed that by decreasing the half length of the tube spacing from 0.0256 m to 0.02 m, the reduction in the maximum temperature, corresponding to centerline (shell center) temperature profile, is around 70%. The larger tube spacing also results in the larger exit temperature of the stream leaving the reactor. Figure 4-7 plots the mixing-cup conversion profiles for these two tube spacings.

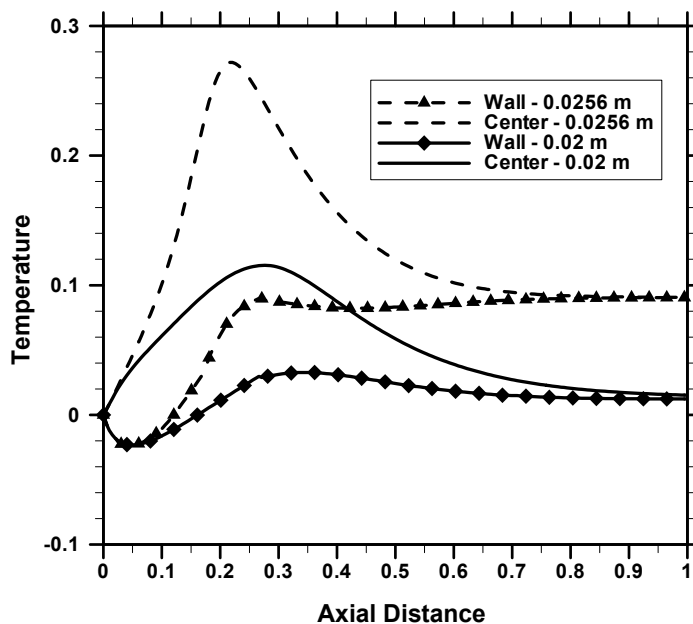


Figure 4-6: Axial Temperature Profiles of Exothermic Reactions in the Co-current Reactor for Two Different Tube Spacing with $\beta^h = 0.4$ (other parameters as reported in Table 4-1)

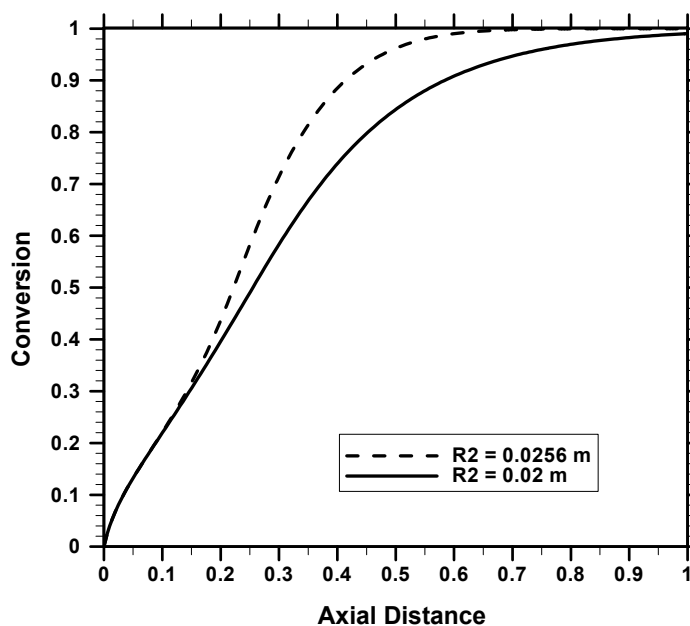


Figure 4-7: Conversion Profiles for Endothermic Reactions in the Co-current Reactor for Two Different Tube Spacing with $\beta^h = 0.4$ (other parameters as reported in Table 4-1)

Both tube spacings result in almost complete conversion at the reactor exit and the case with less tube spacing requires the full length of the reactor (or longer length) to reach the complete conversion. This study again confirms that the temperature peak and the effluent temperature can be reduced by optimizing the design variables such as the spacing between the tubes etc.(i.e. by reducing the tube spacing), while maintaining the similar conversion for the endothermic reaction. The desired conversion and the temperature profile can also be obtained by suitable optimization of the operating conditions, like concentration of the combustion fuel or by the selection of proper fuel with reduced heat of reaction.

Effect of Radial Dispersion: The mass and thermal dispersion terms, in particular Pe , describe the effect of radial dispersion within the reactor. Figure 4-8 shows the effect of Peclet numbers on the wall and centre line temperature profiles on the exothermic side. In these simulations, the mass and thermal Peclet numbers for both the exothermic and the endothermic side are assumed to be identical. For real cases, these Peclet numbers are system dependent and are to be calculated based on experimental data or any available correlation. For this set of simulations, $\beta^h = 0.4$ and $R_1 = R_2 = 0.0256\text{m}$ were used. The other parameters are as reported in Table 4-1.

The temperature profile and the maximum temperature are larger for the case with high Pe . As Pe increases, the radial dispersion or uniformity of temperature decreases and hence the maximum temperature increase. Here, the amount of heat transferred to the endothermic side decreases and, hence, the endothermic temperature profile decreases in magnitude. One would also anticipate a larger temperature drop on the endothermic temperature profiles.

Thus, effective radial dispersion in both sides of the heat exchanger reactor plays a very important role in determining the hot spot in the reactor and the dispersion pattern is often dictated by type of packing and other hydrodynamic factors.

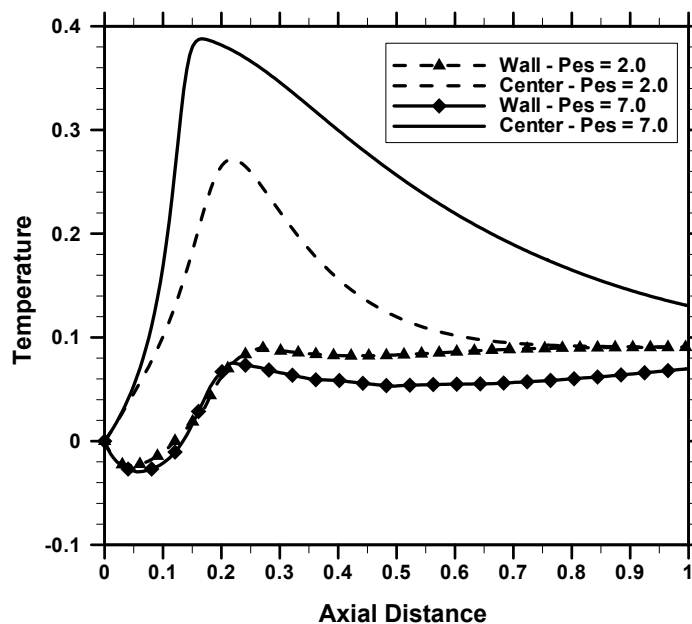


Figure 4-8: Effect of Peclet Number on the Axial Temperature Profiles for the Exothermic Reactions in the Co-current Reactor with $\beta^h = 0.4$ and $R_2 = 0.0256$ m (other parameters as reported in Table 4-1)

4.5.2 Counter-current Reactor

The analysis using the 1-D model shows that the counter-current reactor exhibits cold pinch and hot pinch cross-over points in the temperature profiles, for a certain set of parameters. At these cross-over points both the exothermic and endothermic streams have identical temperature. The cold pinch cross-over point occurs near the inlet for the endothermic feed (position-0). Here, the reactants for the endothermic reaction transfer heat to the effluent of exothermic reaction from the inlet (position-0) up to the cold pinch cross over point. The hot pinch cross-over point occurs near the inlet of the feed for the exothermic reaction (position-1). From this hot pinch cross-over point to position-1, the effluent of the endothermic reaction heats the reactants for the exothermic reaction. These cross-over points manifest themselves differently when using the 2-D model, because of series of axial temperature profiles, one corresponding to each radial location. Hence, for the 2-D model the cross-over points are redefined as the positions in the reactor where the temperatures corresponding to the stream line at

the center of the shell side (or the center of tube spacing) and the centre of tube side are identical. In other words, one could also define the cross over points as the points where the cross sectional area averaged temperatures corresponding to shell and tube sides are identical.

Figure 4-9 shows the axial temperature profiles on the exothermic and endothermic side of the counter-current reactor at the two different radial locations (wall and the center of the tube and the shell sides), predicted by the two dimensional model. The figure clearly shows the occurrence of the cold pinch and hot pinch cross-over points (for this case, even the cross sectional area averaged temperature profiles show the occurrence of these cross-over points). The parameters used for the simulation are as reported in Table 4-1 except $\beta^h = 0.4$ and $R_2 = 0.0126$ m. The temperature profiles on the wall sides for the exothermic and endothermic reactions overlap each other due to the use of large heat transfer coefficients.

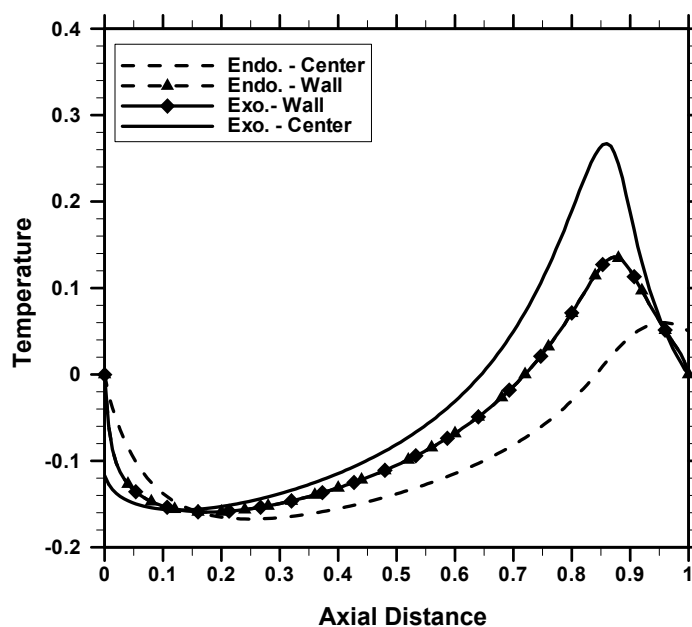


Figure 4-9: Axial Temperature Profiles of Endothermic and Exothermic Reactions at Different Radial Positions within the Counter-current Reactor with $\beta^h = 0.4$ and $R_2 = 0.0126$ m (other parameters as reported in Table 4-1)

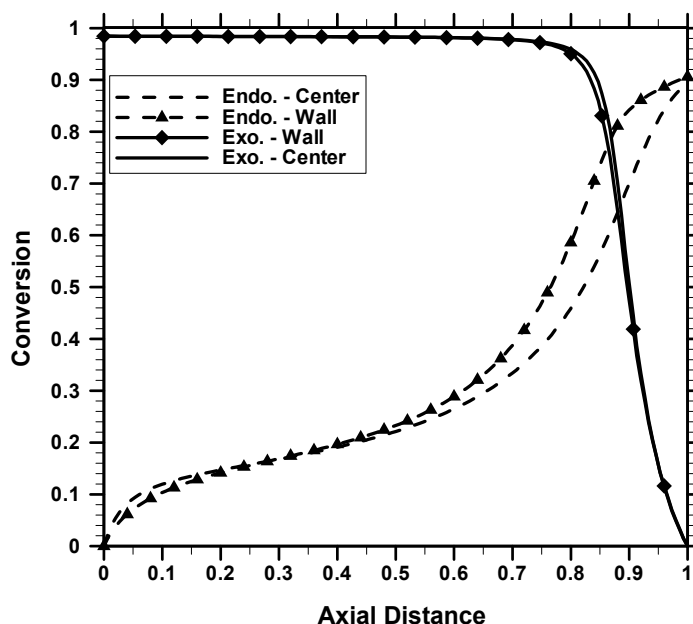


Figure 4-10: Axial Conversion Profiles for Endothermic and Exothermic Reactions at Different Radial Positions within the Counter-current Reactor with $\beta^h = 0.4$ and $R_2 = 0.0126$ m (other parameters as reported in Table 4-1)

The temperature profiles show the temperature peaks near the position-1. The temperature peak can be as large as the adiabatic temperature of the exothermic reaction. These profiles qualitatively match those of the 1-D model. The mixing-cup exit conversion of the endothermic reaction is around 90% for this case. Figure 4-10 plots the conversion profiles at different radial locations within the counter-current reactor for this case.

Using the two dimensional model the effects of the ratio of tube diameter on the conversion and on the temperature rise can be analyzed. Figure 4-11 shows the exothermic temperature profile corresponding to the centre of the shell side for three different tube spacing. With decrease in the tube spacing, the magnitude of the temperature peak (the hot spot) decreases. For the tube spacing of 0.0126 m, the exothermic reaction is extinguished and, hence, the temperature decreases from Position-1. The exit conversions (mixing-cup) for the endothermic reaction for these cases are: 100% for $R_2 = 0.02$ m, 90% for $R_2 = 0.016$ m, and 40% for $R_2 = 0.0126$ m.

Hence, it is clear that there exists a window of tube spacing for which the desired conversion is obtained with lower temperature peak (without the exothermic reaction getting extinguished).

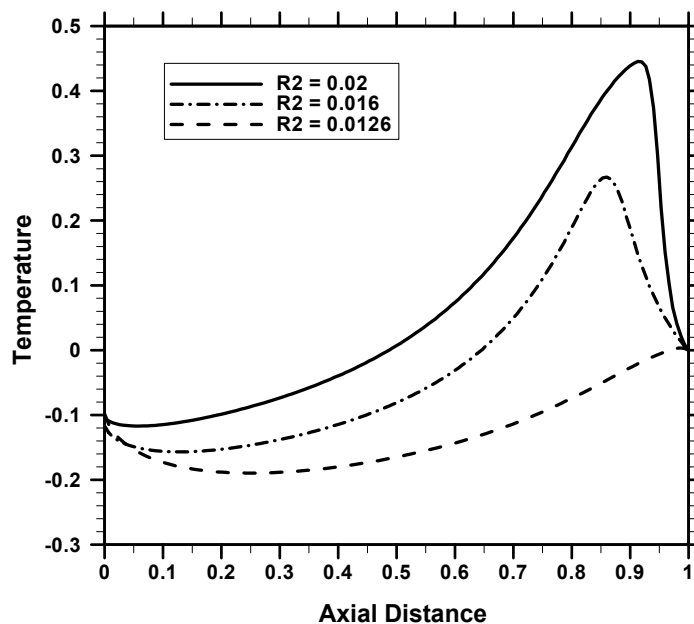


Figure 4-11: Effect of Tube Spacing on the Axial Temperature Profile of Exothermic Reaction at the Centre of the Shell side (Parameters as used in Figure 4-11)

4.6 Summary

A two dimensional pseudo-homogeneous model was used to study the recuperative coupling of exothermic and endothermic reactions in co-current and counter-current heat exchanger reactors. It was found that the spacing between the tubes, within the heat exchanger reactors, plays a great role in controlling the temperature peak. Hence the optimized tube spacing will result in desired conversion for the endothermic reaction with a lower temperature peak, due to efficient heat transfer between the exothermic and the endothermic sides. The inlet concentration of the reactants should also be optimized to control the hot spot within the reactor. The effect of radial dispersion on the performance of these reactors was shown, and it is observed that the good radial

mixing, or lower Pe , favors the uniform transverse temperature distribution resulting in lower temperature peak. It is also observed that predictions by the 1-D and 2-D models qualitatively match each other. The temperature profiles of counter-current reactor, predicted by the 2-D model also exhibit the occurrence of the cold-pinch and hot-pinch cross over points. The cold pinch cross over point can be avoided by using either inert packing in some sections of the reactor, or by using non-similar inlet temperature for the exothermic and endothermic streams, as discussed in Chapter 3.

Chapter 5

Coupling of Exothermic and Endothermic Reactions in Directly Coupled Adiabatic Reactors

5.1 Scope

In this chapter, a one-dimensional pseudo-homogeneous plug flow model is used to investigate the steady state and the dynamic behavior of coupling exothermic and endothermic reactions in directly coupled adiabatic packed bed reactors (DCAR). Two different configurations of DCAR (Simultaneous DCAR - SIMDCAR and Sequential DCAR - SEQDCAR) are investigated. In SIMDCAR, the catalyst bed favors both exothermic and endothermic reactions and both reactions occur simultaneously. SEQDCAR has alternating layers of catalyst beds for exothermic and endothermic reactions and hence the exothermic and endothermic reactions occur in a sequential fashion. The performance of both reactors, in terms of conversion achieved and manifested hotspot behavior, is compared with that of the co-current heat exchanger type reactor. The preliminary criteria for the selection of desirable reactor type, based on the relative magnitudes of heat generation rate and the heat consumption rate, are proposed. The dynamic behavior of these reactors is non-intuitive and we have analyzed some of the transient behavior.

5.1 Introduction

The coupling of exothermic and endothermic reactions is gaining importance in recent years as attempts are being made to reduce the thermal losses associated with the supply of heat to endothermic reactions such as synthesis gas generation. The recuperative

mode of coupling has been analyzed in detail in Chapters 3 and 4 and in this chapter the direct mode of coupling is investigated.

In directly coupled adiabatic reactors (DCAR), both exothermic and endothermic reactions occur in the same reactor space subject to a direct heat transfer within the reacting mixture. The directly coupled adiabatic reactor can be further classified into Simultaneous DCAR (SIMDCAR) and Sequential DCAR (SEQDCAR). The schematic of DCAR is shown in Figure 5-1.

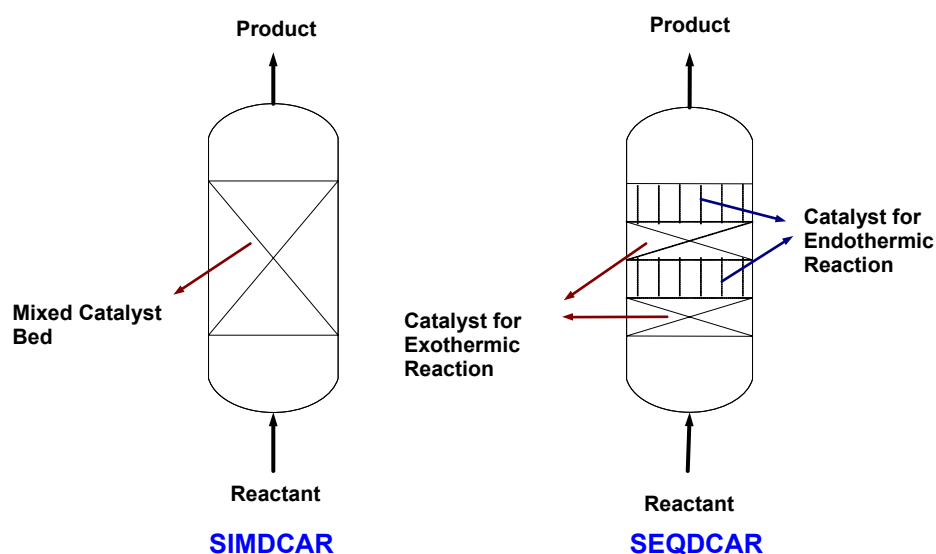


Figure 5-1: Schematic of DCAR - SIMDCAR and SEQDCAR

In SIMDCAR, the bed is made of catalyst that favors both the exothermic and endothermic reactions or the bed is made of uniformly mixed catalysts for exothermic and endothermic reactions (Biesheuvel and Kramer, 2003). SIMDCAR has been practiced industrially in methane steam reforming within the ammonia synthesis process (Ridler and Twigg, 1989) and hydrogen cyanide process (Agar, 1999) etc. It is also being used in the coupling of methane steam reforming with the catalytic oxidation of methane in partial oxidation reactors (De Groote and Froment, 1996; Ma and Trimm, 1996; Avci et al., 2001). The major disadvantage of SIMDCAR is that the catalyst bed

should favor both exothermic and endothermic reactions. On the other hand, SEQDCAR has the alternating beds of catalyst for exothermic and endothermic reactions.

In this chapter, a detailed comparative study of the steady state and the dynamic behavior of the SEQDCAR and SIMDCAR is carried out. The performance of DCARs is also compared with that of the co-current reactor. The conditions for the existence of hotspots in SIMDCAR are analytically derived with a first order irreversible kinetics for both exothermic and endothermic reactions. The preliminary criteria for the selection of different reactor configurations for any application of interest are proposed based on the rate of heat generation and rate of heat consumption.

5.2 One Dimensional Pseudo-homogeneous Plug Flow Model

This section presents the reactor model used for the analyses. The following assumptions are made in the development of the model:

- i) Axial and radial, mass and heat dispersions are neglected.
- ii) Axial conduction in the wall (for the co-current reactor) is not included, and a constant heat transfer coefficient has been assumed along the length of the reactor.
- iii) Physical properties of the fluids and the heat of the reaction are assumed to be independent of temperature, and the total pressure of the system is constant.
- iv) Irreversible first order kinetics is considered for both reactions.

The respective governing equations are:

Mass Balance

$$\frac{\partial x_g^c}{\partial \tau} + \frac{1}{Da^c} \frac{\partial x_g^c}{\partial \xi} - \eta^c (1 - \varepsilon_b) \exp\left[\gamma^c \left(\frac{\theta_g}{1 + \theta_g}\right)\right] (1 - x_g^c) = 0 \quad (5.1)$$

$$\psi \frac{\partial x_g^h}{\partial \tau} + \frac{1}{Da^h} \frac{dx_g^h}{d\xi} - \eta^h (1 - \varepsilon_b) \exp\left[\gamma^h \left(\frac{\theta_g}{1 + \theta_g}\right)\right] (1 - x_g^h) = 0 \quad (5.2)$$

Energy Balance:

$$Da^c (\varepsilon_b + (1 - \varepsilon_b) \frac{\rho_s^c C_{ps}^c}{\rho_g^c C_{pg}^c}) \frac{\partial \theta_g}{\partial \tau} + \frac{\partial \theta_g}{\partial \xi} - \eta^c \beta^c Da^c (1 - \varepsilon_b) \exp\left[\frac{\gamma^c \theta_g}{1 + \theta_g}\right] (1 - x_g^c) - \eta^h \beta^h Da^h (1 - \varepsilon) \exp\left[\frac{\gamma^h \theta_g}{1 + \theta_g}\right] (1 - x_g^h) = 0 \quad (5.3)$$

The dimensionless parameters used are given below:

$$x_g^j = \frac{C_0^j - C^j}{C_0^j}, \theta_g^j = \frac{T^j - T_{ref}}{T_{ref}}, \xi = \frac{z}{L}, \tau = k^c(T_{ref})t$$

$$Da^j = \frac{k^j(T_{ref})L}{u_g^j}, \gamma^j = \frac{E^j}{R_g T_{ref}}, \beta^j = \frac{-\Delta H^j C_0^j}{\rho_g^j C_{pg}^j T_{ref}}, \psi = \frac{k^c(T_{ref})}{k^h(T_{ref})} = \frac{Da^c}{Da^h}$$

The parameters involved in the model are the reaction Damkohler number (Da^j), dimensionless heat of reaction (β^j), dimensionless activation energy (γ^j) and the activity parameter (η^j). The feed (the reactants for both the exothermic and the endothermic reactions) enters at axial position, $\xi=0$.

5.3 Solution Procedure

The method-of-lines (MOL) approach is employed to solve the transient model equations (Vande Wouwer et al., 2001). Here, the partial differential equations are converted to ordinary differential equations (ODE) by suitable discretization of the spatial derivatives and the resulting ODEs are solved using the commercially available stiff integrator. We have used automatic step size adjustable LSODE routine from Netlib as an ODE integrator. The second order finite difference upwind discretisation

scheme is used to discretise the spatial derivatives. The discretization scheme is modified to preserve monotonicity by total variation diminishing (TVD) algorithms (using van-leer splitter) to avoid spurious oscillations (Tannehill et al., 1997). The details of the numerical scheme can be found in Chapter 3. The steady state model equations are obtained by equating the transient derivatives in the above equations (Eqs. 5.1 – 5.3) to zero and are a set of ordinary differential equations in the spatial coordinate. The steady model equations are also solved by LSODE routine from NETLIB libraries.

5.4 Theoretical Analysis of Existence of Hot / Cold Spots in a Directly Coupled Adiabatic Reactor

The analysis presented in this section shows that SIMDCAR exhibits different operating patterns based on the relative magnitudes of the heat generation rate ($\beta^h Da^h$) and the heat consumption rate ($\beta^c Da^c$). This analysis is restricted to the cases where both the exothermic and the endothermic reactions are represented by irreversible first order kinetics and the activation energies of both the reactions are identical ($\gamma^c = \gamma^h$). This simplified analysis based on the steady state pseudo-homogeneous model reveals different operational behavior exhibited by SIMDCAR. It can behave as an isothermal reactor, an exothermic or an endothermic reactor. This reactor can also exhibit a hot or cold spot within the reactor. For this case, the temperature and the conversion at the hot spot can be calculated analytically.

The steady state pseudo-homogeneous model for SIMDCAR can be derived from Eq. 5.1 to Eq. 5.3 by setting the time derivatives to zero.

For $\gamma^c = \gamma^h$, dividing Eq. 5.1 by Eq. 5.2 gives (in steady state),

$$\frac{dx^c}{dx^h} = \frac{Da^c (1 - x_g^c)}{Da^h (1 - x_g^h)} \quad (5.4)$$

Integrating Eq. 5.4 based on separation of variables yields,

$$(1 - x_g^c) = (1 - x_g^h)^{\frac{Da^c}{Da^h}} \quad (5.5)$$

Eq. 5.5 is valid at any point in the reactor. Now, the condition for the hot spot / cold spot in the reactor is given by,

$$\frac{\partial \theta_g}{\partial \xi} = 0 \quad (5.6)$$

Hence, Eq. 5.6 and Eq. 5.3 (with no transient terms) yield,

$$\frac{\beta^h Da^h}{\beta^c Da^c} = - \frac{(1 - x_g^{c*})}{(1 - x_g^{h*})} \quad (5.7)$$

x_g^{c*} and x_g^{h*} are respectively the dimensionless concentration of the reactants for the endothermic and the exothermic reactions at the hot spot / cold spot.

Combining Eqs. 5.5 and 5.7 we get,

$$1 - x_g^{h*} = \exp \left(\frac{\ln \left[- \frac{\beta^h Da^h}{\beta^c Da^c} \right]}{\left[\frac{Da^c}{Da^h} - 1 \right]} \right) \quad (5.8)$$

Eqs. 5.7 and 5.8 are valid only at the position of hot spot / cold spot. From Eq. 5.8, x_g^h at the hot / cold spot can be calculated (and $(1 - x_g^{h*})$ is bounded between 0 and 1). Using these equations (Eqs. 5.5 - 5.8), different patterns exhibited by SIMDCAR can be

classified and are shown in Figure 5-2. Equation 5.8 is not applicable when $\frac{Da^r}{Da^h} = 1$ since Eq. 5.5 and Eq. 5.7 cannot be satisfied simultaneously. Hence for these cases, there is no hot spot / cold spot observed within the reactor.

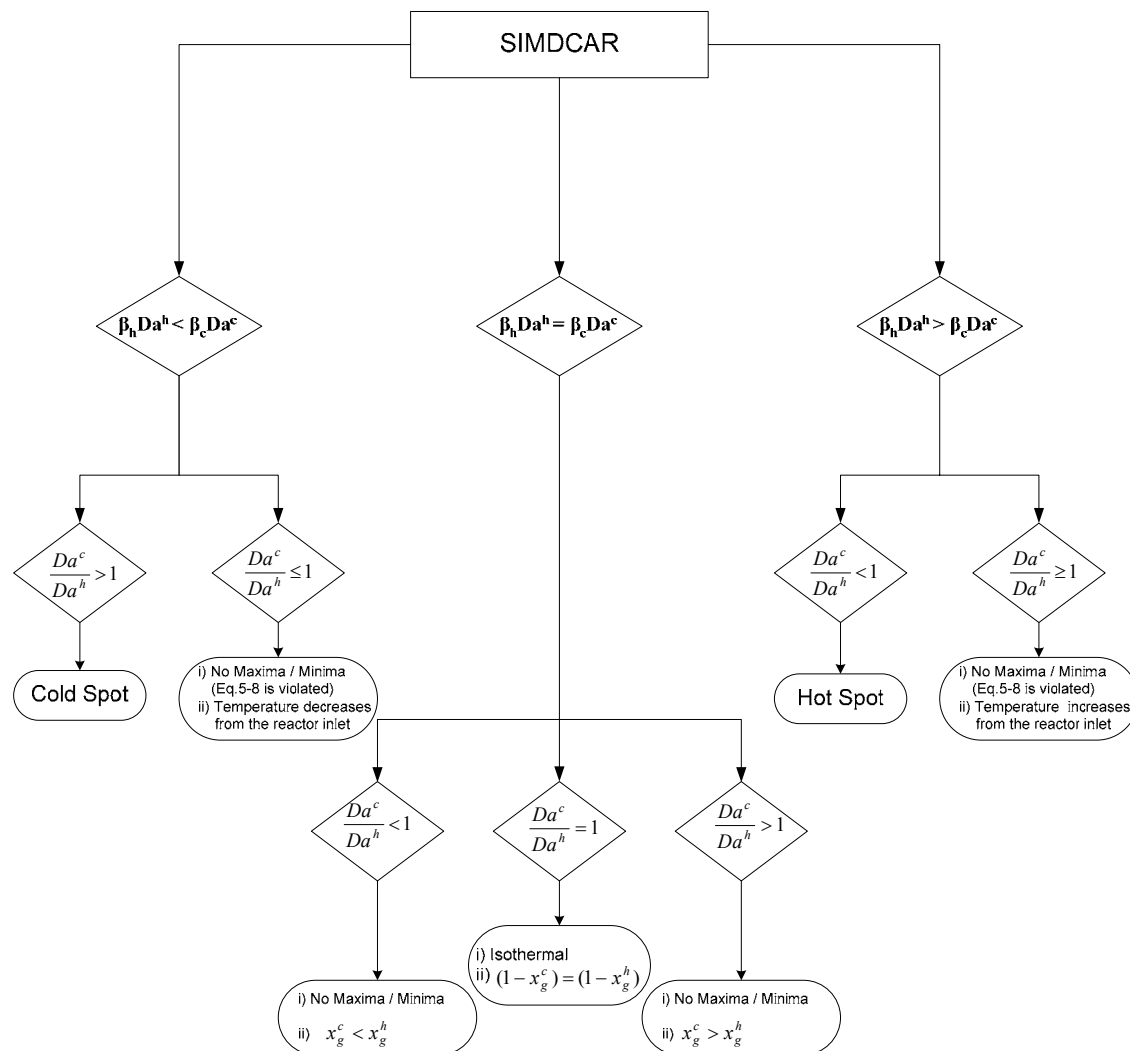


Figure 5-2: A Composite Diagram Showing the Different Patterns Exhibited by SIMDCAR

Combining Eq. 5.1 to Eq. 5.3, we have at the steady state,

$$d\theta_g = \beta^c dx_g^c + \beta^h dx_g^h \quad (5.9)$$

Hence at any point in the reactor,

$$\theta_g = \beta^c x_g^c + \beta^h x_g^h \quad (5.10)$$

From Eq. 5.10, the hot spot temperature can be calculated by using x_g^{c*} and x_g^{h*} obtained from Eqs. 5.5 and 5.8. It is to be noted that the occurrence of hot spot / cold spot is not bounded by the spatial co-ordinate, $\xi \in [0,1]$. Hence the conditions, $x_g^{c*} \leq x_g^c|_{Exit}$ and $x_g^{h*} \leq x_g^h|_{Exit}$ are also to be satisfied to confirm the occurrence of hot spot / cold spot within the reactor. The concentration and the temperature profiles along the reactor (hence the concentration / temperature at the reactor exit) can be obtained through numerical analysis, which are presented in the next section.

5.5 Results and Discussions

In this section, we analyze the steady state and dynamic behavior of different configurations of reactors based on the relative magnitudes of the rate of heat consumption and the rate of heat generation. We also compare the performance of DCARs with that of the co-current reactor. The discussion on the design and operational flexibility of different reactors is also presented.

5.6.1 Steady State Behavior

$\beta^c Da^c > \beta^h Da^h$: This condition simulates the case when the rate of heat consumption per unit volume (based on the inlet concentration) is greater than the rate of heat generation. Figures 5-3a and 5-3b show respectively the temperature and the conversion

profiles in three reactor configurations: i) SIMDCAR ii) SEQDCAR and iii) a co-current reactor. Four alternating beds of exothermic and endothermic catalysts are used in SEQDCAR. The positions of various catalyst beds used in SEQDCAR are i) exothermic from $\xi=0$ to $\xi=0.1$ ii) endothermic from $\xi=0.1$ to $\xi=0.15$ iii) exothermic from $\xi=0.15$ to $\xi=0.5$ and iv) endothermic from $\xi=0.5$ to $\xi=1.0$. In simulation, η^c and η^h are assigned 1 and 0 respectively in the bed with catalyst for endothermic reactions and vice versa in the catalyst bed for exothermic reaction. Care should be taken in deciding the length of the exothermic section near the reactor inlet since the chance of exothermic reaction going to completion and hence the temperature peak reaching the respective adiabatic temperature (hence the hot spot) exists.

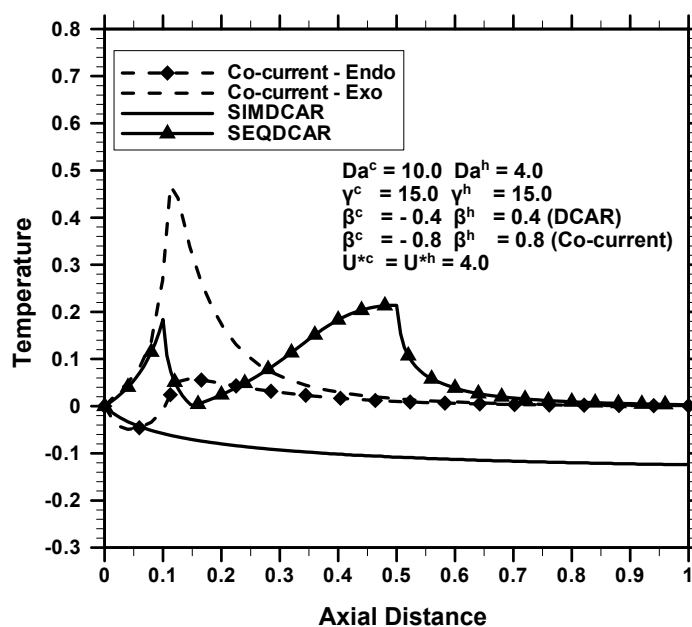


Figure 5-3a: Temperature Profiles in DCAR and Co-current Reactor predicted by Pseudo-homogeneous Model ($\beta^c Da^c > \beta^h Da^h$)

From Figure 5-3 it is clear that at these conditions, SIMDCAR qualitatively operates as an endothermic reactor with temperature decreasing from the reactor inlet and with a lower conversion. This behavior is in line with the discussion presented in Section 3. On the other hand, the sequential mode of operation results in a higher conversion. Two temperature peaks are observed in the temperature profile for SEQDCAR as shown in

Figure 5-3a. This is because the exothermic reaction is carried out in the two sections of the reactor. For the similar set of parameters, in the co-current reactor, the conversion for the endothermic reaction is around 99% and the temperature peak for the exothermic reaction is around 0.5 (using an optimal wall heat transfer coefficient).

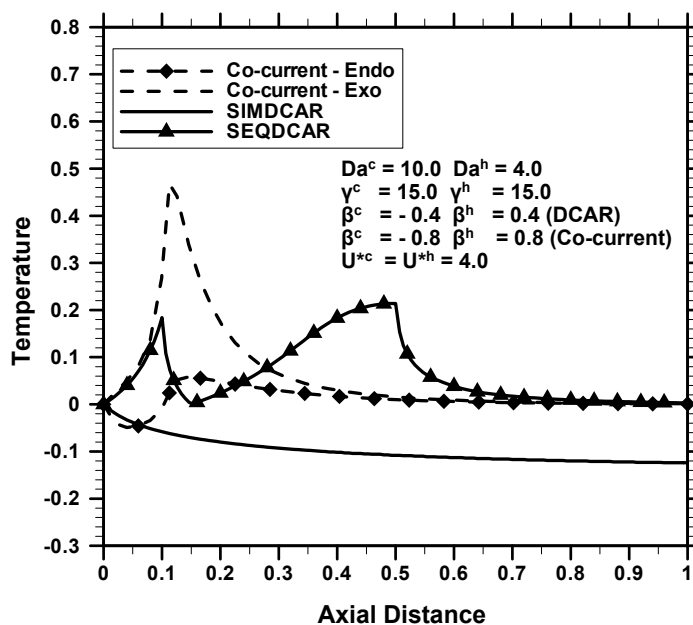


Figure 5-3b: Temperature Profiles in DCAR and Co-current Reactor predicted by Pseudo-homogeneous Model ($\beta^c Da^c > \beta^h Da^h$)

By catalyst activity profiling (by modifying the activity of the catalyst bed axially) in the co-current reactor, this temperature peak could be reduced to around 0.2 without sacrificing the conversion (Ramaswamy et al., 2006), as discussed in Chapter 3. Thus the co-current reactors are better than DCAR in obtaining the desired conversion for the parameters used. This is due to the controlled transfer of heat from the exothermic side to the endothermic side of the co-current reactor without the exothermic reaction getting extinguished. In SIMDCAR, because of the thermal mixing on micro scale, temperature of the system remains low and hence the conversions for both endothermic and the exothermic reactions remain low. For these parameters, SEQDCAR results in a higher conversion for the endothermic reaction than SIMDCAR. In SEQDCAR, the lengths of different sections of the reactors should be optimally chosen in order to avoid any hot

spots and to obtain higher conversion. Hence, we observe that for the cases when $\beta^c Da^c > \beta^h Da^h$, co-current reactor is better than the adiabatic reactors and in adiabatic reactors, SEQDCAR gives better conversion than SIMDCAR.

$\beta^c Da^c < \beta^h Da^h$: This refers to the case when the rate of heat consumption per unit volume (based on inlet concentration) is less than the rate of heat generation.

Figures 5-4a and 5-4b compare the temperature and conversion profiles respectively in SIMDCAR and SEQDCAR with those of the co-current reactor. It is also clear from Figures 5-4a and 5-4b that SIMDCAR results in the lower temperature peak compared to SEQDCAR. The thermal mixing occurring at the micro scale level in SIMDCAR reduces the occurrence of the high temperature peak since the endothermic reactions consumes the heat as and when it is released by the exothermic reaction. The magnitude of the maximum temperature in SEQDCAR is three times greater than that in SIMDCAR.

Figure 5-4b shows that the conversion of endothermic reaction in SEQDCAR is less than that in SIMDCAR. This is due to the fact that the available length for the endothermic reaction is less in the sequential arrangement. Figures 5-4a and 5-4b also reveals that the temperature profile in SIMDCAR is more or less equivalent to the temperature profile on the endothermic side of the co-current reactor and, hence, the conversion profiles for endothermic streams are also qualitatively identical in both the reactors. For these parameters, if the exothermic and the endothermic reactions are segregated in space with resistive heat transfer, as in the co-current reactor, it exhibits a large hot spot on the exothermic side. If the exothermic temperature peak and the conversion of the endothermic reaction are taken as a measure of the reactor performance, then SIMDCAR is better than co-current reactor when $\beta^c Da^c < \beta^h Da^h$. Also for this case, SIMDCAR gives better conversion with lower temperature peak than SEQDCAR.

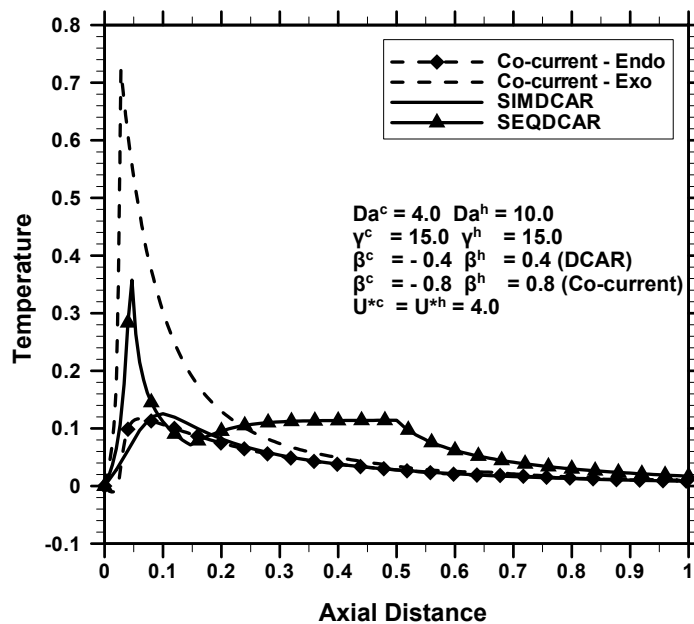


Figure 5-4a: Temperature Profiles of in DCAR and Co-current Reactor predicted by Pseudo-homogeneous Model ($\beta^c Da^c < \beta^h Da^h$)

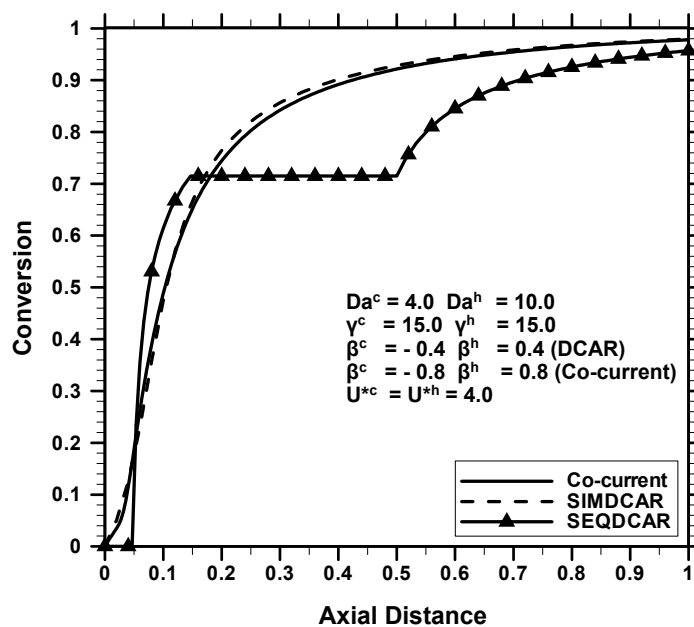


Figure 5-4b: Conversion Profiles of in DCAR and Co-current Reactor predicted by Pseudo-homogeneous Model ($\beta^c Da^c < \beta^h Da^h$)

$\beta^c Da^c = \beta^h Da^h$: Three cases arise when the rate of heat consumption equals the rate of heat generation. In this case, the reactors can be classified based on Damkohler number or dimensionless heat of reactions. If $Da^h = Da^c$ (or $\beta^c = \beta^h$) both the co-current and the adiabatic reactors give the desired conversion with lower temperature peak, for the parameters studied. If $Da^c > Da^h$, (the dimensionless heat of the reaction for the exothermic reaction is higher than the dimensionless heat of reaction for the endothermic reaction) then the SIMDCAR is better than the co-current reactor. Here, SIMDCAR favors the thermal mixing at the molecular scale, which reduces the temperature peak compared to that of the co-current reactor. If $Da^c < Da^h$, the co-current reactor gives better conversion than DCAR because of the controlled release of heat liberated by the exothermic reaction to the endothermic reaction through the wall. In SIMDCAR, the exothermic reaction is suppressed and hence enough heat is not available to increase the reaction rate and to enhance the conversion of the endothermic reaction.

We have also developed a heterogeneous model and used it to simulate the above cases. The predictions with the heterogeneous model qualitatively agree well with that of the pseudo-homogeneous model for the cases investigated and hence the results are not presented here.

5.6.2 Transient Behavior

The reactor dynamics is important for developing suitable control strategies and for the safe start-up and shut down of the reactors. Here, we present some key results that show the different dynamic behavior exhibited by coupling exothermic and endothermic reactions in the directly coupled adiabatic reactors. Figure 5-5 shows the temperature profiles obtained in a SEQDCAR during the startup of the reactor (for various dimensionless time) when $\beta^c Da^c > \beta^h Da^h$. The activity profiles used for the simulation of SEQDCAR are same as those mentioned in Section 5.6.1. It is clear from Figure 5-5 that during evolution, the temperature peak may be higher than the steady state profile. The observed traveling wave pattern is due to the interaction of different time scales,

like time scales of exothermic and endothermic reactions, time scale of convection of heat affected by the heat capacity of the bed. Because of the interaction of various time scales, some of the profiles have three peaks, while the steady state profile has only two peaks. These traveling hot spots could reduce the activity of the catalyst during the start-up of the reactor. Figures 5-6a and 5-6b show the evolution of temperature profiles in SIMDCAR and SEQDCAR, respectively, for the case when $\beta^c Da^c < \beta^h Da^h$.

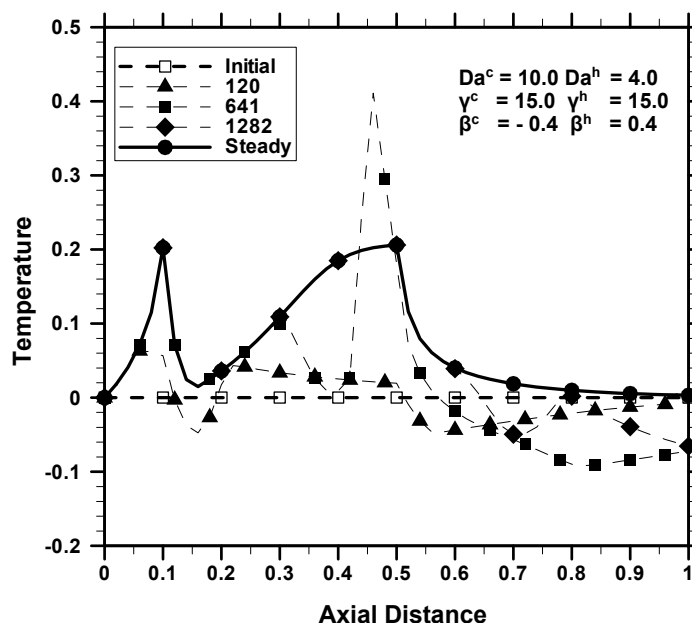


Figure 5-5: Evolution of Temperature Profiles in a SEQDCAR ($\beta^c Da^c > \beta^h Da^h$)

In these cases, the evolving transient profiles are bounded by the steady state profile. The temperature overshoot is not observed in this case, which may be due to the fact that the exothermic reaction attains 90% conversion in the first section of the reactor. The decrease in concentration of the feed for the exothermic reaction reduces the rate of exothermic reaction and hence avoids the occurrence of any wrong-way behavior / hot spots. Figures 5-6a and 5-6b show that there is a drop in some of the temperature profiles during evolution near the reactor exit. This is due to the occurrence of endothermic reaction near the reactor exit. The traveling waves are observed in SEQDCAR compared to SIMDCAR for these cases.

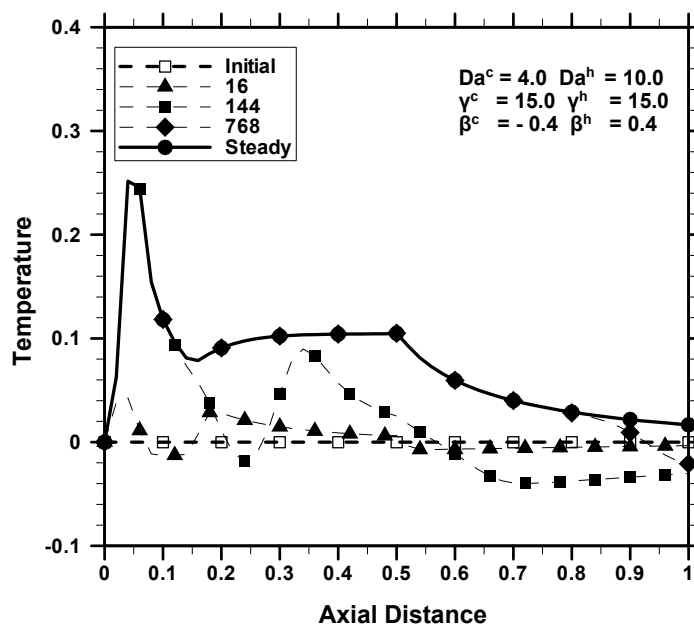


Figure 5-6a: Evolution of Temperature Profiles in a SEQDCAR ($\beta^c Da^c < \beta^h Da^h$)

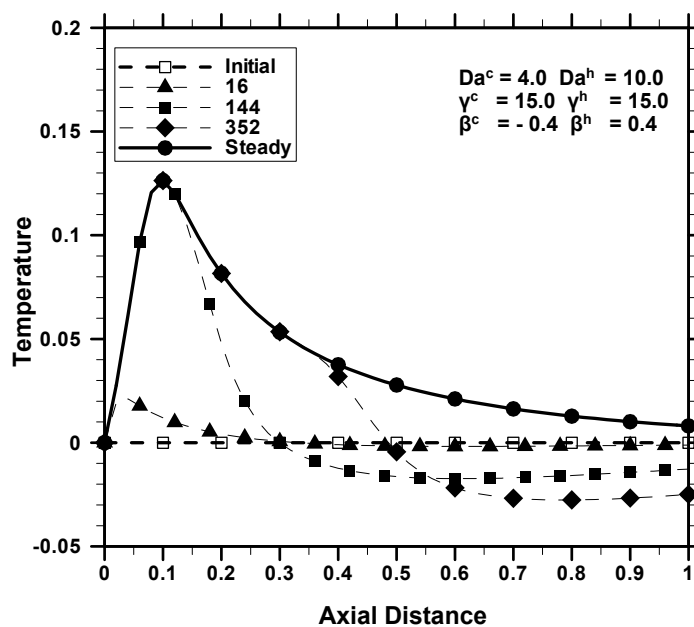


Figure 5-6b: Evolution of Temperature Profiles in a SIMDCAR ($\beta^c Da^c < \beta^h Da^h$)

5.6.3 Heterogeneous Models

The heterogeneous plug flow and axial dispersion models were also developed to analyze the performance of various modes of coupling. It is observed that the predictions by the higher order models were qualitatively similar to those of pseudo-homogenous models. Quantitatively there is a difference between pseudo-homogenous and heterogeneous models, in some cases, in the magnitude of hot spot and/or the position at which the hot spot occurs etc. This is due to the values of heat and mass transfer coefficients (transport resistances) and the dispersion coefficients used in the model. The main advantage of the heterogeneous model is that the temperature and the concentration at the catalyst surface can be predicted. It is observed that, in SIMDCAR, in the portion of the reactor where the exothermic reaction is predominant, the temperature at the catalyst surface is greater than that of bulk phase temperature. Similarly, in the region of the reactors where the endothermic reaction is predominant, it is observed that the bulk phase temperature is greater than the temperature at the solid surface. The results and the plots displaying the above observation are shown for a practical case study of catalytic partial oxidation of methane to syngas in Chapter 7.

Additionally, in the porous catalysts, the reactions (both exothermic and endothermic) may occur within the catalyst particle. In such a situation, the internal transport (diffusion) limitations play an important role in determining the reactor performance in addition to the external transport limitation. Depending on Thiele moduli (ratio of diffusion time scale within the catalyst pellet to the reaction time scale) for exothermic and endothermic reactions, the hot spot may occur within the catalyst pellet. Some of these conditions are studied in more detail in the next chapter.

5.6.4 Design and Operational Implications

The design of SIMDCAR is simpler compared to SEQDCAR and co-current reactors. In SEQDCAR the depth of individual beds has to be optimally chosen to obtain desired conversion and to avoid any hotspots. Similarly, in the co-current reactors, the issues

like the selection of tube material with the desired heat transfer coefficients, the spacing between the tubes are to be addressed and these parameters affect the conversion of the desired reactions, as shown in Chapters 3 and 4. On the contrary, the co-current reactors offer better operational flexibility compared to DCAR. The problems associated with product separation are generally not present in the co-current reactors. But in DCAR, the exothermic and the endothermic reactions have to be carefully chosen so that further downstream purification of the products is eliminated or the products could be easily separated. In co-current reactors, the operating parameters of any stream like Da , β etc., can be changed independently without affecting the other stream. Thus, the operating regime can be switched i.e., from $\beta^c Da^c < \beta^h Da^h$ to $\beta^c Da^c > \beta^h Da^h$, easily in the co-current reactor. DCAR does not offer this operational convenience.

5.6 Summary

This chapter investigated the simultaneous and sequential modes of conducting exothermic and endothermic reactions in the adiabatic reactors (SIMDCAR and SEQDCAR) and the reactor performance is compared with that of the co-current reactor. The conditions for the existence of hot spot and/or the cold spot in SIMDCAR are presented.

It is observed that if $\beta^c Da^c > \beta^h Da^h$, the conversion in the adiabatic reactor is lower than that in the co-current reactor and between the directly coupled adiabatic reactors; SEQDCAR should be used to obtain higher conversion. If $\beta^c Da^c < \beta^h Da^h$, then SIMDCAR results in higher conversion with a lower temperature peak compared to the co-current reactor and SEQDCAR. For the case, where $\beta^h Da^h = \beta^c Da^c$, the reactors are to be chosen based on the relative magnitudes of the exothermic and endothermic heats of reactions. The dynamic behaviors of these reactors are also investigated. SEQDCAR exhibits stronger traveling waves than SIMDCAR during evolution. These reactors exhibit hot spots during evolution for some of the cases and hence the detailed transient studies are to be considered for the design and optimization of directly coupled adiabatic reactors.

The SIMDCAR exhibits a wide range of temperature profile patterns based on the relative magnitudes of the heat generation rate ($\beta^h Da^h$) and the heat consumption rate ($\beta^c Da^c$). Thus, it can behave as an isothermal reactor, an exothermic or an endothermic reactor or the reactor where the endothermic reaction follows the exothermic reaction or the exothermic reaction follows the endothermic reaction. Hence it is clear that, especially for the packed bed reactor of latter cases with porous particles, when the exothermic and endothermic reactions compete (somewhere in the interior of the reactor), the catalyst particles undergo both the reactions. Some of the interesting behavior exhibited by the porous catalyst particles is studied in the next chapter.

Chapter 6

Coupling of Exothermic and Endothermic Reactions within the Porous Catalyst Particle

6.1 Scope

In the previous chapter it is discussed that the directly coupled adiabatic packed bed reactor can be operated as an isothermal reactor, an exothermic or an endothermic reactor or the reactor where the rate of endothermic reaction increases once the limited reactant of the exothermic reaction is completely consumed or the rate of the exothermic reaction increases once the limited reactant for the endothermic reaction completely disappeared. In the cases where the operating regime shifts from predominantly exothermic to predominantly endothermic (the latter two cases) or vice versa, there exists a region in the reactor where both exothermic and endothermic reactions compete with each other. In such regions, the porous catalyst particle undergoes both the reactions. The understanding of coupling behavior within the particle is essential for the robust design of catalysts to meet the required performance target. These systems are complex as the exothermic reaction within the catalyst particle could result in the multiple steady states. Hence the scope of this chapter includes the development of a robust numerical procedure to analyze the coupling behavior and to determine the multiple steady states in diffusion-reaction types of problems using a combination of the boundary element method (BEM) and the arc length continuation technique. The BEM based numerical procedure has been used to analyze the coupling in the catalyst particle and BEM combined arc length continuation technique has been used to investigate the multiple steady states in the current distributed parameter system. The use of boundary element method eliminates the numerical errors associated with the process of discretization of the differential operators and hence the use of BEM

in continuation methods could reduce the spurious steady states. Another advantage is that the Jacobian required for the continuation techniques is directly available from the BEM formulation. Hence BEM and continuation methods complement each other and can be used to predict the multiple steady states in the distributed parameter systems. Several standard problems are studied to demonstrate the usefulness of this method and the results are only presented for single exothermic reaction system and a coupled exothermic and endothermic reactions system. The particle level coupling of exothermic and endothermic reactions shows the dependence of heat source and heat sink in determining the region of multiple steady states in such systems and the region of multiplicity is narrowed in general.

6.2 Introduction

Several examples of the distributed parameter systems (DPS) can be found in the chemical engineering discipline like the mathematical models describing the diffusion-reaction process within a catalyst, dispersion-convection-reaction models for the packed bed reactors (one such case will be shown in the next chapter) etc. Some of these systems exhibit multiple steady states in the parameter range of practical interest (Hu et al., 1985a-c; Burghardt and Berezowski, 1989, 1991; Ramachandran, 1994; Dommeti et al., 1999; Liu and Jacobsen, 2004; etc.). The prediction of the multiple steady states is important for the optimization and control of these processes (Mancusi et al., 2000; Burghardt and Berezowski, 2003). Various numerical procedures used for the prediction of the multiple steady states and stability analysis are available in the literature (Kubicek and Marek, 1983; Golubitsky and Schaeffer, 1985; Liu and Jacobsen, 2004). The free domain software like AUTO (Doedel et al., 1997), XPPAUT (Ermentrout, 2002), LOCA (Salinger et al., 2002), CONT (Kohout et al., 2002) etc could also be used for the determination of multiplicity and for the related bifurcation and stability analysis. These algorithms and software are very effective in predicting the multiple steady states of the differential systems (lumped parameter systems) and have also been used for DPS. However, the determination of multiple steady states for the distributed

system is still a difficult compared to that for the lumped parameter system (LPS) as indicated by Kubicek and Marek (1983), Liu and Jacobsen (2004) and others..

The multiple steady states of DPS are usually obtained by a two step procedure (Kubicek and Marek, 1983). In the first step, the distributed parameter system is converted to the lumped parameter system by suitable discretization of the spatial derivatives. For example, the finite difference, finite element discretization or orthogonal collocation techniques can be used for the reduction of the DPS to LPS (Burghardt and Berezowski, 2003; Liu and Jacobsen, 2004). In the second step, a suitable continuation technique (for example, the arc length methods), is used on the LPS to determine the multiple steady states. In the overall computational process, the discretization of spatial derivatives (first step) introduces errors resulting in prediction of spurious bifurcation points and steady states (Liu and Jacobsen, 2004) in the second step. Hence, higher order discretization schemes with a larger number of discretization nodes are often required to obtain a reasonable accuracy in the solution. The finer approximations of DPS can increase the dimension of the resulting LPS used in the continuation method. Hence the determination of multiple steady states for DPS is numerically challenging.

As mentioned above, the techniques used in the first step to reduce DPS to LPS are prone to introduce numerical errors. This problem can be circumvented by using the boundary element method (BEM) for the step to generate equivalent LPS. Compared to other methods, BEM obviates the need to approximate the derivative operators and casts the problem in an integral format. This provides an extra element of accuracy and the solution based on this method has excellent convergence properties. The boundary element method has been successfully applied to diffusion with reaction (Ramachandran, 1990), electrochemical transport (Barbero et al., 1994) and packed bed heat transfer (Lesage et al., 2000). Also BEM requires fewer nodes / elements to capture the solution with higher accuracy compared to other methods (Ramachandran, 1994, 2005). Thus BEM stands out as a good choice to be used along with the continuation algorithm to determine the multiple steady states in DPS. In this approach, the

Jacobians required for the continuation algorithms are also directly obtained from the BEM formulation. This chapter focuses on the development and testing of such a numerical procedure for the determination of all the steady states of the diffusion-reaction processes using boundary element method (Ramachandran, 1994) and the arc length continuation algorithm (Kubicek and Marek, 1983). The developed technique is used to investigate the coupling of exothermic and endothermic reactions in a catalyst particle.

This chapter is arranged in the following manner. The next section presents the BEM for the diffusion reaction problems. The continuation algorithm applied on BEM formulation of diffusion reaction problems is provided in Section 6.4. Section 6.5 demonstrates the usefulness of this BEM-Continuation algorithm in determining multiple steady states in some benchmark chemical engineering problems (the cases with single reaction). Section 6.6 investigates the case where the coupling of exothermic and endothermic reactions taking place in a catalyst pellet is studied for multiplicity. Summary is presented at the end.

6.3 Boundary Element Method

Here, the diffusion-reaction problem is treated as a representative of DPS and the boundary element formulation for the diffusion reaction problems is presented for completeness. More details on BEM can be found in Ramachandran (1994). The multi-component diffusion-reaction process, in the steady state, can be represented mathematically as a set of second order differential equations:

$$\nabla^2 C_k = \frac{1}{x^r} \frac{d}{dx} \left(x^r \frac{dC_k}{dx} \right) = R_k(C_1, C_2, \dots, C_m, x; \alpha) \quad (6.1)$$

where $r = 0, 1,$ and 2 for slab, cylinder and sphere respectively and k denotes the equation index; $k = 1$ to m with m being the total number of differential equation. The function R_k is the forcing function (non-linear rate expressions) for the k^{th} equation. The

dependent variable C_k is usually the concentration of the various species k as well as the temperature in the non-isothermal system. α is the parameter or the vector of parameters whose dependency on the solution is often required.

Due to the non linear nature of the problem (Eq. 6.1) BEM is usually applied on a subdomain basis. Thus the domain is discretized into $N-1$ subdomains, with $x = 0$ being the node 1 and $x = 1$, designated as the node N . Over any subdomain (a,b) the solution proceeds by forming a weighted residual formulation of Eq. 6.1 with weighting functions G . Thus multiplying Eq. 6.1 by $x^r G$ and integrating with respect to x from a to b we obtain the weighted residual formulation for any k^{th} equation:

$$\int_a^b G \frac{d}{dx} \left(x^r \frac{dC_k}{dx} \right) dx = \int_a^b x^r G R_k(C_1, C_2, \dots, C_m, x; \alpha) dx \quad (6.2)$$

The weighting function, G , is determined as the solution to the adjoint operator:

$$\frac{d}{dx} \left(x^r \frac{dG}{dx} \right) = 0 \quad (6.3)$$

Two linearly independent solutions of Eq. 6.3 form the weighting functions G_1 and G_2 and a choice of these functions, for three standard geometries is specified as follows:

$$\text{Slab : } G_1 = x-a, G_2 = b-x \quad (6.4a)$$

$$\text{Cylinder : } G_1 = \ln(x), G_2 = 1 \quad (6.4b)$$

$$\text{Sphere : } G_1 = -1/x, G_2 = 1 \quad (6.4c)$$

With this choice for G , Eq. 6.2 can be reformulated (by integrating by parts twice) as the boundary integral element formulation:

$$\begin{aligned}
& -a^r G(a) p_{ak} + a^r G'(a) C_{ak} + b^r G(b) p_{bk} - b^r G'(b) C_{bk} \\
& - \int_a^b x^r G R_k(C_1, C_2, \dots, C_m, x; \alpha) dx = 0
\end{aligned} \tag{6.5}$$

where, the gradient of the dependent variable is represented as p . Thus,

$$p_k = \frac{dC_k}{dx} \tag{6.6}$$

and G' is the derivative of G with respect to x .

The non-linear forcing function, R , can be represented in quasi-linearized sense at each stage of iteration as,

$$R_k = K_{0,k} + \sum_{M=1}^m K_{1,kM} C_M \tag{6.7}$$

where,

$$K_{0,k} = R_k^* - \sum_{M=1}^m \left\{ \left. \frac{\partial R_k}{\partial C_M} \right|_{C_M^*} \right\} C_M^* \tag{6.8a}$$

$$K_{1,kM} = \left. \frac{\partial R_k}{\partial C_M} \right|_{C_M^*} \tag{6.8b}$$

$K_{0,k}$ and $K_{1,kM}$ are respectively the zero and first order terms in the Taylor's expansion used for the quasi-linearization and C_M^* represents the average value of the concentration of species M over a given element at the current level of iteration.

The integral terms on Eq. 6.5 are substituted in Eq. 6.7, resulting in:

$$\begin{aligned}
& -a^r G(a) p_{ak} + a^r G'(a) C_{ak} + b^r G(b) p_{bk} - b^r G'(b) C_{bk} - \int_a^b x^r G \sum_{M=1}^m K_{1,kM} C_M dx \\
& = \int_a^b x^r G K_{0,k} dx
\end{aligned} \tag{6.9}$$

To evaluate the integral term containing C_M on Eq. 6.9, an osculating polynomial for C_M for each sub domain is constructed and is given by,

$$C_M = (b-a)\varphi_1 p_{aM} + \varphi_2 C_{aM} + (b-a)\varphi_3 p_{bM} + \varphi_4 C_{bM} \tag{6.10}$$

The functions φ_i are given below (Ramachandran, 1994).

$$\begin{aligned}
\varphi_1 &= \eta - 2\eta^2 + \eta^3 \\
\varphi_2 &= 1 - 3\eta^2 + 2\eta^3 \\
\varphi_3 &= -\eta^2 + \eta^3 \\
\varphi_4 &= 3\eta^2 - 2\eta^3
\end{aligned} \tag{6.11a-d}$$

$$\text{where, } \eta = \frac{x-a}{b-a} \tag{6.12}$$

Upon substituting Eqs. 6.10, 6.11, and 6.12 in Eq. 6.9, the discretized boundary element equations for each of the k species is obtained. The k^{th} equation can be compacted by using the Kronecker delta (δ_{kM}) notation. Thus for any subinterval, the discretized version of the k^{th} equation is,

$$\sum_{M=1}^m H_{l1M} p_{aM} + H_{l2M} C_{aM} + H_{l3M} p_{bM} + H_{l4M} C_{bM} = F_{lk}, \quad l=1 \text{ and } 2 \tag{6.13}$$

Various coefficients used in Eq. 6.13 are provided in Table 6-1. The two equations, Eq. 6.13, along with the respective boundary conditions represent the original diffusion reaction problem (Eq. 6.1) in the discretized form. A steady solution is obtained by solving Eq. 6.13 with the respective boundary conditions iteratively.

The above set of equations, Eq. 6.13, can be compactly represented as

$$f_i = \sum_{j=1}^{2Nm} A_{ij} y_j - B_i = 0, \quad i = 1, 2, \dots, 2m, \dots, 2Nm \quad (6.14)$$

where, $A_{ij} = \frac{\partial f_i}{\partial y_j}$ (which are the coefficients, H , appearing in Eq. 6.13) and y_j s are the total $2Nm$ variables used in BEM formulation, which are the dependent variables (C_k) and its respective flux (p_k) at each node. The next section explains the implementation of continuation algorithm using Eq. 6.14.

Table 6-1: Element level coefficient matrix in BEM discretization as per Eq. 6.13;

Note $l = 1$ and 2

H_{11M}	$-a^r G_l(a) \delta_{kM} - (b-a) K_{1,kM} \int_a^b x^r G_l \phi_1 dx$
H_{12M}	$a^r G_l'(a) \delta_{kM} - K_{1,kM} \int_a^b x^r G_l \phi_2 dx$
H_{13M}	$b^r G_l(b) \delta_{kM} - (b-a) K_{1,kM} \int_a^b x^r G_l \phi_3 dx$
H_{14M}	$-b^r G_l'(b) \delta_{kM} - K_{1,kM} \int_a^b x^r G_l \phi_4 dx$
F_{lk}	$\int_a^b x^r G_l K_{0,k} dx$

6.4 Continuation Algorithm

The multiple steady states are predicted using the continuation algorithm on the discretized representation given by Eq. 6.14. The procedure used in this work to calculate the multiple steady states is arc length continuation technique as prescribed by Kubicek and Marek (1983).

Here, let us consider α , as a parameter of the model and determine the solution of the problem as a function this parameter. Then Eq. 6.14 can be rewritten as,

$$\vec{f}(\vec{y}(\alpha), \alpha) = 0, \alpha \in [\alpha_0, \alpha_1] \quad (6.15)$$

In this continuation technique, the arc length of the solution curve is considered as an independent parameter of the method. Upon differentiating Eq. 6.15 with respect to z , the arc length, we get,

$$\frac{df_i}{dz} = \sum_{j=1}^{2Nm} \frac{\partial f_i}{\partial y_j} \frac{dy_j}{dz} + \frac{\partial f_i}{\partial \alpha} \frac{d\alpha}{dz} = 0, \quad i = 1, 2, \dots, 2Nm \quad (6.16)$$

The additional equation needed to determine z , the length of the arc of the solution curve, is given by the Pythagorean rule

$$\sum_{j=1}^{2Nm} \left(\frac{dy_j}{dz} \right)^2 + \left(\frac{d\alpha}{dz} \right)^2 = 1 \quad (6.17)$$

The initial conditions for Eq. 6.16 are given as,

$$z = 0, \vec{y} = \vec{y}_0, \alpha = \alpha_0.$$

The initial conditions are the solutions of the original set of differential equations (Eq. 6.1) known at any particular value of α , say α_0 . It is clear by comparing Eq. 6.14 and Eq.

6.16 that BEM provides the jacobi $\frac{\partial f_i}{\partial y_j}$ (which are the coefficients, H , appearing in Eq.

6.13), and only the extra derivatives, $\frac{\partial f_i}{\partial \alpha}$ are to be calculated. In this work, $\frac{\partial f_i}{\partial \alpha}$ are

calculated numerically for simplicity and this proved to be sufficiently accurate as shown by the results.

The details of implementation of this method are now described. The solution vector is now augmented by defining y_{2Nm+1} as α . Also, Eqs. 6.16 and 6.17 are rearranged in terms of a chosen control variable, y_k :

$$\sum_{\substack{j=1 \\ j \neq k}}^{2Nm+1} \frac{\partial f_i}{\partial y_j} \frac{dy_j}{dz} = -\frac{\partial f_i}{\partial y_k} \frac{dy_k}{dz}, \quad i = 1, 2, \dots, 2Nm \quad (6.18)$$

$$\sum_{\substack{j=1 \\ j \neq k}}^{2Nm+1} \left(\frac{dy_j}{dz} \right)^2 = 1 - \left(\frac{dy_k}{dz} \right)^2 \quad (6.19)$$

Note that the parameter α itself is chosen as the control variable (k^{th} variable) to start the calculations. Once $|dy_k/dz|$ becomes less than a prescribed tolerance (close to zero), then a new variable (say i) with highest derivative $|dy_i/dz|$ is selected as the new control variable.

Now, the solutions \vec{y} along the arc length z are calculated from the following set of differential equations:

$$\frac{dy_j}{dz} = \beta_j \frac{dy_k}{dz}, \quad j = 1, 2, \dots, k-1, k+1, \dots, 2Nm+1 \quad (6.20)$$

where β_j and $\frac{dy_k}{dz}$ are obtained as shown below.

Substitution of Eq. 6.20 in Eq. 6.18 leads to the set of linear algebraic equations:

$$\sum_{\substack{j=1 \\ j \neq k}}^{2Nm+1} \frac{\partial f_i}{\partial y_j} \beta_j = -\frac{\partial f_i}{\partial y_k}, \quad i = 1, 2, \dots, 2Nm \quad (6.21)$$

The solutions of Eq. 6.21 provide the values of β_j . Then using Eq. 6.19, we find,

$$\left(\frac{dy_k}{dz}\right)^2 = \left(1 + \sum_{\substack{j=1 \\ j \neq k}}^{2Nm+1} (\beta_j)^2\right)^{-1} \quad (6.22)$$

The sign of the derivative dy_k/dz in Eq. 6.22 is given by the orientation of the parameter z along the curve – the direction of movement along the curve. The system of equations, Eq. 6.20, can now be solved and marched along the arc length by a suitable numerical integration solver. In this work, we have used LSODE solver from Netlib libraries for the integration.

This algorithm generates a continuous solution curve and passes through limit points without any difficulties and continues at bifurcation points on the next branch (usually at a random direction). Some of the examples presented in the next section demonstrate the applications of BEM-continuation algorithm in determining the multiple steady states.

6.5 Illustrations

The multiple steady states are predicted using BEM-Continuation method for some chemical engineering test problems for the purpose of validation of the numerical method and are illustrated in this section.

6.5.1 Example 1a: A Non-isothermal Chemical Reaction in a Slab Catalyst

The mass balance and energy balance equations describing the diffusion process with irreversible first order reaction kinetics in slab geometry can be combined in the absence of external transport processes into a single equation. The resulting governing equation is given as,

$$\frac{d^2 C}{dx^2} - \Phi^2 C \exp\left[\frac{\gamma\beta(1-C)}{1+\beta(1-C)}\right]$$

Here, C is the concentration of the reactants and Φ , γ , β are respectively Thiele modulus, dimensionless activation energy and dimensionless heat of reaction (includes the thermal conductivity of the solid) . The boundary conditions used are:

- (i) at the catalyst centre, $x = 0$, $\frac{dC}{dx} = 0$
- (ii) and at the surface, $x = 1$, $C = 1$.

For certain range of parameters, (for example, $\Phi=0.15$, $\gamma=20$, $\beta=0.8$), this system exhibits multiple steady states. Figure 6-1 shows the concentration profile within the catalyst pellet for this set of parameters. All the three multiple steady states were predicted by BEM using different initial guesses.

In order to obtain the complete solution as a function of Φ , BEM-continuation method described earlier was used with Thiele modulus as the continuation parameter ($\alpha = \Phi$). The concentration at the centre of pellet for different Thiele modulus is plotted in Figure 6-2. Here, the continuation analysis indicates that multiple steady states exist in the range of $\Phi = 0.069$ to $\Phi = 0.25$ and these results are in agreement with earlier studies. The three steady state concentrations at the catalyst centre, corresponding to $\Phi=0.15$, shown in Figure 6-2 match with those reported in Figure 6-1. In this example, ten elements are used in the BEM discretization and the obtained results match those of with the larger number of nodes.

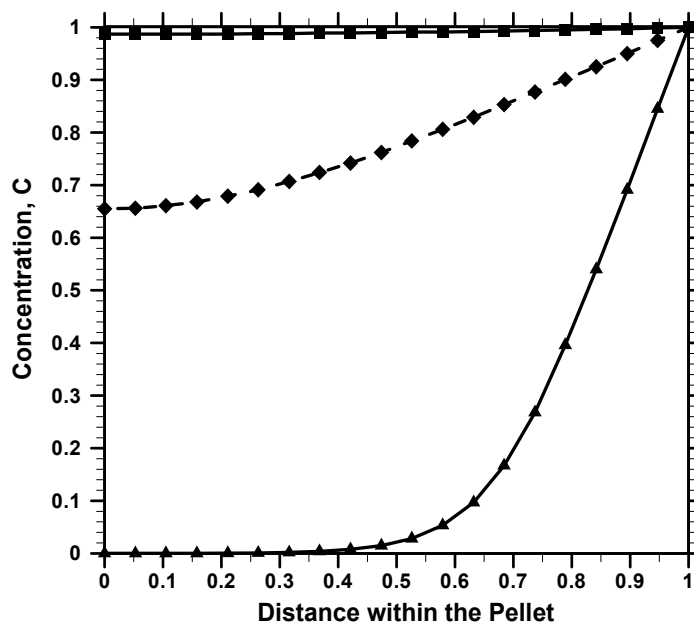


Figure 6-1: Concentration Profiles in a Catalyst Pellet for Example 1a Predicted by BEM using Different Initial Guesses ($\Phi=0.15$, $\gamma=20$, $\beta=0.8$)

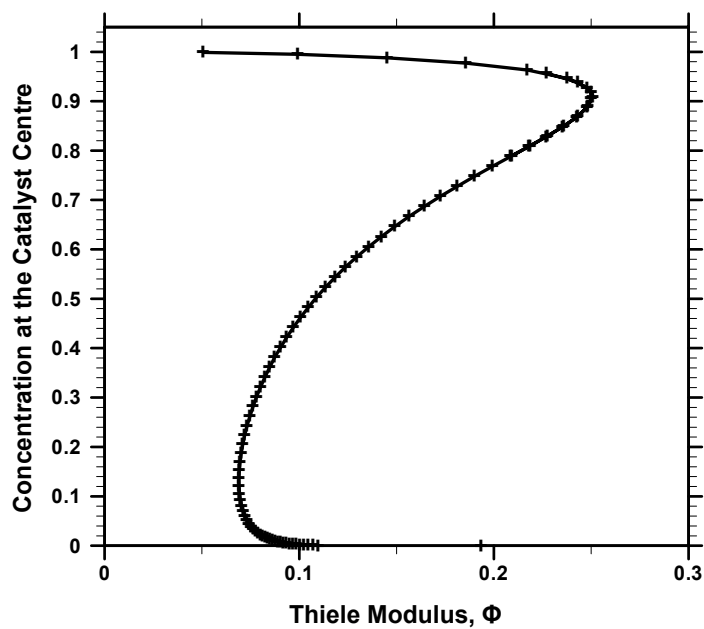


Figure 6-2: Concentration at the Centre of the Catalyst for Example 1a predicted by BEM-Continuation Technique ($\gamma=20$, $\beta=0.8$)

6.5.2 Example 1b: Reaction in the Catalyst Pellet with External Transport Resistances

The diffusion reaction problem, same as the above is considered with external mass and heat transport resistance. This system is modeled as a set of two second order differential equations one for concentration and the other for temperature with the respective boundary conditions. The model equations and the respective boundary conditions used and the other details can be found in Aris and Hatfield (1969). It was shown in the original paper that this system exhibits multiple steady states for a certain range of transport parameters. We tested BEM-continuation method for this problem by simulating a case with the set of parameters ($Bi=10$, $Sh=30$) reported in the original paper. Figure 6-3 shows the effect of Thiele modulus on the effectiveness factor and one could observe two peaks in the effectiveness factor. This result is in agreement with that reported by Aris and Hatfield (1969). Twenty boundary elements are used to simulate this case and BEM-continuation approach is robust and accurate in capturing the five steady states occurring at a particular Thiele modulus (around 0.25).

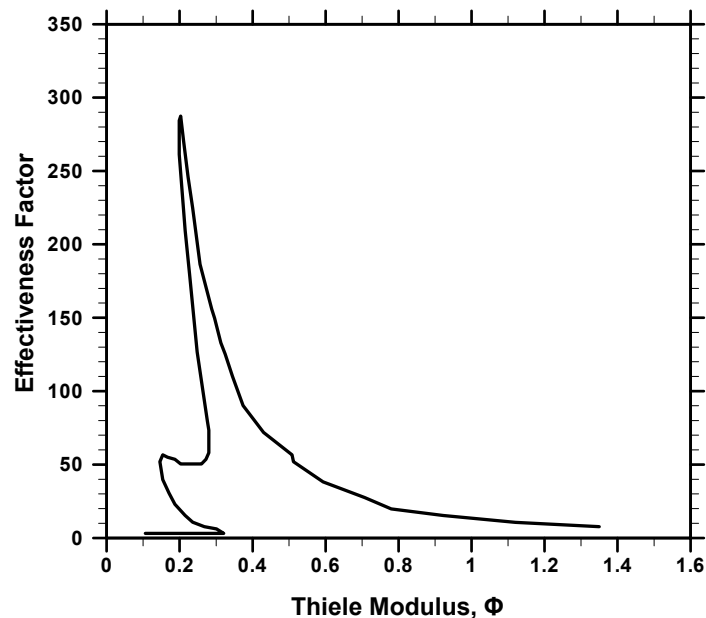


Figure 6-3: Effectiveness Factor vs. Thiele Modulus for a First-Order Reaction in a Slab Catalyst ($\gamma=27$, $\beta=1/3$, $Sh=30$, $Bi=10$) (Example 1b)

6.6 Coupling of Exothermic and Endothermic Reactions in a Porous Catalyst Particle

Several catalyst systems favor both exothermic and endothermic reactions like rhodium catalyst used for partial oxidation of methane to syngas production. Here we evaluate a model catalyst system that favors both exothermic and endothermic reactions. Two parallel reactions, $A \rightarrow R$ (Exothermic) and $C \rightarrow S$ (Endothermic) are considered in this work. A first order irreversible kinetics is assumed for both exothermic and endothermic reactions.

The governing equations for this system are:

$$\frac{d^2 C_1}{dx^2} = \Phi_h^2 C_1 \exp[\gamma^h (1 - \frac{1}{T})]$$

$$\frac{d^2 C_2}{dx^2} = \Phi_c^2 C_2 \exp[\gamma^c (1 - \frac{1}{T})]$$

$$\frac{d^2 T}{dx^2} = -\beta_h \Phi_h^2 C_1 \exp[\gamma^h (1 - \frac{1}{T})] - \beta_c \Phi_c^2 C_2 \exp[\gamma^c (1 - \frac{1}{T})]$$

Here C_1 and C_2 are the dimensionless concentrations of the reactant for exothermic (A) and endothermic (C) reactions respectively, non-dimensionalised using the total concentration (C_{tot}) at the catalyst surface (i.e. $C_i = C_{actual,i} / C_{tot}$). T is the dimensionless temperature of the system ($= T_{actual} / T_{ref}$). The other parameters are:

$$\text{Thiele Modulus, } \Phi_j^2 = \frac{k^j (T_{ref}) L^2}{De_m^j}$$

$$\text{Activation Energy, } \gamma^j = \frac{E^j}{RT_{ref}}$$

$$\text{Heat of Reaction, } \beta_j = \frac{-\Delta H^j De_m^j C_{tot}}{k_e T_{ref}}$$

where $j = c, h$ (c for endothermic reaction - $C \rightarrow S$, and h for exothermic reaction - $A \rightarrow R$), L is characteristic length of the catalyst, k is the reaction rate constant, E and ΔH are

respectively activation energy and heat of reaction , and De_m and k_e are respectively the effective diffusivity of species and the effective thermal conductivity of the solid. Note that β is positive for exothermic reaction ($j = h$) and negative for endothermic reaction ($j = c$).

The boundary conditions are:

at the catalyst surface ($x = 1$): $C_1 = C_{1s}$; $C_2 = C_{2s}$; $T = T_s$ (with $C_{1s} + C_{2s} = 1$)

at the catalyst centre ($x = 0$): $\frac{dC_1}{dx} = 0$; $\frac{dC_2}{dx} = 0$; $\frac{dT}{dx} = 0$

We carried out a simulation study using BEM to obtain the steady state temperature profile within the catalyst pellet. The parameters used are: $\gamma^h=27$, $\beta_h=1/3$, $\Phi_c=0.25$, $\gamma^c=27$, $\beta_c=-2/3$, $C_{1s}=0.9$, $C_{2s}=0.1$. Figure 6-4 shows the temperature profile within the catalyst pellet for two different Thiele moduli, $\Phi_h=0.35$ and $\Phi_h=2.5$. It is clear from these results that for lower Thiele modulus, the system exhibits multiple steady states whereas for $\Phi_h=2.5$, the system has a unique steady state. In Figure 6-4, the temperature profiles for $\Phi_h=0.35$ resemble those of the cases with exothermic reaction. In other words, the maximum temperature is reached at the centre of the pellet. On the other hand for the case with higher Thiele modulus, maximum temperature occurs at some intermediate point within the pellet. This is because the exothermic reaction is predominant very near the pellet surface, thus the temperature increases from pellet surface to that point. Once the exothermic reactants are completely consumed, the endothermic reaction dominates and hence the temperature decreases further till the centre of the catalyst pellet.

The range, at which the multiplicity occurs in this system, is predicted using BEM-continuation method. Figure 6-5 presents the temperature at the centre of the catalyst as a function of Thiele modulus for exothermic reaction (Φ_h) for different reactant concentration at the catalyst surface (C_{1s} and C_{2s}). All other parameters are the same as provided in Figure 6-4.

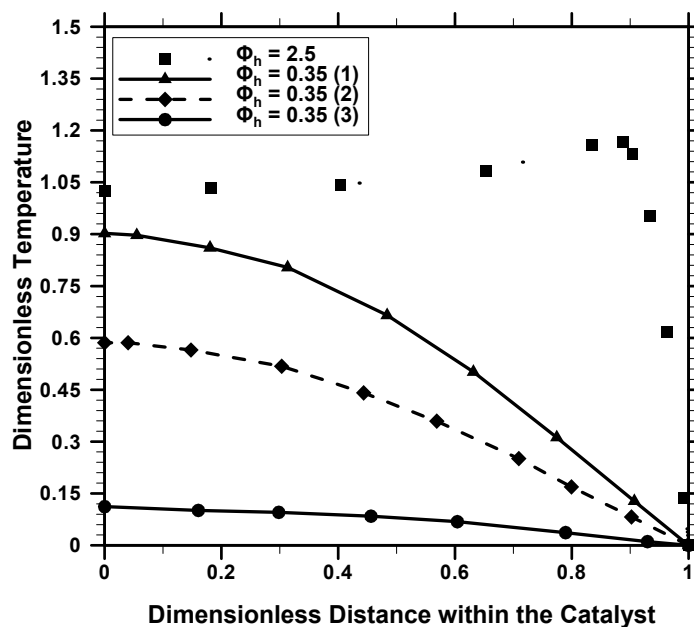


Figure 6-4: Concentration Profile within a Catalyst Pellet where both Exothermic and Endothermic Reactions Occur ($\gamma^h=27$, $\beta_h=1/3$, $\Phi_c=0.25$, $\gamma^c=27$, $\beta_c=-2/3$, $C_{1s}=0.9$, $C_{2s}=0.1$)

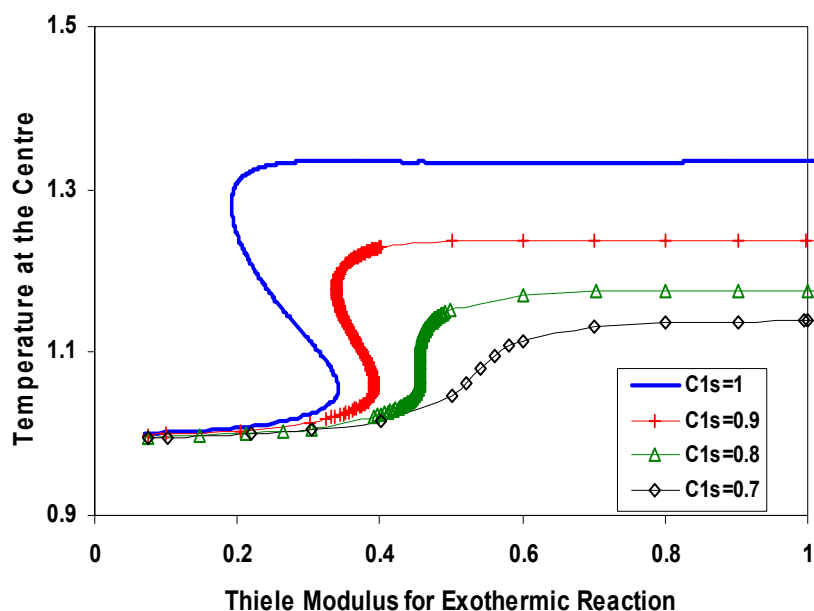


Figure 6-5: Multiple Steady States in a Catalyst Pellet with First Order Exothermic Reaction and Endothermic Reactions (Φ_h - varied, $\gamma^h=27$, $\beta_h=1/3$, $\Phi_c=0.25$, $\gamma^c=27$, $\beta_c=-2/3$)

At any Thiele Modulus, with decrease in the surface concentration of C_1 (hence increase in C_{2s}), the temperature at the centre of the catalyst decreases. Also it is clear from Figure 6-5 that with decrease in the surface concentration of the reactants of exothermic reaction, the region of multiple steady states shifts to higher Thiele moduli. The range of Thiele modulus for which the multiple steady states exist, decreases with increase in the concentration of endothermic reactants at the catalyst surface and further, the multiplicity disappears after a critical surface composition (below $C_{1s} = 0.7$).

The results obtained by coupling exothermic and endothermic reactions are compared to a case with only exothermic reaction in order to examine the region of multiplicity. Table 6-2 presents the region of multiplicity for different composition at the catalyst surface for these two cases. The case where only the exothermic reaction takes place, can be simulated by setting $\Phi_c^2 = 0$ for comparison purposes. In this case C_2 represents the concentration of inert species in the system. The other parameters are same as the base case. From Table 6-2 it is clear that the range of Thiele modulus at which multiplicity occurs increases with increase in the composition of exothermic reactants at the surface for both the cases. Also it is observed that for the system with only exothermic reaction, the multiplicity occurs when C_{1s} is higher than 0.6. However, for the case with both exothermic and endothermic reactions, the multiplicity occurs only when C_{1s} is higher than 0.8.

Hence the presence of endothermic reaction stabilizes the reaction system and reduces the range of Thiele modulus, at which multiplicity occurs. The occurrence of multiple steady states with respect other parameters like γ^h , γ^c , β_h , β_c etc., can also be examined using the developed BEM-Continuation technique and are not addressed in this work.

Table 6-2: Region of Multiplicity for Different Surface Concentrations ($\gamma^h=27$, $\beta_h=1/3$, $\gamma^c=27$, $\beta_c=-2/3$)

Concentration of Exothermic Reactants at the surface, C_{Is}	Range of Thiele Modulus with Multiple Steady States (Φ_h)	
	Only Exothermic Reaction, $\Phi_c = 0$	Exothermic and Endothermic Reaction, $\Phi_c = 0.25$
0.1-0.5	No Multiplicity	No Multiplicity
0.6	0.468-0.487	No Multiplicity
0.7	0.370-0.424	No Multiplicity
0.8	0.305-0.399	0.456-0.457
1.0	0.192-0.340	0.192-0.340

6.7 Summary

The boundary element combined arc length continuation technique was shown to be an effective method to determine the multiple steady states in the multi variable distributed parameter systems like diffusion-reaction problems. The BEM approach eliminates the discretization errors in the derivatives while the arc length continuation method smoothly captures the complete dependency of the solution on any parameter including the region of multiple steady states. This combined procedure is quite reliable and easy to implement and use. Several illustrative examples demonstrate the robustness of this method. This approach was also used to determine the multiple steady states in the catalyst particles where both exothermic and endothermic reactions take place. It was found that the multiple steady states were vanished by the presence of endothermic reactions for certain reactant composition at the catalyst surface. This study is important for controlling the hot spot in the interior of the catalyst, thus avoiding the catalyst deactivation through sintering, and for stabilizing the process system.

Chapter 7

Modeling of Catalytic Partial Oxidation of Methane to Syngas in Short Contact Time Packed Bed Reactors

7.1 Scope

The catalytic partial oxidation of methane to syngas is investigated as a case study because of the interesting challenges it offers due to the interaction of exothermic combustion and endothermic reforming reactions. In this system, methane is a common reactant for both the exothermic and the endothermic reactions. The steam produced in the exothermic combustion step undergoes the endothermic reforming reactions with methane. Hence, at the reactor inlet, the rate of heat generation by exothermic reaction is greater than the rate of heat consumption by endothermic reaction, in general. From the guidelines discussed in Chapter 5, it is clear that the directly coupled reactor, such as packed bed reactor, is suitable for this partial oxidation process. Hence, in this chapter, the steady state and dynamic behavior exhibited by this process in a short contact time packed bed reactor is analyzed using the heterogeneous plug flow and axial dispersion models. The effects of inlet mass velocity and feed quality (such as the presence of steam in the feed and the effects of methane-to-oxygen ratio and methane-to-steam ratio in the feed) on the product yield and hotspots are analyzed. The effects of film transfer coefficients and axial dispersion coefficients on the steady state profiles are also discussed. The evidence for the occurrence of wrong way behavior, due to the perturbation of the inlet temperature and the feed quality, in this short contact time reactor is presented.

7.2 Introduction

Syngas is an important feedstock for the production of synthetic automotive fuels (synfuels) and for a variety of chemicals like methanol and its derivatives. Syngas is produced from wide range of hydrocarbons, such as natural gas (mostly methane), naphtha, coal, etc., and the different methods used to produce syngas were discussed in Chapter 2. Several oil companies, such as ExxonMobil, Shell and others are building plants in Qatar, Middle East, to be commissioned in the second part of this decade, to convert natural gas to Fischer-Tropsch liquids (fuels). The production of synfuels and chemicals from natural gas and coal, through the syngas route, could reduce the consumption of crude oil.

The availability of pollutant free natural gas and the ability to produce the desired ratio of CO/H₂ (~0.5 for methanol synthesis), have attracted much research on the conversion of methane to synthesis gas by the catalytic partial oxidation route. Syngas production by the catalytic partial oxidation route proceeds through the coupled exothermic combustion reaction(s) and the endothermic reforming reactions, in the same catalyst bed. The simultaneous occurrence of combustion and reforming reactions, in this partial oxidation processes, makes this route more attractive as it minimizes the energy requirement for the production of syngas compared to the steam reforming route.

The mechanism of methane conversion to syngas is still debated in the literature. Although the possibility of performing the reaction via the direct route (in one step from methane to syngas) has been reported by several researchers, there seems to be an increasing consensus that (for most of the catalysts) the reaction occurs mainly via the indirect route. It is to be noted that the hot spot could be eliminated if the reaction occurs via the direct route. Schmidt's group (2001) reported that with highly active *Rh* based catalysts the entire process could be completed in a short contact time of the order of milliseconds and the reactors used for this process are called short contact time reactors. Because of the complexity of the processes due to the interactions of exothermic and endothermic reactions in a system where the flow time scale is also

short, a suitable mathematical model is required for the optimization of the process and for reactor control.

The reported modeling studies in the literature discuss, mostly, the steady state behavior of this process, in particular, the effects of feed temperature, importance of gas phase reactions at higher operating pressure and the role of thermal conductivity of the catalyst bed and gas hourly space velocity (GHSV) on the methane conversion and on the product pattern. The interaction between exothermic and endothermic reactions becomes more significant especially during the transient operations and there is not much information available in the literature on the dynamic behavior of these reactors. In this work, we investigate some of the transient aspects in more detail using 1-D transient heterogeneous plug flow and axial dispersion models of the short contact time packed bed reactors. Some of the key transient behavior, including the wrong way phenomenon, resulting in response to a sudden increase or decrease in the feed temperature (from a steady state profile) is analyzed. The steady state and dynamic behavior resulting from the interaction of the exothermic and endothermic reactions due to the addition of steam in the feed is investigated. The effects of the inlet mass velocity (hence gas hourly space velocity, GHSV) on the temperature profile and on the product distribution are also discussed. Here, we attempt to resolve the debated issue of increase in the conversion of methane with increase in GHSV in the short contact time reactors. The effects of transport coefficients and dispersion coefficients on the hot spot, length of the reactor and on the time taken to reach the steady state are presented.

The next section (Section 7.3) presents the heterogeneous plug flow and axial dispersion models and the solution procedure used in this work. The steady state and dynamic behavior exhibited by the partial oxidation process are discussed in Section 7.5. The summary is provided at the end.

7.3 Model Development

This section presents the transient heterogeneous plug flow and axial dispersion models for the packed bed reactors. The rate of the reactions and other correlations for the transport properties used are also presented here. The solution procedure employed in this work is discussed in Section 7.4.

7.3.1 Transient Plug Flow Model : The species mass balance and energy balance equations for the gas phase and the solid phase are presented here:

Species Mass Balance in the Gas Phase:

$$\varepsilon_b \rho_g \frac{\partial y_{ig}}{\partial t} + M_T \frac{\partial y_{ig}}{\partial z} = \varepsilon_b R_{ig} - \frac{S_p}{V} n_{ifo} \quad (7.1)$$

Continuity Equation:

$$\varepsilon_b \frac{\partial \rho_g}{\partial t} + \frac{\partial M_T}{\partial z} = 0 \quad (7.2)$$

where,

$M_T = \rho_g u_g$, is the mass flux (equals the inlet mass flux at the steady state)

Species Mass Balance in the Solid Phase:

$$(1 - \varepsilon_b) \frac{\partial \rho_{is}}{\partial t} = (1 - \varepsilon_b) R_{is} + \frac{S_p}{V} n_{ifo} \quad (7.3)$$

where,

ρ_{is} is the mass density of species i in the solid phase and,

$$n_{ifo} = k_{gi} (\rho_{ig} - \rho_{is}) \quad (7.4)$$

where, k_{gi} is the mass transfer coefficient of species i . The accumulation and reaction of the species in the gas film surrounding solid particles is neglected in this work.

Energy Balance for the Gas Phase:

$$\varepsilon_b \sum \rho_{gi} C_{pgi} \frac{\partial T_g}{\partial t} + \sum \rho_{gi} u_g C_{pgi} \frac{\partial T_g}{\partial z} = \varepsilon_b \sum_{j=1}^{nrxg} (-\Delta H_j) R_{jg} - (1 - \varepsilon_b) h a_p (T_g - T_s) \quad (7.5)$$

Energy Balance for the Solid Phase:

$$\rho_{bed} C_{pcat} \frac{\partial T_s}{\partial t} = (1 - \varepsilon_b) \sum_{j=1}^{nrxs} (-\Delta H_j) R_{js} + (1 - \varepsilon_b) h a_p (T_g - T_s) \quad (7.6)$$

The species densities / concentrations are calculated using the ideal gas law. The total density of mixture is given as, $\rho = \sum \rho_i = \sum \frac{p_i M_{wt,i}}{R_g T}$. The above equations (Eqs. 7.3-

7.6) are rendered dimensionless as follows:

$$z^* = \frac{z R_{ref}}{M_{Tref}}, \quad t^* = \frac{t R_{ref}}{\rho_{ref}}, \quad y_i = \frac{\rho_i}{\rho}, \quad T^* = \frac{T}{T_{ref}}$$

$$\rho^* = \frac{\rho}{\rho_{ref}}, \quad M_T^* = \frac{M_T}{M_{Tref}}, \quad R^* = \frac{R}{R_{ref}}, \quad (-\Delta H^*) = \frac{(-\Delta H)}{(-\Delta H_{ref})}$$

$$C_{pg}^* = \frac{C_{pg}}{C_{pref}}, \quad \beta = \frac{T_{ref} C_{pref}}{(-\Delta H_{ref})}$$

The resulting dimensionless equations of the transient heterogeneous plug flow model are:

Mass Balance for the Gas Phase:

$$\varepsilon_b \rho_g^* \frac{\partial y_{ig}}{\partial t^*} + M_T^* \frac{\partial y_{ig}}{\partial z^*} = \varepsilon_b R_{ig}^* - (1 - \varepsilon_b) \frac{k_{gi} a_p (\rho_{ig} - \rho_{is})}{R_{ref}} \quad (7.7)$$

Mass Balance for the Solid Phase:

$$\frac{\partial \rho_{is}^*}{\partial t^*} = R_{is}^* + \frac{k_{gi} a_p (\rho_{ig} - \rho_{is})}{R_{ref}} \quad (7.8)$$

Energy Balance for the Gas Phase:

$$\begin{aligned} \varepsilon_b \rho_g^* \beta \sum y_{gi} C_{pgi}^* \frac{\partial T_g^*}{\partial t^*} + M_T^* \beta \sum y_{gi} C_{pgi}^* \frac{\partial T_g^*}{\partial z^*} = \varepsilon_b \sum_{j=1}^{nrxg} (-\Delta H_j^*) R_{jg}^* - \\ (1 - \varepsilon_b) \frac{h a_p (T_g - T_s)}{(-\Delta H_{ref} R_{ref})} \end{aligned} \quad (7.9)$$

Energy Balance for the Solid Phase:

$$\rho_{bed}^* C_{pcat}^* \beta \frac{\partial T_s^*}{\partial t^*} = (1 - \varepsilon_b) \sum_{j=1}^{nrxs} (-\Delta H_j^*) R_{js}^* + (1 - \varepsilon_b) \frac{h a_p (T_g - T_s)}{(-\Delta H_{ref} R_{ref})} \quad (7.10)$$

In this work, Ergun equation is used to calculate the pressure drop at each and every axial position, which complements the above set of model equations. The above set of model equations is solved with the appropriate inlet and initial conditions.

7.3.2 Dimensionless Transient Axial Dispersion Model: The species mass balance and energy balance equations for the gas phase and the solid phase are given as follows:

Mass Balance for the Gas Phase:

$$\varepsilon_b \rho_g^* \frac{\partial y_{ig}}{\partial t^*} - \frac{\varepsilon_b \rho_g^*}{Pe_{mg}} \frac{\partial^2 y_{ig}}{\partial z^{*2}} + M_T^* \frac{\partial y_{ig}}{\partial z^*} = \varepsilon_b R_{ig}^* - (1 - \varepsilon_b) \frac{k_{gi} a_p (\rho_{ig} - \rho_{is})}{R_{ref}} \quad (7.11)$$

Mass Balance for the Solid Phase:

$$\frac{\partial \rho_{is}^*}{\partial t^*} = R_{is}^* + \frac{k_{gi} a_p (\rho_{ig} - \rho_{is})}{R_{ref}} \quad (7.12)$$

Energy Balance for the Gas Phase:

$$\begin{aligned} \varepsilon_b \rho_g^* \sum y_{gi} C_{pgi}^* \frac{\partial T_g^*}{\partial t^*} - \frac{\varepsilon_b}{Pe_{Tg}} \frac{\partial^2 T_g^*}{\partial z^{*2}} + M_T^* \sum y_{gi} u_g C_{pgi}^* \frac{\partial T_g^*}{\partial z^*} = \\ \frac{1}{\beta} \left[\varepsilon_b \sum_{j=1}^{nrsg} (-\Delta H_j^*) R_{jg}^* - (1 - \varepsilon_b) \frac{ha_p (T_g - T_s)}{(-\Delta H_{ref} R_{ref})} \right] \end{aligned} \quad (7.13)$$

Energy Balance for the Solid Phase:

$$\rho_{bed}^* C_{pcat}^* \frac{\partial T_s^*}{\partial t^*} - \frac{1 - \varepsilon_b}{Pe_{Tc}} \frac{\partial^2 T_s^*}{\partial z^{*2}} = \frac{1}{\beta} \left[(1 - \varepsilon_b) \sum_{j=1}^{nrsg} (-\Delta H_j^*) R_{js}^* + (1 - \varepsilon_b) \frac{ha_p (T_g - T_s)}{(-\Delta H_{ref} R_{ref})} \right] \quad (7.14)$$

Here,

$$Pe_{mg} = \frac{M_{Tref}^2}{D_{axi,m} R_{ref} \rho_{ref}}, Pe_{Tg} = \frac{M_{Tref}^2 C_{pref}}{\lambda_{eg} R_{ref}}, Pe_{Tc} = \frac{M_{Tref}^2 C_{pref}}{\lambda_{ec} R_{ref}}$$

The boundary conditions used to solve the above set of axial dispersion equations are:

$$\begin{aligned} At z^* = 0, \\ \frac{dy_i}{dz^*} = \frac{(u_g \rho_{gi} - u_{g0} \rho_{gi0}) Pe_{mg}}{M_{Tref} \rho_g^*} \\ \frac{dT_g^*}{dz^*} = \frac{(u_g \rho_g C_{pg}^* T_g^* - u_{g0} \rho_{g0} C_{pg0}^* T_{g0}^*)}{M_{Tref}} Pe_{Tg} \\ \frac{dT_s^*}{dz^*} = 0 \end{aligned} \quad (7.15a-c)$$

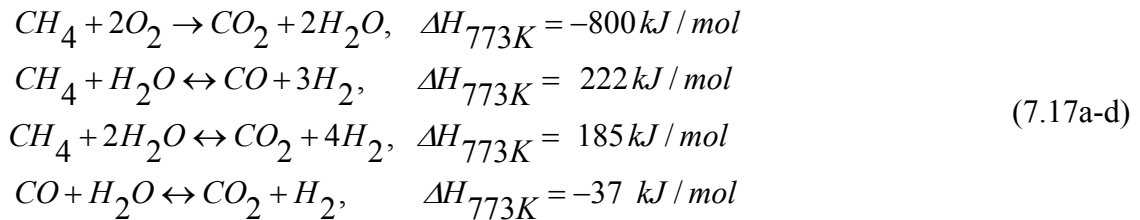
$$\text{At } z^* = L^*$$

$$\frac{dy_i^*}{dz^*} = \frac{dT_g^*}{dz^*} = \frac{dT_s^*}{dz^*} = 0 \quad (7.16)$$

The initial conditions may vary depending on the simulation study and are mentioned in Section 7.5. In the simulation study presented in this work, instead of using Danckwert's boundary condition (Eq. 7.15a-b), Dirichlet boundary conditions ($\rho_{gi}|_{z^*=0} = \rho_{gi0}$, $T_{gi}|_{z^*=0} = T_{gi0}$) are used because of large Pe_{mg} and Pe_{Tg} values. The correlations to estimate the axial heat and mass transfer coefficients are provided in Appendix B. The heat loss due to radiation is not included in our model as we found that the effect of radiation on the temperature profiles is not significant for the range of parameters we investigated. The steady state plug flow and axial dispersion models can be easily obtained by equating the terms corresponding to time derivatives in the respective transient models (Eq. 7.7 to Eq. 7.14) to zero.

7.3.3 Reaction Rates

The following reactions are considered to represent the partial oxidation of methane to syngas process and the corresponding rate expressions are obtained from the literature (de Smet et al., 2001)



The respective rate equations for the chemical reactions (7.17a)-(7.17d) are,

$$r_1 = \frac{k_{1a} p_{CH_4} p_{O_2}}{(1 + K_{CH_4}^{ox} p_{CH_4} + K_{O_2}^{ox} p_{O_2})^2} + \frac{k_{1b} p_{CH_4} p_{O_2}}{(1 + K_{CH_4}^{ox} p_{CH_4} + K_{O_2}^{ox} p_{O_2})} \quad (7.18a)$$

$$r_2 = \frac{\frac{k_2}{p_{H_2}^{2.5}} (p_{CH_4} p_{H_2O} - \frac{p_{H_2}^3 p_{CO}}{K_{e,2}})}{(Den)^2} \quad (7.18b)$$

$$r_3 = \frac{\frac{k_3}{p_{H_2}^{3.5}} (p_{CH_4} p_{H_2O}^2 - \frac{p_{H_2}^4 p_{CO_2}}{K_{e,3}})}{(Den)^2} \quad (7.18c)$$

$$r_4 = \frac{\frac{k_4}{p_{H_2}} (p_{CO} p_{H_2O} - \frac{p_{H_2} p_{CO_2}}{K_{e,4}})}{(Den)^2} \quad (7.18d)$$

where,

$$Den = 1 + K_{CO} p_{CO} + K_{H_2} p_{H_2} + K_{CH_4} p_{CH_4} + K_{H_2O} p_{H_2O} / p_{H_2}$$

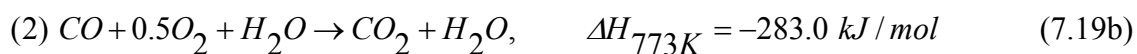
The values of pre-exponential factors, activation energies, heats of adsorption, and equilibrium constants are given in Table 7-1. We have used the above global kinetics to demonstrate the coupling and interactions of exothermic and endothermic reactions in packed bed reactors. These rate expressions are developed for the *Ni/Pt* catalyst system and it is to be noted that the temperature and product profiles obtained with *Ni/Pt* and *Rh* catalyst systems are qualitatively similar. De Smet et al. (2001) used the above kinetics (Eq. 7.18a-7.18d) with an effectiveness factor of around 10^{-3} (for all reactions) to simulate the industrial reactor. The effectiveness factor has been used in their work as the catalyst is assumed to be porous. The studies with the rhodium catalyst (Hohn and Schmidt, 2001; Bizzi et al., 2002), which is non-porous, shows that the catalyst is highly active for the partial oxidation process and the reaction is completed in a very short contact time, of the order of milliseconds. However, the global kinetic scheme for the partial oxidation processes with the rhodium catalyst is not well established. Hence we decided to use this kinetics without any effectiveness factor to qualitatively simulate

the short contact time reactor and to analyze the coupling of exothermic and endothermic reactions in the partial oxidation process.

Table 7-1: Pre-exponential factors for reaction rates, heats of adsorption and activation energies

Constant	Pre-exponential factor A(k _k); A(K _i)	Activation energy, E _k (kJ/mol) Heat of adsorption (ΔH) _k (kJ/mol)
k _{1a} (kmol / kg _{cat} bar ² h)	2.92 x 10 ⁶	86.0
k _{1b} (kmol / kg _{cat} bar ² h)	2.46 x 10 ⁶	86.0
k ₂ (kmol bar ^{0.5} / kg _{cat} h)	4.225 x 10 ¹⁵	240.1
k ₃ (kmol bar ^{0.5} / kg _{cat} h)	1.020 x 10 ¹⁵	243.9
k ₄ (kmol / kg _{cat} bar h)	1.955 x 10 ⁶	67.13
K _{CO} (bar ⁻¹)	8.23 x 10 ⁻⁵	70.65
K _{CH₄} (bar ⁻¹)	6.65 x 10 ⁻⁴	38.28
K _{H₂O}	1.77 x 10 ⁵	-88.68
K _{H₂} (bar ⁻¹)	6.12 x 10 ⁻⁹	82.9
K _{CH₄} ^{ox} (bar ⁻¹)	1.26 x 10 ⁻¹	27.3
K _{O₂} ^{ox} (bar ⁻¹)	7.87 x 10 ⁻⁷	92.8
	K _{e,2} (bar ²) = exp(-26830/T+30.114)	
	K _{e,3} (bar ²) = exp(-22430/T+26.078)	
	K _{e,4} (-) = exp(4400/T-4.036)	

At higher operating pressures, the gas phase reactions become important and therefore in some of the simulations, the following gas phase reactions (Dupont et al., 2002) were considered in addition to the previously listed heterogeneous reactions:



The rate expressions for the above homogeneous reactions are:

$$r_{\text{hom},1} \text{ (mol/m}^3\text{-s)} = 1.585 \times 10^5 \exp(-202600/R_g T) [\text{CH}_4]^{0.7} [\text{O}_2]^{0.8} \quad (7.20a)$$

$$r_{\text{hom},2} \text{ (mol/m}^3\text{-s)} = 5.623 \times 10^6 \exp(-180000/R_g T) [\text{CO}] [\text{H}_2\text{O}]^{0.5} [\text{O}_2]^{0.25} \quad (7.20b)$$

The pre-exponential factors in Eqs. 7.20a and 7.20b are slightly modified from those reported in the literature (Dupont et al., 2002).

7.3.4 Transport Properties

The heterogeneous models require the particle to fluid heat and mass transfer coefficients. These film transfer coefficients are calculated based on the correlations recommended by Wakao and Kaguei (1982) and Mills (1995) and are given below:

Heat transfer correlation:

$$Nu = 2 + 1.1 \text{Re}^{0.6} \text{Pr}^{1/3} \quad (7.21)$$

where,

$$\text{Re} = \frac{\ell \mathcal{G} \rho_{\text{mix}}}{\mu_{\text{mix}}}; \text{Pr} = \frac{C_{p\text{gmix}} \mu_{\text{mix}}}{K_{\text{mix}}}$$

$$Nu = \frac{h \ell}{K_{\text{mix}}}; \ell = \frac{d_p \varepsilon_b}{1 - \varepsilon_b}$$

$$\mathcal{G} = \frac{M_T}{\rho_{\text{mix}} \varepsilon_b}$$

Mass transfer correlation

$$Sh_i = 2 + 1.1 \text{Re}^{0.6} Sc_i^{1/3} \quad (7.22)$$

where,

$$Sc_i = \frac{\mu_{mix}}{\rho_{mix} D_{im}}$$

$$Sh_i = \frac{k_{gi} \ell}{D_{im}}$$

The viscosity, thermal conductivity, specific heat and the diffusivity of the species used in this work are corrected for the temperature and / or pressure. The respective mixture properties at any point in the reactor are calculated based on the mixture rule for gases (Mills, 1995).

7.4 Solution Procedure

The transient plug flow and transient axial dispersion model equations (Eqs. 7.7-7.14) are solved by the method-of-lines (MOL) approach (van de Wouwer et al., 2001). In this approach, the partial differential equations (PDE) are converted to a set of ordinary differential equations (ODE) by suitable discretization of spatial derivatives and the resulting ODEs in time are then integrated using an explicit algorithm. We have used automatic step size adjustable LSODE routine from Netlib as an ODE integrator. It is observed that the explicit solver (corresponding to the feature MF = 10, in the LSODE solver) is more robust and faster compared to the stiff solver (MF = 22) for this problem. The second order finite difference upwind discretization scheme is used to discretize the spatial derivatives. The discretization scheme has been made robust to spurious oscillations using total variation diminishing (TVD) algorithms (using van-leer splitter) (Tannehill et al., 1997). The grid independence of the solution is verified and the number of nodes used for the simulation in this work is 250, unless otherwise stated. In our model the pressure drop at each point along the reactor length is updated at every time step using Ergun equation, which is a steady state equation. The discretization of Ergun equation results in a set of algebraic equations, which are solved using modified Newton-Powell hybrid solver (HYBRD) from the Netlib libraries.

7.5 Results and Discussions

7.5.1 Steady State Behavior

Here we analyze the effect of mass and heat transfer coefficients on the temperature and concentration profiles. The effects of feed quality (in particular the addition of steam in the feed) and the mass flow rate on the methane conversion, the product pattern and on the hot spot are discussed (using plug flow heterogeneous model). The influence of the axial dispersion coefficients (within the limitation of Dirichlet boundary conditions) on the performance of the short contact time reactor is also presented.

Effect of Heat and Mass Transfer Coefficients: The temperature profiles predicted using the plug flow model for two sets of heat and mass transfer coefficients are shown in Figure 7-1a. The input parameters used in the simulation are presented in Table 7-2. The heat and mass transfer coefficients are smaller for Case 2 compared to Case 1. For Case 2 the mass transfer coefficients are around 10% and the heat transfer coefficients are 30 % lower than those of Case 1 (multiply the heat and mass transfer correlations Eqs. 7.21 and 7.22, by the respective factors). The temperature profiles corresponding to Case 1 qualitatively match some of the experimental and other modeling results published in the literature (Bizzi et al., 2002; Biesheuvel and Kramer, 2003). In this process, the exothermic reaction is dominant initially and, hence, the temperature increases near the inlet of the reactor. The increase in the reactor temperature favors the endothermic reaction subsequently. Once the concentration of one of reactants (here, oxygen which is the limiting reactant) participating in the exothermic reaction decreases (or if it is completely consumed), the endothermic reaction becomes predominant and, therefore, a drop in temperature is observed in the later section of the reactor. In the portion near the reactor inlet, where the exothermic reaction is dominant, the solid phase temperature is higher than the gas phase temperature. On the other hand, the gas phase temperature is higher than the solid phase temperature when the endothermic reaction is dominant (near the reactor exit). This also shows that there exists a point in the reactor where the gas and solid phase may have similar temperature and at that point the rate of heat generation by the exothermic reaction matches the rate of heat

consumption by the endothermic reaction, in an adiabatic reactor. For the cases discussed in Figure 7-1a, the temperature profiles reach the equilibrium value, for both sets of film coefficients, near the exit. Also Case-2 requires more reactor length to reach the equilibrium compared to Case-1. It is to be noted that the magnitude of temperature peak is higher for the case with higher transport coefficient. We also observed that the temperature peak is higher for the case simulated with pseudo-homogeneous model (de Groote and Froment (1996) also have showed sharp temperature peak), for the parameters reported in Table 7-2. This shows that the presence of heat and mass transfer resistances minimizes the hot spot in the reactor, for this process.

Table 7-2: Model Input Parameters (Base Case)

Reactor length, m	0.1
Catalyst diameter, m	0.002
Inlet Temperature, K	700
Inlet Pressure, atm	40
Reactant Mass Flow Rate, kg/m ² -s	20
Feed Composition (mole fraction)	
CH ₄	0.6666
O ₂	0.3333
CO ₂	0.0000
H ₂ O	0.0000
CO	0.0000
H ₂	0.0001
Bed Porosity	0.43
Heat Capacity of Catalyst, J/kg-k	750

The predicted concentration profiles (for film transfer coefficients corresponding to Case 1) are shown in Figure 7-1b. The methane and oxygen concentration falls drastically near the reactor inlet with the production of CO and H₂. The equilibrium conversion is achieved in these reactors at short length of about 0.02 m. The ratio of CO/H₂ at the reactor exit is 0.52. It is to be noted that the non-equilibrium conditions can result when the reactor length is very small, say 0.015m. For further work, the film coefficients corresponding to Case 1 were used.

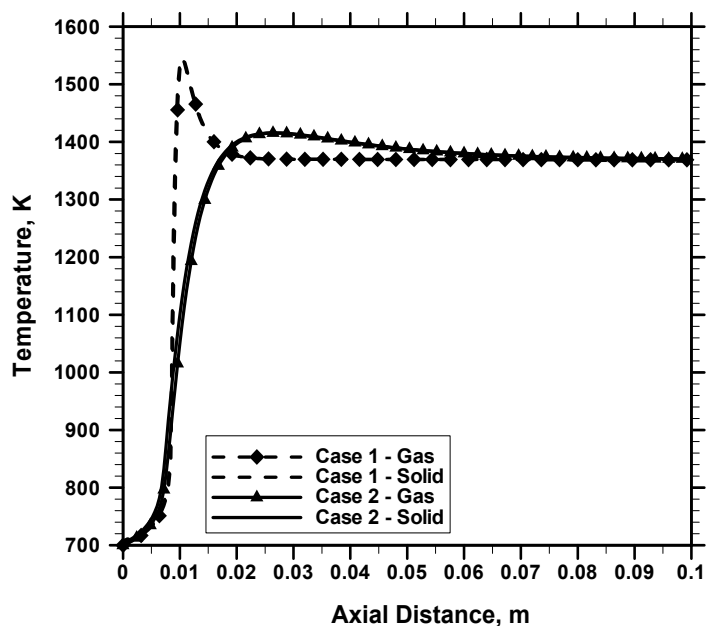


Figure 7-1a: Temperature Profiles Predicted by the Heterogeneous Plug Flow Model for Two Sets of Heat and Mass Transfer Coefficients (Parameters used are reported in Table 7-2)

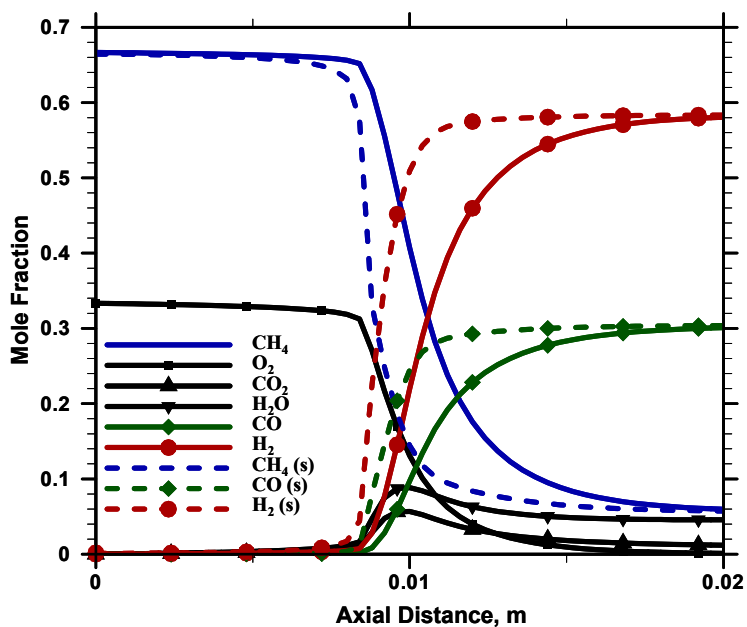


Figure 7-1b: Concentration Profiles Predicted by the Heterogeneous Plug Flow Model for Case 1 (s – for catalyst surface; Other parameters reported in Table 7-2)

Effect of Operating Pressure: Higher operating pressure favors the homogeneous reactions in addition to the heterogeneous reactions. Figures 7-2a and 7-2b show the effect of pressure on the temperature profile and on methane conversion respectively with and without gas phase reactions. As the operating pressure increases, the combustion reaction (homogeneous / heterogeneous) is enhanced. Hence, the temperature peak moves closer to the reactor inlet (Figure 7-2a). Also higher pressure favors more methane and water formation due to the thermodynamic equilibrium, and, hence decreases methane conversion (Figure 7-2b). This reduction in the reforming rate compared to the combustion rate can be attributed to the increase in the temperature peak at higher pressures.

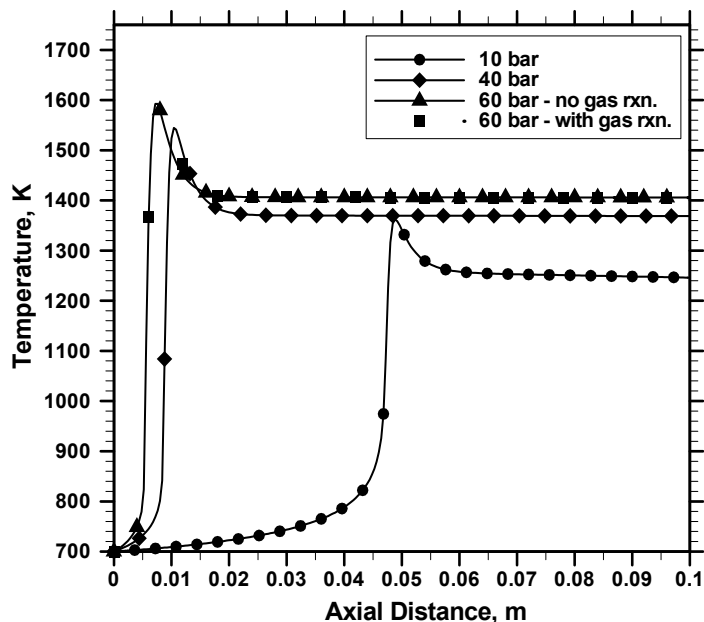


Figure 7-2a: Effect of Operating Pressure on the Gas Phase Temperature Profiles

The observed temperature profile shown in Figure 7-2a reveals that the gas phase reaction is not favored at lower pressures. At higher pressures, the predicted temperature peak is higher for the case with exothermic gas phase reactions than for the case without gas phase reactions. It is also clear from Figure 7-2a that gas phase reactions are relatively slow and take a while to kick on. The occurrence of gas phase reactions increases the production of CO_2 and H_2O , as evident from Figure 7-2c.

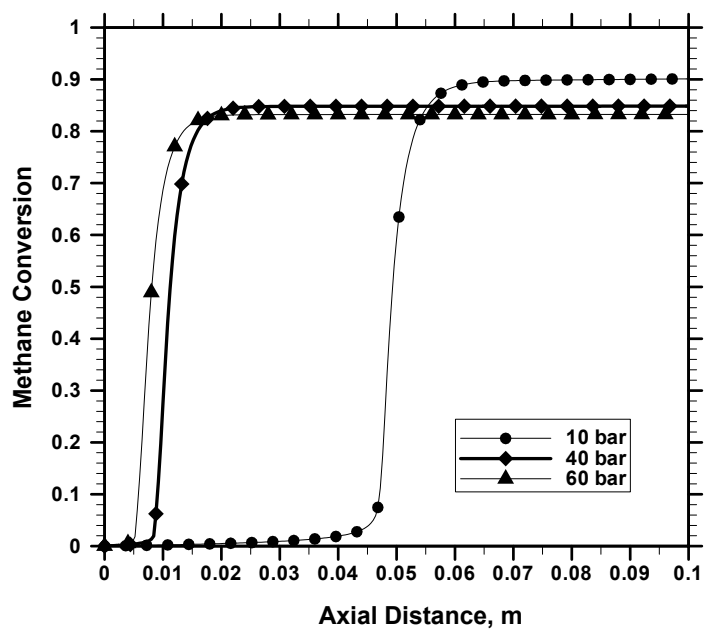


Figure 7-2b: Effect of Operating Pressure on Methane Point Conversion

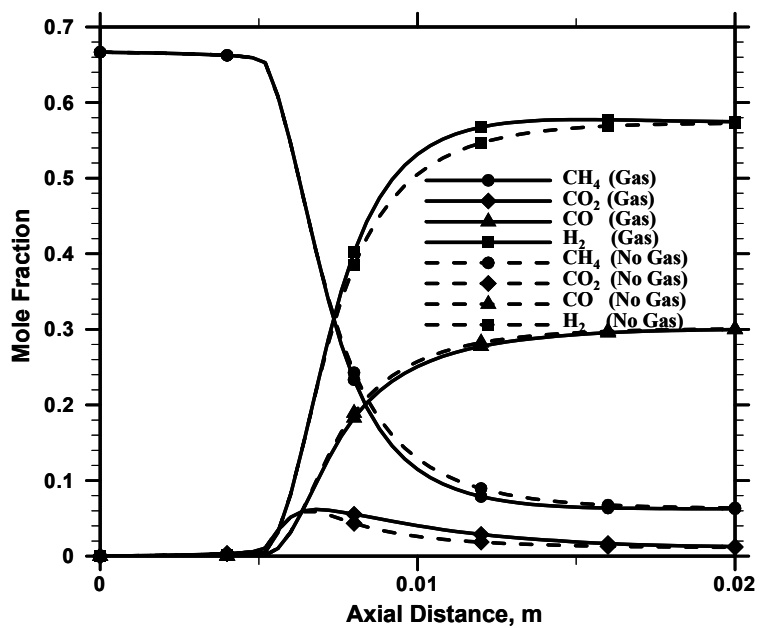


Figure 7-2c: Effect of Gas Phase Reactions on the Concentration Profiles (Gas – with gas phase reactions, No Gas – without gas phase reactions)

Effect of Steam in the Feed: It is known, in general, that the addition of steam to the feed increases hydrogen generation and reduces the exit / equilibrium temperature. This is due to increase in the rate of reforming reactions (endothermic). We observed that, for some cases, the magnitude of the temperature peak increases with the addition of steam (compared to the case without steam in the feed) and this is due to the ratios of steam-to-methane and methane-to-oxygen in the feed. Hence, in this section, the effects of addition of steam at constant and varying methane-to-oxygen ratio are analyzed and the observed behavior is explained.

Varying Methane-to-Oxygen Ratio (fixed amount of steam in the feed): First, the amount of steam (molar percent) in the feed was kept constant but the methane-to-oxygen ratio was varied. Figure 7-3a shows the resulting axial temperature profiles. With the increase in the feed methane-to-oxygen ratio at fixed molar percentage of steam, the temperature peak as well as the exit temperature decreases. This is due to the preferential occurrence of the reforming reactions with respect to the combustion reaction because of the availability of more methane and less oxygen. The temperature peak shifts to the right, away from the reactor inlet, with the addition of steam due to the increased rate of endothermic reactions in addition to the lowered rate of the exothermic combustion reactions. For the cases studied, the temperature peak is higher for the feed with lower methane-to-oxygen ratio. The CO-to-H₂ profiles for these cases are plotted in Figure 7-3b. Carbon mono-oxide to hydrogen ratio at the reactor exit decreases with the addition of steam compared to the case without steam in the feed. Among the cases with steam in the feed, the CO-to-H₂ ratio decreases, at the reactor exit, with increase in the feed methane to oxygen ratio due to the formation of more hydrogen. It is to be noted that CO can be produced in this process (inferred from Figures 7-3b and 7-3c and Eq. 7.17b and 7.17c) by the reverse water gas shift reaction. Figure 7-3c shows the CO₂ profile and it reveals that for the lower methane to oxygen feed ratio, more CO₂ is produced (initially) which then participates in the shift reaction further downstream to produce larger CO to H₂ ratio. This study shows that for the fixed amount of water in the feed, the lower methane-to-oxygen ratio in the feed results in the higher temperature peak, higher CO-to-H₂ ratio and lower CO₂ in the product.

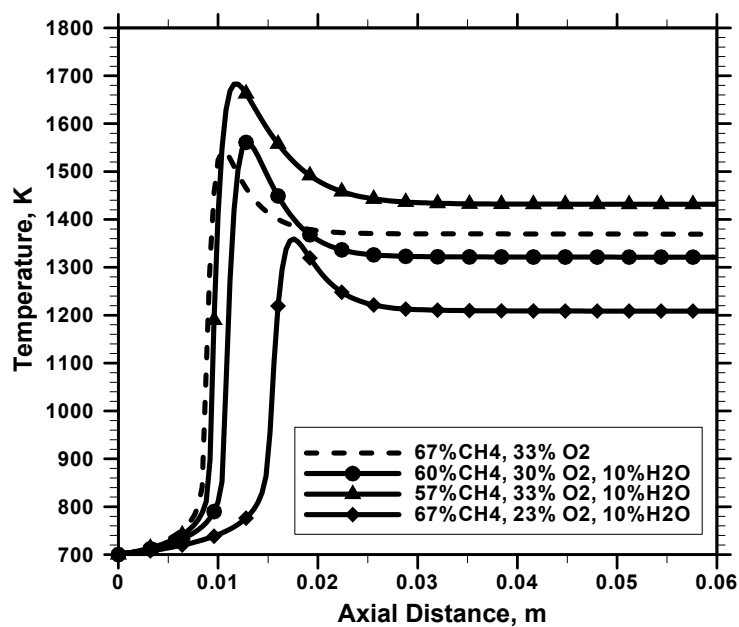


Figure 7-3a: Effect of Water in the Feed on Temperature Profiles (Gas Phase) – with varying Methane-to-Oxygen Ratio

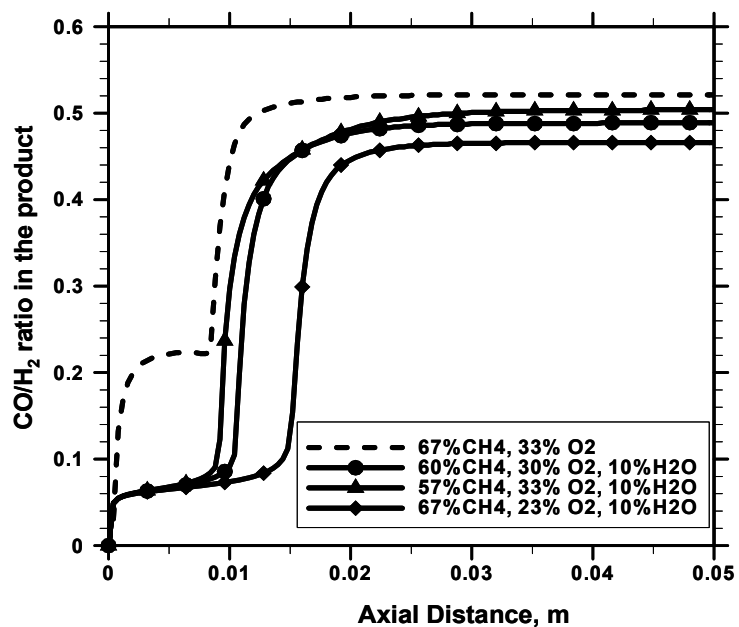


Figure 7-3b: Effect of Water in the Feed on CO/H₂ Profiles – with varying Methane-to-Oxygen Ratio

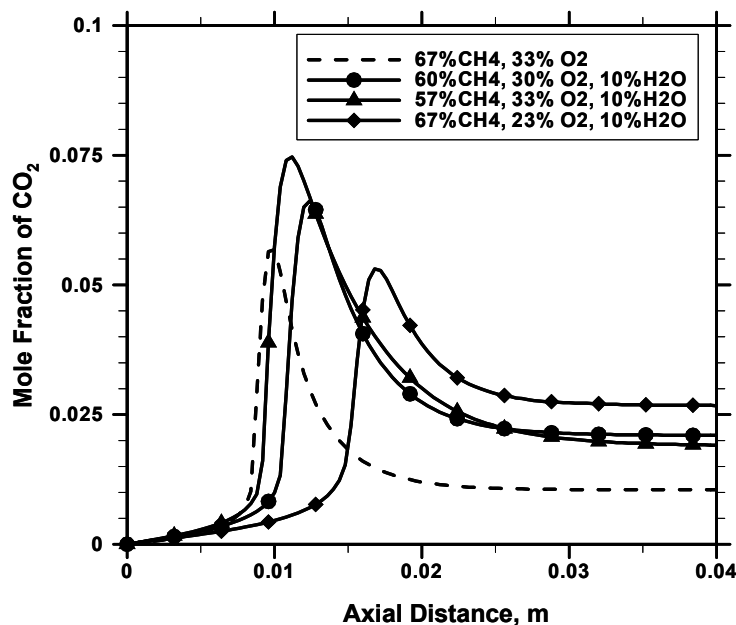


Figure 7-3c: Effect of Water in the Feed on CO₂ Mole Fraction Profiles– with varying Methane-to-Oxygen Ratio

Fixed Methane-to-Oxygen Ratio (with varying amount of steam in the feed): Here the molar ratio of methane to oxygen in the feed is kept constant at 2 and the amount of steam in the feed is varied. Figure 7-4a shows the predicted temperature peak and the respective equilibrium temperature as a function of the molar percentage of steam in the feed. The equilibrium temperature is calculated at the constant inlet pressure (reported in Table 7-2) using CHEMKIN software. Here, the equilibrium temperature (and also the temperature at the reactor exit) drops with the addition of steam whereas the temperature peak passes through a maximum at about 20% steam in the feed. The CO-to-H₂ ratios corresponding to the equilibrium conversion and at the position 0.025m in the reactor are plotted in Figure 7-4b. The CO-to-H₂ ratio decreases with the addition of steam. In the absence of steam, or in presence of small percentage of steam in the feed, the equilibrium composition is achieved at the shorter reactor length. For larger percentage of steam in the feed, more reactor length is needed to attain the equilibrium conversion. The initial increase in the temperature peak with water addition in the feed is due to water gas shift reaction. An increased percentage of water in the feed lowers

the amount of methane and oxygen in the feed and, hence, reduces the amount of CO_2 produced by the combustion reaction. Additionally, the presence of water favors the exothermic shift gas reaction attributing to slight temperature rise along with reduction in CO/H_2 ratio. This is further confirmed by Figure 7-4c where CO_2 profiles for three different feed qualities are plotted. In the presence of steam, the amount of CO_2 produced per mole of methane reacted decreases (near the reactor inlet). On the other hand, the conversion of CO_2 (at the reactor exit) decreases (mole fraction of CO_2 increases) with the addition of steam in the feed due to the equilibrium gas shift reaction. When the amount of water exceeds a certain critical limit, the rate of exothermic combustion reaction is reduced and, hence, the temperature peak decreases (which is the case with 30% water in the feed)

The above two studies show that the addition of water in the feed may increase the maximum temperature in the reactor depending on the methane-to-oxygen and /or methane-to-steam ratio and, hence, a proper protocol has to be established to control the temperature peak and the exit temperature.

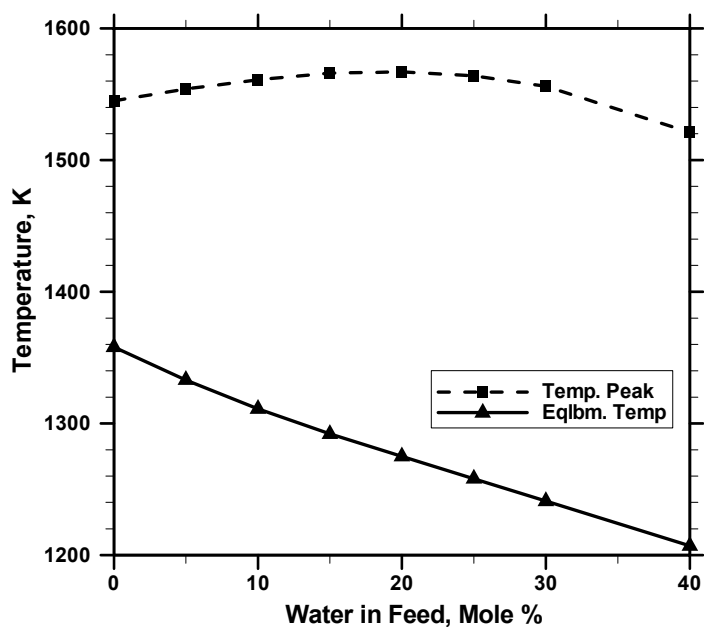


Figure 7-4a: Effect of Water in the Feed on Temperature Peak and the Equilibrium Temperature – with Constant Methane-to-Oxygen Ratio

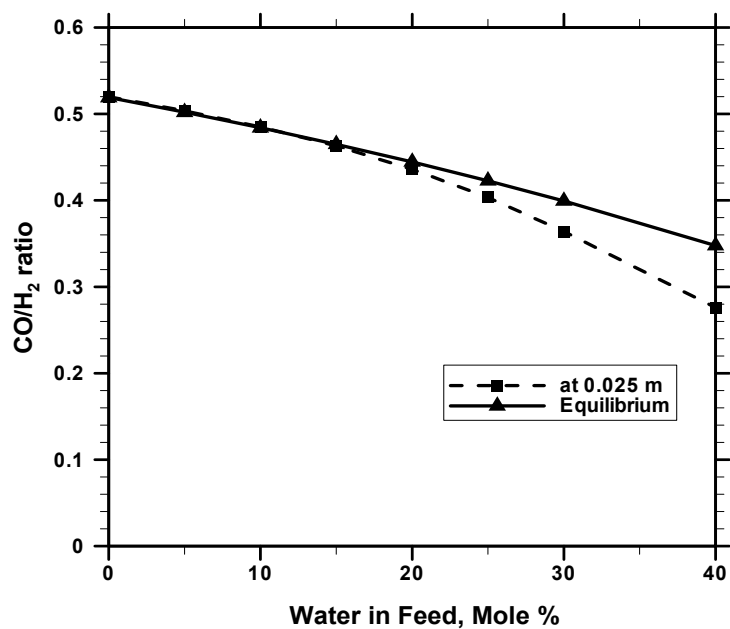


Figure 7-4b: Effect of Water in the Feed on CO/H₂ ratio – with Constant Methane-to-Oxygen Ratio

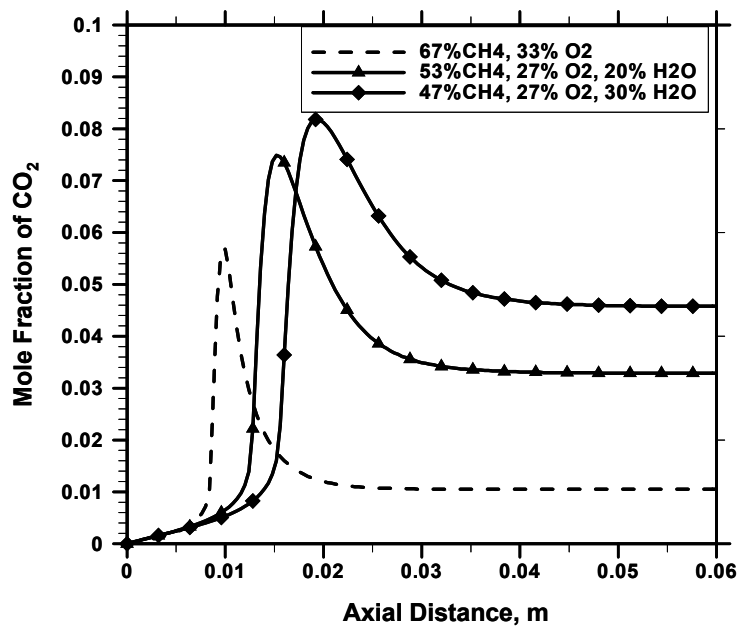


Figure 7-4c: Effect of Water in the Feed on CO₂ Mole Fraction Profiles– with Constant Methane-to-Oxygen Ratio

Effect of Inlet Mass Velocity: The increase in the reactant mass velocity increases the productivity (if the level of conversion is assumed constant) and decreases the contact time in the reactor. The effect of the mass velocity on the temperature profile, predicted by the heterogeneous plug flow model, is shown in Figure 7-5. The temperature peak increases with increase in the inlet velocity but is shifted towards the reactor exit. This shift is due to the decrease in the Damkohler numbers of the exothermic and endothermic reactions. Thus, the process needs more reactor length for the reactions (in particular the exothermic reaction) to click on. The increase in the temperature peak can be attributed to the reduced rate of endothermic reforming reactions and thus, the rise in temperature due to the exothermic combustion reaction is not curbed by the endothermic reaction. This increase in the temperature peak, due to increase in the inlet mass flow rate, increases the methane conversion slightly. There is some experimental evidence for the increase in methane conversion with the increase in gas hourly space velocity in the literature (Hohn and Schmidt, 2001; Bizzi et al., 2002). The methane conversion and the selectivity to CO and H₂ for the range of mass velocity investigated are shown in Table 7-3.

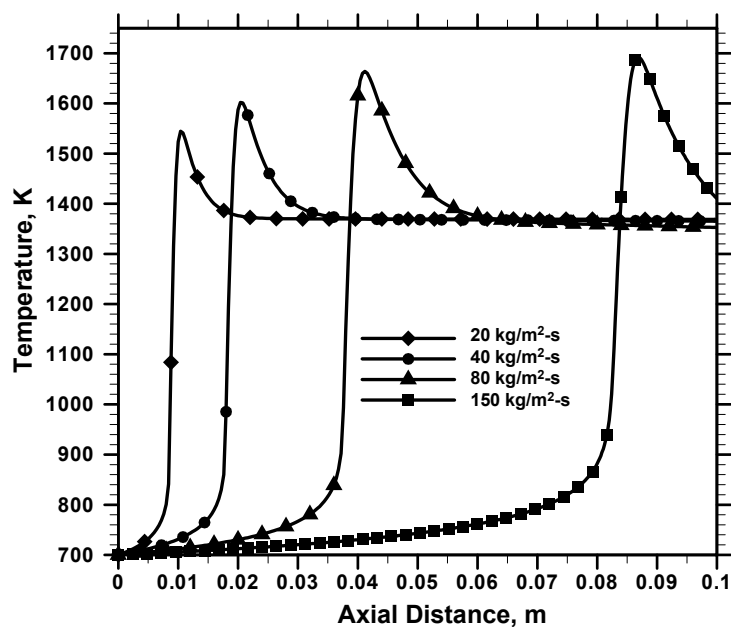


Figure 7-5: Effect of Inlet Mass Velocity on the Temperature Profiles (Other parameters reported in Table 7-2)

There is another school of thought regarding the increase in methane conversion with GHSV, which needs some clarification and is discussed here. Bizzi et al. (2002, 2003, and 2004) attributed such increase in methane conversion with mass velocity to the increase in the mass transfer rate. It is generally observed that the conversion decreases with increase in the mass velocity, which is due to decrease in the residence time for the reactants. This can be illustrated for an isothermal reaction system. For the heterogeneous systems, the dependence of mass transfer coefficients on the velocity scales as Re^α where α ranges from 1/3 to a maximum of about 0.8 (This is true for the heat transfer rate also). Thus, for a simple isothermal irreversible (or reversible) kinetics for reaction of types $A \rightarrow B$ (or $A=B$), the conversion of the reactant A (X_A), in the limit of mass transfer controlled regime is given as,

$$X_A = 1 - \exp(-K_m L / u_g), \quad (7.23)$$

where K_m is the volumetric mass transfer coefficient (1/s) and L is the length of the reactor and u_g is the inlet superficial velocity. Equation 7.23 shows that the conversion decreases with increase in the velocity. The conversion can only increase initially or pass through a maximum if the dependence of the mass transfer coefficient on velocity scales as a power greater than one ($\alpha > 1$). This suggests that the increase in conversion due to increase in the mass transfer rate can not be the sole reason for the experimentally observed behavior in short contact time reactors. The expressions for the dependence of conversion on the velocity, similar to Eq. 7.23, for the non-isothermal case can be derived analytically with some approximations or can be determined numerically.

In contrast to the above explanation, there are two different ways by which methane conversion could increase in this non-isothermal system. Firstly, the increase in the mass transfer rate supplies more reactants to the catalyst surface. The presence of more methane and oxygen increases the rate of exothermic reaction and thus increases the temperature at the catalyst surface. This higher temperature at the catalyst surface favors the endothermic reforming reactions (which also uses methane) and thus contributing to

increase in the methane conversion. Often, the above phenomenon is offset by the convection and the short residence time and thereby, methane conversion increases, initially, slightly. This slight increase in the methane conversion with the mass velocity is reported in Table 7.3. Secondly, there is a possibility that increase in the temperature peak, increases the temperature at upstream of the reactor (due to the dispersion) and at the inlet to the catalyst bed and, hence, resulting in higher methane conversion. This is explained in the next section.

As discussed earlier, when the convection dominates, methane conversion decreases with increase in the mass velocity, which is normally the case with larger velocity. From Table 7-3, it is clear that for much larger inlet mass velocity (or GHSV) the exit methane conversion is reduced. For this case, the temperature peak occurs very near the reactor exit (and for ever larger velocity the temperature peak can be pushed out of the reactor) as shown in Figure 7-5. When the temperature peak occurs near the exit of the reactor, the residence time for the predominant endothermic reactions (between the position of the temperature peak and the reactor exit) decreases and thereby contributing to decrease in the methane conversion, and the product selectivity. This is true for the mass velocity 150 kg/m²-s shown in Table 7-3. The increase in the conversion due to the increase in the inlet linear or mass velocity is counter balanced by the increase in the pressure drop across the reactor. The pressure drop calculated using the Ergun equation for different mass flow rates is reported in Table 7-3. This increase in the pressure drop may limit the commercial application of these reactors at higher GHSV.

Table 7-3: Effect of Inlet Mass Velocity on the Reactor Performance

Mass Flow Rate, kg/m ² -s	Inlet linear Velocity, m/s	Methane Conversion at the Exit, %	H ₂ Selectivity at the exit	CO selectivity at the exit	Pressure drop at the reactor exit, atm
20	1.36	84.9	1.856	0.967	0.58
40	2.73	85.0	1.857	0.967	2.17
80	5.46	85.6	1.864	0.968	7.77
150	10.22	80.7	1.877	0.917	18.00

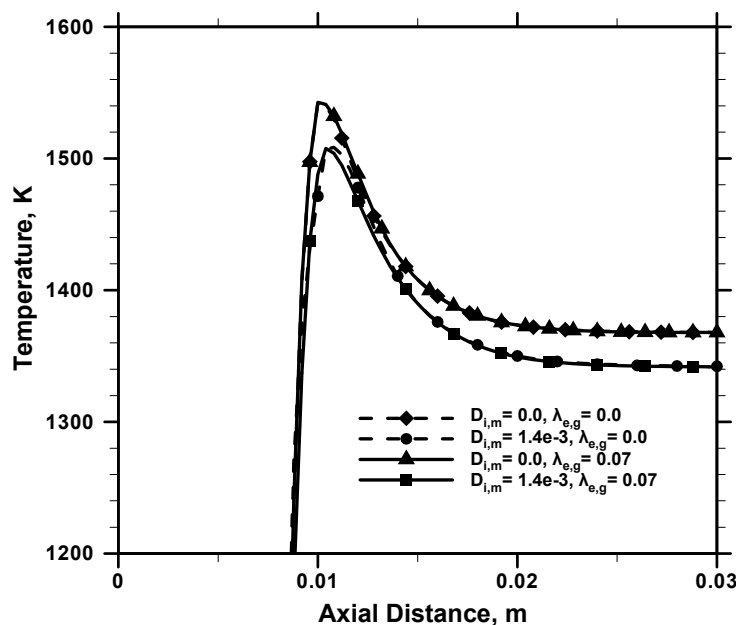


Figure 7-6: Temperature Profiles Predicted by Axial Dispersion Model (Parameters as reported in Table 7-2)

Effect of Axial Dispersion Coefficients: Bizzi et al. (2003, 2004) have shown that the mass and gas phase thermal dispersion coefficients can be neglected in the modeling of the short contact time packed bed reactors due to large Pe_{mg} and Pe_{Tg} . In this work, we have analyzed the influence of these dispersion coefficients on the temperature profiles. The mass and thermal dispersion coefficients can be calculated from the literature (Rase, 1990 and also refer Appendix B) and in this work an average value of $D_{axi,m} = 1.4 \times 10^{-3} \text{ m}^2/\text{s}$, $\lambda_{e,g} = 0.07 \text{ W/m-K}$ are used. The effective thermal conductivity for the solid can be obtained from Wakao and Kaguei (1982) and here, $\lambda_{e,c} = 1 \text{ W/m-K}$ (Bizzi et al., 2003) is used. The effect of the dispersion coefficients on the temperature profiles for the base case parameters reported in Table 7-2, are presented in Figure 7-6. The temperature profiles are qualitatively similar for the cases with and without dispersion coefficients. The presence of thermal dispersion coefficients did not have much influence on the temperature profile, whereas the mass dispersion coefficient affects the profile. In the presence of mass dispersion coefficient, the temperature peak and the exit temperature decrease.

It is to be noted that the dispersion effects play a huge role in these reactors if the reaction zone is sandwiched between two conducting inert packing sections, as seen in some of the experiments (Bizzi et al., 2002). In such a reactor arrangement, with increase in the mass velocity, the temperature peak increases. This in turn increases the temperature at upstream of the reactor (due to dispersion) and at the inlet to the catalyst bed resulting in higher methane conversion. In this work for further simulation studies, $D_{axi,m} = 0.0$, $\lambda_{e,g} = 0.07$ W/m-K, $\lambda_{e,c} = 1$ W/m-K (predominantly focusing on the thermal dispersions) were used.

7.5.2 Dynamic Behavior

The transient characteristics are important for the design, operation and control of the partial oxidation reactors. The phenomena such as wrong way behavior are commonly observed in packed bed reactors (where, say, exothermic reaction is conducted) due to the perturbation in the feed temperature and flow rates and are important to be understood for the steady-state and stable operation of the reactor. Suitable control protocols and operation protocols are developed based on the temperature excursion observed during this transient behavior. Similarly, the evolution of the temperature profiles (from initial conditions) is important for the safe start-up of the partial oxidation reactor where the exothermic and endothermic reactions occur simultaneously. Hence in this section, we analyze the evolution of the temperature and concentration profiles during the start-up of these short contact time packed bed reactors. Some wrong-way behavior observed in these reactors due to changes in feed temperature and due to the addition of steam in the feed is also presented.

Evolution Profile: Figure 7-7a shows the time series of the maximum gas phase temperature in the reactor predicted by the heterogeneous plug flow and the axial dispersion models for two cases – one with steam in the feed and the other without steam in the feed. The feed composition of these two cases are: - (i) with steam: 53% CH₄, 27% O₂ and 20% H₂O and (ii) without steam: 67% CH₄, 33% O₂. In this

simulation, the initial conditions along the reactor are kept the same as the inlet conditions.

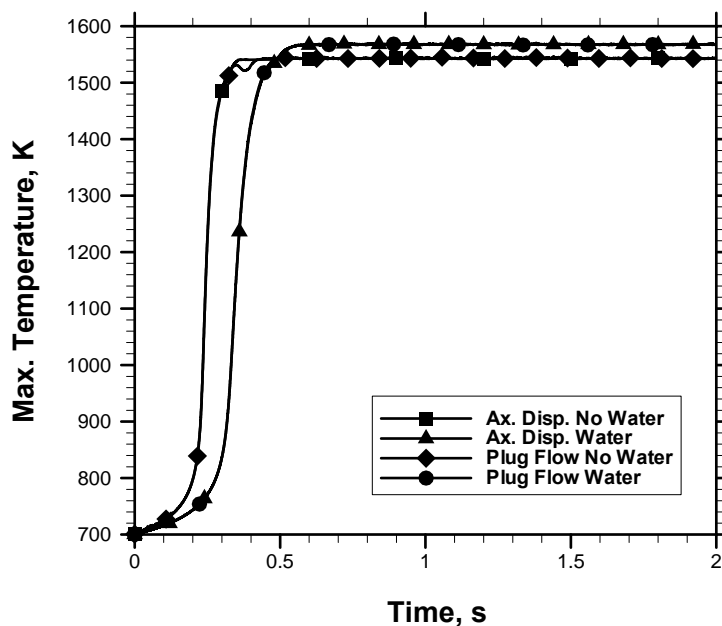


Figure 7-7a: Evolution of the Maximum Gas Phase Temperature in the Reactor Predicted by the Plug Flow and Axial Dispersion Models (Feed Composition: Water -: 53% CH₄, 27% O₂ and 20% H₂O and No Water - 67% CH₄, 33% O₂)

Here, the exothermic reaction clicks on around 0.3 s and, hence, the magnitude of the maximum temperature in the reactor increases sharply. The time at which this sharp increase in temperature occurs is predicted to be the same by both the plug flow and the axial dispersion models. The maximum temperature for the case with steam in the feed is higher than for the case without steam and is consistent with the steady state results discussed earlier (for the feed composition used). Also, for the case with steam, the time taken for the exothermic reactions to click on is slightly longer than that for the case without steam. This may be due to the reduced combustion rate (because of the decrease in the partial pressure of oxygen and methane in the feed) and increased reforming rate (due to water in the feed). It is to be noted that, for these cases, the temperature profile evolves smoothly and finally reaches the steady state. This trend may not be expected for the processes with very high exothermic reaction rate and/or heat of reaction or for the case with the lower heat capacity of the catalyst bed (one such extreme case will be

the coupling of homogeneous exothermic and endothermic reactions). In such situations, the maximum temperature in the reactor may overshoot the steady state temperature peak due to the short exothermic reaction time scale compared to other time scales involved in the process such as endothermic reaction time scale, the time scale of dissipation of heat by the solids etc.

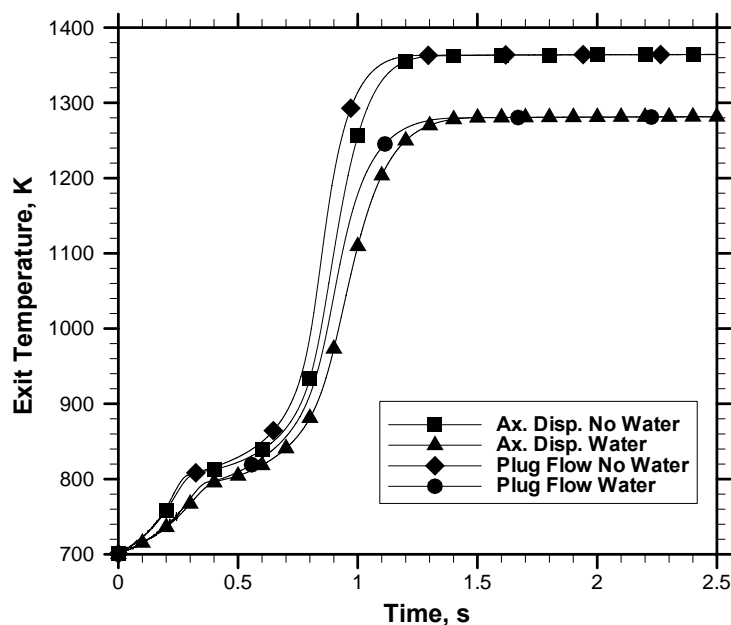


Figure 7-7b: Evolution of the Reactor Exit Temperature Predicted by the Plug Flow and Axial Dispersion Models (Feed Composition: Water -: 53% CH₄, 27% O₂ and 20% H₂O and No Water - 67% CH₄, 33% O₂)

Figure 7-7b shows the evolution of the gas phase temperature at the reactor exit. Here, the exit temperature for the case with water in the feed is lower than the one without water, consistent with the equilibrium limitations and our earlier discussions. The time taken to reach the steady state is slightly longer for the axial dispersion model compared to the plug flow model, which is due to the presence of the dispersion time scale in the problem. This study shows, for the parameters and initial conditions used in this work that the time taken to reach the steady state is around 1.2s. Though this time seems very short, it is several orders of magnitude greater than the residence time of the reactants (based on inlet conditions) in the reactor. This type of transient behavior with shorter

time to reach the steady state should be anticipated in the system with very active catalysts.

Wrong Way Behavior: Wrong-way behavior in packed bed reactors is well recorded for the reactions of the same type, like all exothermic reactions (Pinjala et al., 1988; Chen and Luss, 1989). The wrong-way phenomenon is caused by a sudden drop in the feed temperature, which results in the temperature excursion in the bed due to the different propagation speeds of the concentration and temperature profiles within the reactor. In this work, we have studied the wrong way behavior in the packed bed reactor where both exothermic and endothermic reactions take place. The occurrence of wrong way due to sudden decrease and increase in the feed temperature is analyzed. Similarly the transient temperature profiles observed in this reactor due to the introduction of steam in the feed are also investigated.

Decrease in the Feed Temperature: Here, the reactor is assumed to be operating at the steady state corresponding to the base case parameters reported in Table 7-2. Then, the feed temperature is decreased from 700 K to 650 K and the temperature profiles and concentration profiles during this transient period are monitored. The maximum temperature observed in the reactor and the temperature at the reactor exit are plotted in Figure 7-8a. The wrong way behavior is observed in this case with the magnitude of temperature peak increasing initially. The maximum increase in the magnitude of the temperature peak is not greater than 2% of the temperature peak corresponding to the initial temperature profile (steady state profile corresponding to the feed temperature of 700K). The temperature excursion due to wrong way is reduced or controlled, in this process, due to the presence of endothermic reactions.

Figure 7-8a shows a wavy (oscillatory) pattern in the profile of maximum temperature and a smooth pattern in the profile of the reactor exit temperature. These oscillations are the indication of the traveling hot and cold waves resulting due to decrease in the feed temperature and the simultaneous occurrence of the exothermic and endothermic reactions.

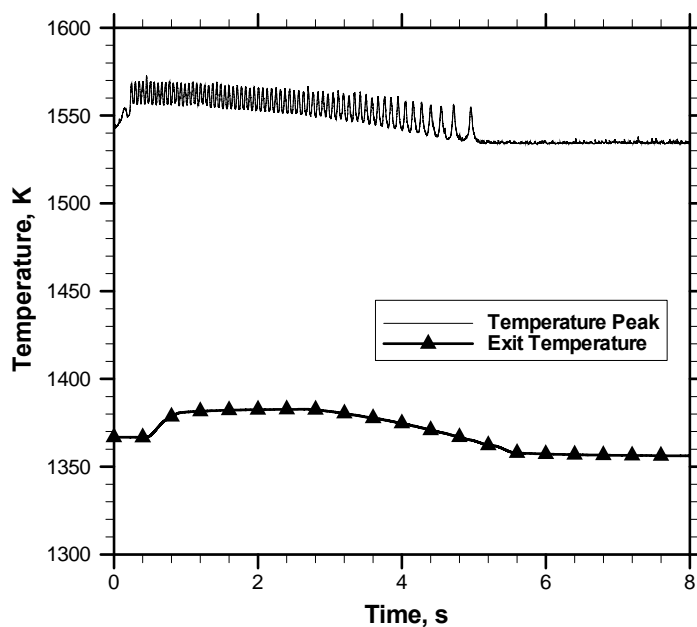


Figure 7-8a: Maximum temperature in the Reactor and the Exit Temperature Profiles Predicted by Axial Dispersion Models (Feed Temperature is reduced from 700 K to 650 K and Feed Composition: 67% CH₄, 33% O₂)

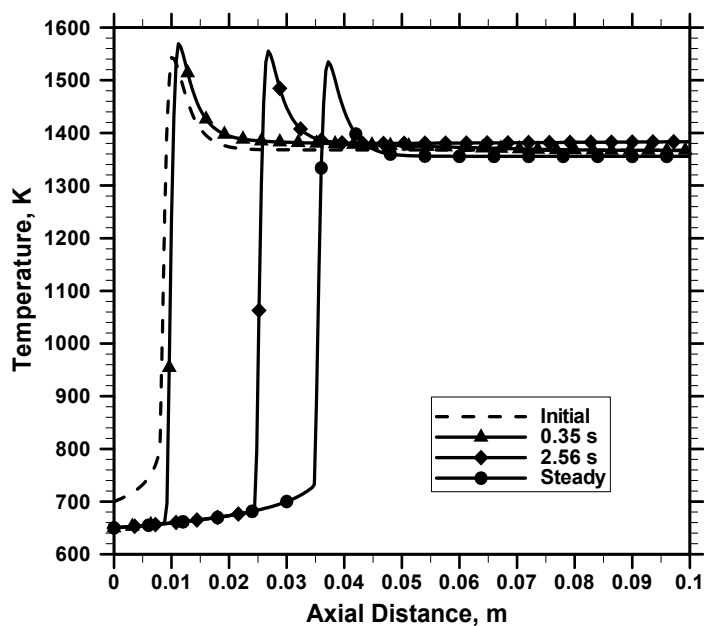


Figure 7-8b: Axial Temperature Profiles as a Function of Time (Feed Temperature is reduced from 700 K to 650 K and Feed Composition: 67% CH₄, 33% O₂)

The rate of endothermic reactions increases as and when the temperature increases in the reactor (due to wrong way), and these in turn contribute to controlling the temperature excursion. Figure 7-8b shows the axial temperature profiles within the reactor during this transient period. These profiles also reveal that, as the feed temperature is reduced, the reaction rates are reduced and, hence, the reactants with higher concentration meet the catalyst with higher temperature in the downstream part of the reactor. This results in wrong way with the temperature peak increasing beyond the steady state value. The sudden increase in the temperature promotes the endothermic reactions and hence the temperatures tend to decrease slightly. During this transient period, the reaction front moves right, away from the reactor inlet. This phenomenon continues until the steady state is achieved. The magnitude of the temperature peak at the steady state corresponding to the feed temperature of 650 K is lower than that of 700 K and is shifted to the right of reactor inlet.

Increase in the Feed Temperature: The sudden increase in the feed temperature also results in the wrong-way behavior in this process and is investigated in this section. The initial conditions for the temperature and concentration of the species within the reactor correspond to those of the base case steady state. Now, the feed temperature is increased from 700 K to 750 K. The maximum gas phase temperature and the temperature at the reactor exit during the transient period are plotted in Figure 7-9a. There is a drop in the maximum temperature observed, initially, followed by the temperature rise to the steady state. This is observed due to different traveling speeds of the concentration and thermal waves and, thereby, resulting interaction between the exothermic and endothermic reactions. The axial temperature profiles at the different instants of time are shown in Figure 7-9b. Due to the increase in the feed temperature, the rate of the exothermic reaction is increased near the reactor inlet. This in turn increases the rate of endothermic reaction, thereby the temperature peak is reduced. With further increase in time, both exothermic and endothermic reaction balance and finally settle at the steady state with temperature peak greater than that for 700K.

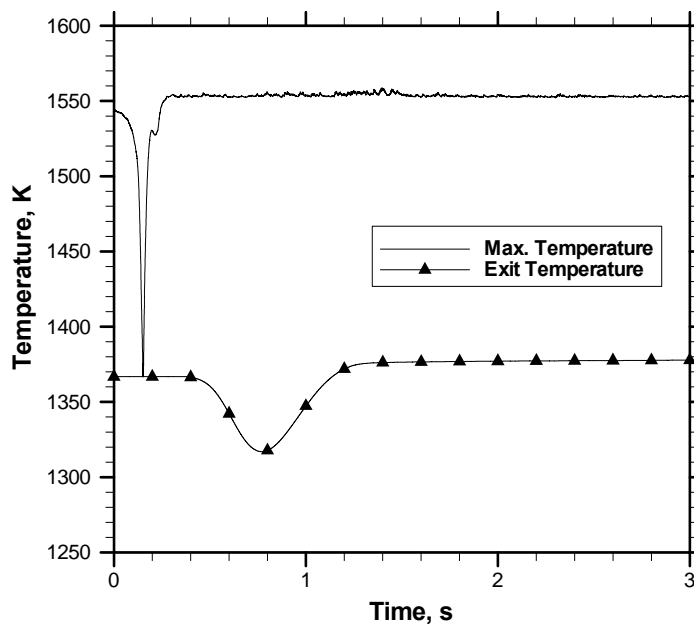


Figure 7-9a: Maximum temperature in the Reactor and the Exit Temperature Profiles Predicted by Axial Dispersion Models (Feed Temperature is increased from 700 K to 750 K and Feed Composition: 67% CH₄, 33% O₂)

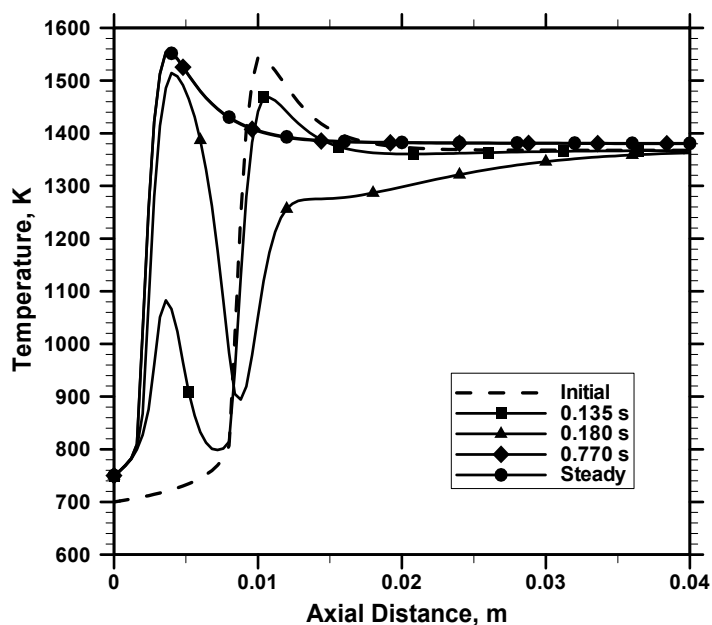


Figure 7-9b: Axial Temperature Profiles as a Function of Time (Feed Temperature is increased from 700 K to 750 K and Feed Composition: 67% CH₄, 33% O₂)

In some of the transient temperature profiles, as shown in Figure 7-9b, two temperature peaks are observed. The first temperature peak occurs near the reactor inlet and is due to the increased exothermic rate because of increase in the feed temperature. This temperature peak occurs around the location where the final (steady state) temperature peak corresponding to the imposed feed temperature is expected. The increase in the exothermic reaction rate increases the temperature which in turn favors the endothermic reaction and hence the temperature drop is observed (after the temperature peak). The gas stream within the reactor has some unreacted methane and oxygen. Once this gas stream (cooled) contacts the high temperature bed (from previous instant of time), the exothermic combustion reaction occurs, due to the presence of oxygen, resulting in the second peak in the temperature profile. However, during this transient period, the magnitudes of both these peaks are less than that of the initial profile and with increase in time, the second peak disappears. It is to be noted that the temperature peak corresponding to 750 K is greater than that for 700 K and is moved towards the reactor inlet, due to the accelerated exothermic rate near the reactor inlet.

The axial concentration profiles for methane and CO in the reactor are shown in Figures 7-9c and 7-9d respectively. It is clear that the methane conversion increases (near the reactor inlet) with the increase in the feed temperature. The increase in CO concentration in the region near the inlet confirms the simultaneous occurrence of endothermic reactions along with the exothermic reactions. During the initial transients, methane conversion decreases at the exit, with the production of less CO and with increase in time, the methane conversion and CO production increases. The methane conversion and CO selectivity are higher at 750 K compared to 700 K. The total duration of the transient lasts for less than 2s. It is clear from this study that, for the cases investigated, the occurrence of wrong-way phenomena does not affect the reactor performance severely and the reactor is able to attain the steady state.

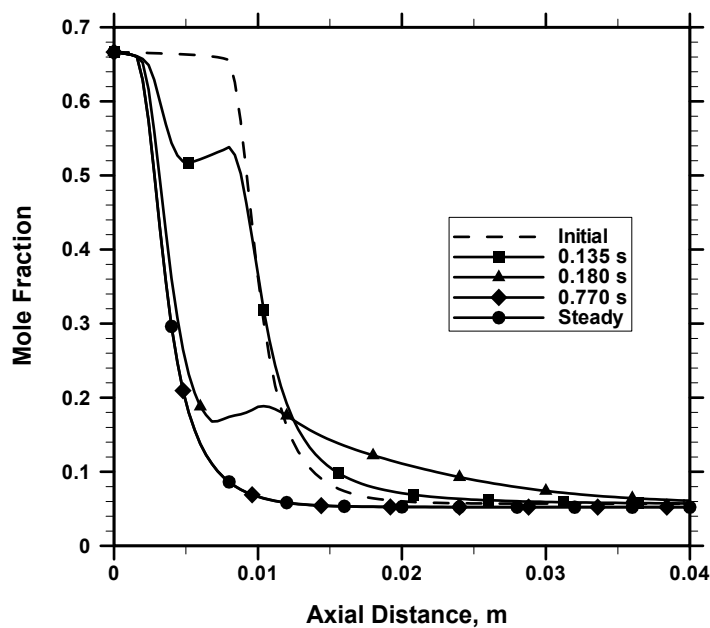


Figure 7-9c: Axial Concentration Profiles of Methane as a Function of Time (Feed Temperature is increased from 700 K to 750 K and Feed Composition: 67% CH₄, 33% O₂)

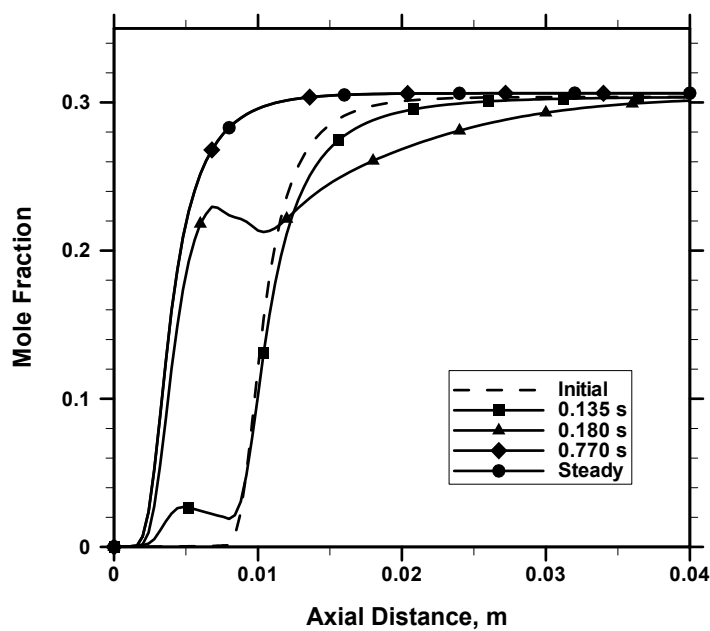


Figure 7-9d: Axial Concentration Profiles of CO as a Function of Time (Feed Temperature is increased from 700 K to 750 K and Feed Composition: 67% CH₄, 33% O₂)

Transient Profiles Due to the Addition of Steam in the Feed: As mentioned steam is added to the process to control the temperature and to increase the hydrogen selectivity. The steady state analysis shows that the decrease in the temperature at the reactor exit is independent of the maximum temperature observed in the reactor. The magnitude of the maximum temperature may increase with steam addition and it depends on the methane-to-oxygen ratio and steam-to-methane ratio in the feed. In this section, some of the dynamic behavior, in particular, the transient profiles observed due to sudden introduction of steam in the feed are analyzed. This study provides an insight in using water as a manipulated variable to control the temperature peak / excursion. The feed temperature chosen for this study is 700 K and the initial steady state profiles correspond to those reported in Table 7-2. Two cases with 10% steam in the feed are studied. The respective feed compositions are – a) 60% CH₄, 30 % O₂, 10% H₂O and b) 67% CH₄, 23% O₂, 10% H₂O. These two cases exhibit different dynamic behavior due to different mode of interaction of the exothermic and endothermic reactions. The temperature at the reactor exit and the maximum temperature within the reactor for these two cases are presented in Figures 7-10a and 7-10b. The exit temperature profiles smoothly settles to the final steady state for both the cases and the exit temperature for the cases with the water addition is lower than that for the initial profile. The maximum temperature in the reactor exhibits different dynamic behavior for these two cases.

For the case with CH₄/O₂ ~ 2.9 (Figure 7-10a), the maximum temperature decreases from the initial profile to the final steady state profile. This is due to the presence of limiting amount of oxygen and hence the rate of exothermic reaction is reduced. The endothermic reaction is enhanced at the same time due to the presence of more methane and water and hence the maximum temperature decreases. On the other hand, the maximum temperature for the case with CH₄/O₂ ~ 2 (Figure 7-10b), increases from the initial profile. During this transient period, until the steady state, the temperature peaks greater than the steady states profile is observed, which are shown as humps in the Figure 7-10b. The magnitudes of these temperature peaks are not greater than 30 K from the steady state value. The occurrence of these humps depends on the amount of water in the feed used and it also depends on the other operating conditions.

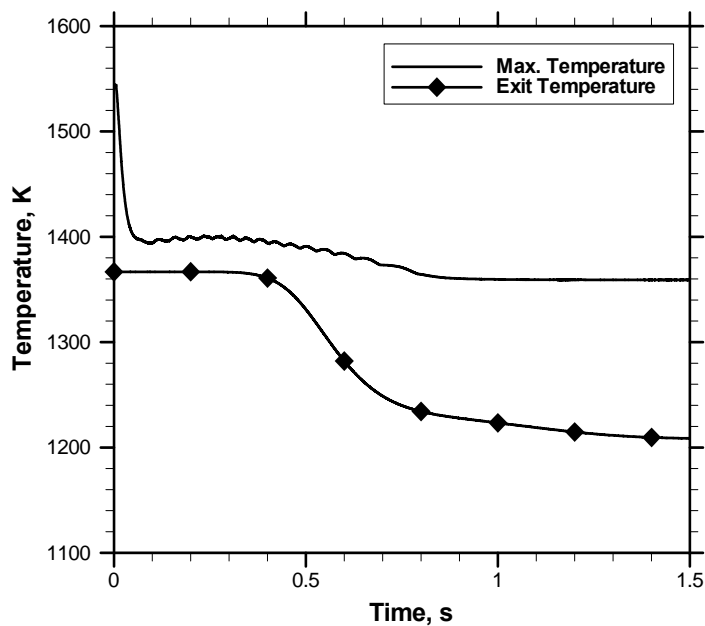


Figure 7-10a: Maximum Temperature and the Exit Temperature as a Function of Time. Water is introduced into the Feed Suddenly (Final Feed Composition: 67% CH₄, 23% O₂ and 10% H₂O)

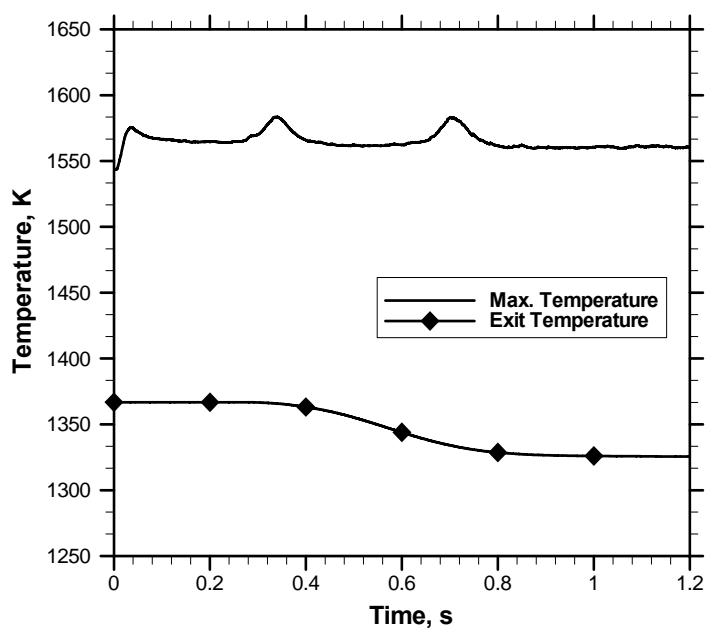


Figure 7-10b: Maximum Temperature and the Exit Temperature as a Function of Time. Water is introduced into the Feed Suddenly (Final Feed Composition: 60% CH₄, 30% O₂ and 10% H₂O)

7.6 Summary

The interaction of exothermic and endothermic reactions in the catalytic partial oxidation of methane to syngas in a short contact time packed bed reactor is analyzed using the heterogeneous plug flow and axial dispersion models. It was shown that the increase in the mass velocity of the reactants increases the productivity and the methane conversion slightly but at the expense of increased pressure drop. The addition of water in the feed reduces the exit temperature / equilibrium temperature but has the potential of increasing the temperature peak within the reactor. The magnitude of the temperature peak in the reactor depends on the methane-to-oxygen ratio and methane-to-steam ratio in the feed. The water should be added to the process if the increase in the selectivity of hydrogen is the primary focus. If one wants to use water as the manipulated variable to control the temperature excursions, then an appropriate control strategy has to be implemented in maintaining the desired methane-to-oxygen and methane-to-steam ratio.

The dynamic behavior of this process in the short contact time packed bed reactor is also analyzed. The wrong way behavior could result in this process by decreasing or increasing the feed temperature and/or by the sudden addition of steam to the feed. We also identified that the wrong way could also result in cold spot in these reactors, due to the presence of endothermic reactions. It was also found that the rise in the temperature peak, due to wrong way, is limited due to the simultaneous occurrence of the endothermic reforming reactions along with the combustion reactions. For the range of parameters investigated, the wrong-way behavior does not affect the reactor performance or pose any severe challenge to the catalyst used.

Chapter 8

Exergy Analysis and Comparison of Reactor Performance

8.1 Scope

In this chapter the performance of various reactor systems, such as recuperative and directly coupled adiabatic reactors is compared based on the first and second law of thermodynamics using exergy analysis. This procedure provides additional guidance in selecting the reactor choice and, in practical cases, quantifies the energy losses associated with the process irreversibilities in each reactor. The methods to calculate the total exergy of streams and the exergy losses in the reactors are presented. Additionally, for the recuperative reactors, the conversion obtained in the co-current and the counter-current reactors are compared against that in the newly proposed “bench-mark model” and the proposed treatment of comparing the reactor performance through the achieved conversion is presented.

8.2 Introduction

The thermal efficiency of coupling exothermic and endothermic reactions is a key parameter in comparing the performance of different modes of coupling. The first law of thermodynamics simply guarantees that the total energy of the system is conserved and it can be transformed to other forms of energy. An example for such energy transformation is the conversion of potential energy into mechanical energy and then later into electrical energy, in the case of power generation. The decrease in the quality of energy during the transformation is not explained by the first law of thermodynamics.

The quality of an energy stream can be defined as the capacity to do useful work with respect to the surrounding / environment. The second law of thermodynamics quantifies the quality of energy streams in terms of entropy losses. Entropy of a reversible system can be defined as follows:

$$ds = \frac{\delta Q}{T} \quad (8.1)$$

where ds , is the change in entropy of the system, δQ is the amount of heat (energy) supplied to the system at the temperature, T . Entropy is a non-conservable property with the entropy of thermodynamic universe constantly increasing. The entropy of a system can increase or decrease depending on supply or removal of heat and is created in all spontaneous processes (isolated irreversible processes). Hence, the efficiency of energy-use can be determined effectively by combining both the first and the second law of thermodynamics, through the concept of exergy.

The exergy of a stream is defined as the useful energy, thermodynamically available, to perform work (exergy is also defined as ‘availability’). To perform exergy analyses, one needs to know the exergy (available energy) of every material stream in a process in addition to the exergy of the heat streams and work. In the absence of kinetic and potential exergy terms, the basic exergy/mol (of a stream) can be defined as,

$$Ex = (H - H_o) - T_o(S - S_o) \quad (8.2)$$

where H_o , and S_o are enthalpy and entropy of the stream at reference conditions (T_o).

This chapter discusses the procedure to calculate the exergy losses in the reacting systems and demonstrate the use of exergy analysis in comparing the performance of various reactor systems. The derivation of stream exergy for chemical and non-chemical systems and the calculation of exergy losses in a process vessel / system are presented in the following sections.

8.3 Exergy Losses in a System at Steady State

The first law of thermodynamics states that the sum of all forms of energy flowing into the system at steady state equals the sum of the energy flows leaving the system:

$$\sum_{\substack{\text{out of} \\ \text{system}}} (nh_s) - \sum_{\substack{\text{in to} \\ \text{system}}} (nh) = \Delta Q + \Delta W \quad (8.3a)$$

Eq. 8.3a can also be rewritten as following (Eq. 8.3b):

$$\sum_{\substack{\text{out of} \\ \text{system}}} (nh + Q + W_s) - \sum_{\substack{\text{in to} \\ \text{system}}} (nh + Q + W_s) = 0 \quad (8.3b)$$

where n is the molar flow rates, h , the molar enthalpies, Q , the heat flows in or out of the system, W_s the shaft work crossing the boundaries of the system.

The second law of thermodynamics predicts, the production of entropy, ΔS_{irr} , which is the irreversible increase in the entropy, and is given by,

$$\sum_{\substack{\text{out of} \\ \text{system}}} \left(ns + \frac{Q}{T_s} \right) - \sum_{\substack{\text{in to} \\ \text{system}}} \left(ns + \frac{Q}{T_s} \right) = \Delta S_{irr} \quad (8.4)$$

where, s is the molar entropy and T_s the temperature at which heat, Q , is transferred.

Combining the above two equations (Eqs. 8.3b and 8.4), the availability balance or the exergy balance can be derived.

$$\sum_{\substack{\text{out of} \\ \text{system}}} \left(nb + Q \left(1 - \frac{T_0}{T_s} \right) + W_s \right) - \sum_{\substack{\text{in to} \\ \text{system}}} \left(nb + Q \left(1 - \frac{T_0}{T_s} \right) + W_s \right) = LW \quad (8.5)$$

Where, T_o is the reference temperature, b is the stream availability function which is a measure of the maximum amount of stream energy that can be converted into shaft work if the stream is taken to the reference temperature, and is given by,

$$b = h - T_o s \quad (8.6)$$

LW is the lost work, which is always a positive quantity. The greater its value, the greater is the energy inefficiency of the system and is given by

$$LW = T_o \Delta S_{irr} \quad (8.7)$$

Lost work tends to zero for a reversible process and it has the same units of energy. The magnitude of lost work depends on the extent of process irreversibilities like fluid friction, heat transfer due to finite temperature-driving forces, mass transfer due to finite concentration or activity driving forces, mixing of streams at differing conditions of temperature, pressure, concentrations etc.

8.4 Extra Loss Work due to Recuperative Coupling

The entire recuperative reactor, with shell and tubes, can be considered as an isolated system (Figures 1-1a and 1-1b). There is no heat transfer between the system and the surrounding. Hence for this case, $Q = 0$. Therefore the lost work ($LW_{isolated}$) calculated based on Eq. 8.5 for this reactor system is

$$\sum_{\substack{\text{out of} \\ \text{system}}} nb - \sum_{\substack{\text{in to} \\ \text{system}}} nb = LW_{isolated} \quad (8.8)$$

Now let us calculate the lost work on an individual side basis (for tube and shell sides).

For the endothermic side,

$$\sum_{\substack{\text{out of} \\ \text{system}}} (nb)_{Endo} - \sum_{\substack{\text{in to} \\ \text{system}}} (nb)_{Endo} - \sum_{\substack{\text{all discretisation} \\ \text{elements}}} Q \left(1 - \frac{T_0}{T_{endo}}\right) = LW_{endo} \quad (8.9)$$

For the exothermic side,

$$\sum_{\substack{\text{out of} \\ \text{system}}} (nb)_{Exo} - \sum_{\substack{\text{in to} \\ \text{system}}} (nb)_{Exo} + \sum_{\substack{\text{all discretisation} \\ \text{elements}}} Q \left(1 - \frac{T_0}{T_{exo}}\right) = LW_{exo} \quad (8.10)$$

Hence, in the recuperative coupling, the total lost work is,

$$\begin{aligned} LW_{system} &= LW_{endo} + LW_{exo} \\ &= \sum_{\substack{\text{out of} \\ \text{system}}} (nb)_{Endo} - \sum_{\substack{\text{in to} \\ \text{system}}} (nb)_{Endo} - \sum_{\substack{\text{all discretisation} \\ \text{elements}}} Q \left(1 - \frac{T_0}{T_{endo}}\right) \\ &+ \sum_{\substack{\text{out of} \\ \text{system}}} (nb)_{Exo} - \sum_{\substack{\text{in to} \\ \text{system}}} (nb)_{Exo} + \sum_{\substack{\text{all discretisation} \\ \text{elements}}} Q \left(1 - \frac{T_0}{T_{exo}}\right) \end{aligned} \quad (8.11)$$

We know,

$$\sum_{\substack{\text{out of} \\ \text{system}}} (nb)_{Exo} - \sum_{\substack{\text{in to} \\ \text{system}}} (nb)_{Exo} + \sum_{\substack{\text{out of} \\ \text{system}}} (nb)_{Endo} - \sum_{\substack{\text{in to} \\ \text{system}}} (nb)_{Endo} = \sum_{\substack{\text{out of} \\ \text{system}}} nb - \sum_{\substack{\text{in to} \\ \text{system}}} nb \quad (8.12)$$

Eqs. 8.8, 8.11 and 8.12 reveal that there is an extra lost work in the recuperative reactor.

The extra lost work in the recuperative reactor is given as follows:

$$\text{Extra lost work} = \sum_{\substack{\text{all discretisation} \\ \text{elements}}} Q \left(1 - \frac{T_0}{T_{exo}}\right) - \sum_{\substack{\text{all discretisation} \\ \text{elements}}} Q \left(1 - \frac{T_0}{T_{endo}}\right) \quad (8.13)$$

In a dimensionless form, the extra lost work (LW_{extra}) for the recuperative reactor is given as:

$$LW_{extra} = \sum_{\substack{\text{all discretisation} \\ \text{elements}}} U^{*c} (\theta^c - \theta^h) \frac{\theta^c}{1 + \theta^c} + \sum_{\substack{\text{all discretisation} \\ \text{elements}}} U^{*h} (\theta^h - \theta^c) \frac{\theta^h}{1 + \theta^h} \quad (8.14)$$

This extra lost work occurs because the temperature at which Q is transferred from, say, exothermic reaction and the temperature at which Q is received by endothermic side are different. This extra lost work always occurs as long as Q and / or T of exothermic and endothermic sides are different. If recuperative reactors operate in a way such that the exothermic and endothermic temperature are nearly the same, due to large heat transfer coefficients of the wall, then this extra lost work is zero (This corresponds to as close as we can get to “perfect reversibility”).

From Eqs. 8.11 and 8.12, the lost work due to entropy contribution can be given as:

$$Lost\ Work_{entropy} = \sum_{\substack{\text{out of} \\ \text{system}}} (nb)_{Exo} - \sum_{\substack{\text{in to} \\ \text{system}}} (nb)_{Exo} + \sum_{\substack{\text{out of} \\ \text{system}}} (nb)_{Endo} - \sum_{\substack{\text{in to} \\ \text{system}}} (nb)_{Endo} \quad (8.15)$$

If the endothermic and exothermic streams are assumed to be ideal gas then the change in entropy is given as:

$$ds = c_{pg} d \ln T \quad (8.16)$$

Hence, the lost work due to entropy, in dimensionless form, is given as:

$$LW_{entropy} = \ln(1 + \theta_{exit}^c) + \ln(1 + \theta_{exit}^h) \quad (8.17)$$

The variables used for non-dimensionalizing are similar to those reported in Chapter 3. In the foregoing discussions in this chapter, the extra lost work and the entropy contribution of the lost work (LW_{extra} and $LW_{entropy}$) are used as the measures to compare the performance and/or thermal efficiency of coupling exothermic and endothermic

reactions in the recuperative reactor. For directly coupled adiabatic reactor, the extra lost work is zero but the lost work due to entropy contribution exists $[= \ln(1 + \theta_{exit})]$ and it can be used as a measure to compare the reactor performance.

Table 8-1: References to the Parameter Sets Used in the Different Cases

Cases	Parameter Set
Case A (Base Case)	Same as the cases presented in Figure 3-3 and 3-5
Case B	Same as Row 4 of Table 3-2
Case C.1	Same as the case presented in Figure 3-12
Case C.2	Same as the case presented in Figure 3-12

Table 8-1 provides the references to the model parameters for the cases studied in this chapter. In Table 8-2 the lost work for various reactor systems are compared for different cases. For the base case, Case-A, it is clear that lost work due to entropy contribution and the extra lost work are higher for the counter-current reactor compared to the co-current reactor. For SIMDCAR, the extra lost work is not present. In this case, SIMDCAR behaves as an endothermic reactor, with the exit temperature lower than the inlet temperature and hence the lost work due to entropy contribution is negative. It should be noted that for this case, the exit conversion in SIMDCAR is lower than in the other two reactors. For Case-B, with smaller reactors, LW_{extra} is lower for co-current reactor whereas $LW_{entropy}$ is higher than the counter-current reactor. For this case, the reactor is short and hence not enough time was available to transfer heat from the exothermic side to the endothermic side, in the case of co-current reactor, and this resulted in larger $LW_{entropy}$ (due to higher exit temperature of exothermic stream). Cases C.1 and C.2 show that extra lost work is reduced with the introduction of inert packing in a section of the counter-current reactors (at similar level of conversion). For any reactor system with real species, then the addition of these two terms (in dimensional form) will give the total exergy loss in the reactor. It is to be noted that the exergy loss in a reactor should be treated as an independent parameter in addition to conversion and the hotspot for comparing the performance of the various reactor systems.

Table 8-2: Comparison of Lost Work in Different Modes of Coupling Exothermic and Endothermic Reactions

Cases	$LW_{entropy}$ (dimensionless)	LW_{extra} (dimensionless)	Conversion for Endothermic Reaction
Case A			
Counter-current	3.97e-3	4.96e-2	0.98
Co-current	2.03e-3	3.79e-2	1.00
DCAR	-0.13	0	0.67
Case B			
Counter-current	0.116	0.224	0.85
Co-current	0.233	0.157	0.69
DCAR	-0.082	0	0.37
Case C.1 – Without inert			
Counter-current	-1.7e-3	1.58e-2	0.99
Co-current	-5.2e-2	2.96e-3	0.95
DCAR	-0.064	0	0.88
Case C.2 – With inert			
Counter-current	5.7e-3	1.07e-2	0.98

It should be noted that the chemical exergies of the species are to be considered for the real systems and the method to calculate those will be presented in the next section. The exergy analysis for the catalytic partial oxidation of methane to syngas in an adiabatic packed bed reactor is also presented. The exergy analysis should be coupled with the

economic analysis to quantify the cost associated with the exergy losses / lost work. There is another way of comparing the performance of counter-current and co-current reactors, apart from the exergy analysis, and is presented in the Section 8.6.

8.5 Exergy of Chemical Streams

For the material stream with chemical constituents, the exergy arising due to chemical composition of the stream with respect to the reference environment has also to be accounted in addition to physical exergies. The reference environment is chosen to possess zero exergy and some of the standard reference environments can be found in Szargut et al., (1988). The exergy of any material stream can be defined as a summation of three different terms, such as exergy due to the chemical term, the physical term and a mixing term and is given as:

$$Ex = Ex_{chem} + Ex_{phys} + \Delta_{mix}Ex \quad (8.18)$$

The procedure to calculate the individual contributions to the total exergy, prescribed by Hinderink et al., (1996), is described below:

8.5.1 Calculation of Chemical Exergy

The chemical exergy of a material stream refers to that part of its total exergy that results from the difference in chemical potential – evaluated at reference conditions (T_o , P_o) – between the pure process components and the reference environment components at their environmental concentration. For an example, one such reference environment has the following components with the respective partial pressures: N₂O (2.2 kPa), N₂ (75.78 kPa), CO₂ (0.0335 kPa), O₂ (20.39 kPa), Ar (0.906 kPa).

In calculating the chemical exergy, the first step is the determination of the standard chemical exergy values of the pure reference environment components (denoted as *REF*

– species). By assuming ideal gas behavior, the standard chemical exergy of the gaseous *REF*-species is calculated as follows (Moran, 1982; Szargut et al., 1988):

$$Ex_{chem,REF-i}^0 = RT_0 \ln\left[\frac{P_o}{P_{REF-i}}\right] \quad (8.19)$$

Here, $Ex_{chem,REF-i}^0$ denotes the standard chemical exergy of a *REF*-species i and P_{REF-i} denotes its partial pressure evaluated at a mean atmospheric pressure of 99.31 kPa according to Szargut et al., (1988). P_o is the defined reference overall pressure (101.325 kPa).

In the second step, the chemical exergies of the species which do not exist in the reference environment (*non-REF* species) are determined. Here, the standard chemical exergy values of the stable form of the pure elements at T_o , P_o are evaluated from a consistent set of *REF*-species. Then the *non-REF*-species are formed from their elements. The formula with which the chemical exergy of a component can be calculated according to its formation reaction from its constituent elements is given by:

$$Ex_{chem,i}^0 = \Delta_f G_i^0 - \sum_j \nu_j Ex_{chem,j}^0 \quad (8.20)$$

In Eq. 8.20, $Ex_{chem,i}^0$ denotes the standard chemical exergy of any species i , $Ex_{chem,j}^0$ denotes the standard chemical exergy of the element j in species i and ν_j denotes the stoichiometric coefficient of element j in species i . For calculating the standard chemical exergy values of the elements from *REF*-species, the above expression (Eq. 8.20) must be used in addition to Eq. 8.19. When dealing with mixtures, the phase(s) at which the species components are present at reference conditions should be considered, since the standard chemical exergies are also phase dependent. The standard chemical exergy of any species i in its phase α can be calculated from the value in its phase β according to:

$$Ex_{chem,i}^{0\alpha} = \Delta_{\beta \rightarrow \alpha} G_i^0 - Ex_{chem,i}^{0\beta} \quad (8.21)$$

in which

$$\Delta_{\beta \rightarrow \alpha} G_i^0 = \Delta_f G_i^{0\alpha} - \Delta_f G_i^{0\beta} \quad (8.22)$$

Hence the chemical exergy of a multi component material stream is given by,

$$Ex_{chem} = L_0 \sum_{i=1}^n x_{0,i} Ex_{chem,i}^{0l} + V_0 \sum_{i=1}^n y_{o,i} Ex_{chem,i}^{0v} \quad (8.23)$$

It is clear that for calculating the chemical exergy of material streams, the flash calculations at the reference conditions have to be carried out for obtaining the required phase and composition data. We have used the commercial software, Aspen Plus, to do the flash calculations.

8.5.2 Calculation of Physical Exergy

The physical exergy of a material stream is the maximum obtainable amount of shaft work when this stream is brought from actual conditions (T, P) to thermo-mechanical equilibrium at ambient temperature (T_o, P_o) , by reversible processes and heat being only exchanged with the environment at T_o .

Here the material stream is adiabatically brought to the temperature of the environment T_o . Then, the material stream is isothermally brought to thermo-mechanical equilibrium with the environment at T_o, P_o . The physical exergy depends on the initial and final states of the system such as enthalpy and entropy and is given as:

$$Ex_{phys} = \Delta_{actual \rightarrow 0} \left[L \left(\sum_{i=1}^n x_i H_i^l - T_0 \sum_{i=1}^n x_i S_i^l \right) + V \left(\sum_{i=1}^n y_i H_i^v - T_0 \sum_{i=1}^n y_i S_i^v \right) \right] \quad (8.24)$$

8.5.3 Calculation of the Exergy Change of Mixing

In the calculations of chemical exergies and physical exergy, the mixture has been treated as a collection of individual components. The final step in the determination of the total exergy of a material stream comprises the determination of the mixing term resulting from the isothermal and isobaric mixing of the pure process components at actual thermo-mechanical conditions (T, P). The mixing term, denoted as exergy change of mixing, has a negative value relative to the pure process components. The concept of '*property change of mixing*' has to be utilized to determine the exergy change of mixing. The enthalpy and entropy change of mixing can be found from in standard text books (e.g. Smith et al.,1996). Using these property changes of mixing, the exergy of mixing can be defined as:

$$\Delta_{mix} Ex = \Delta_{mix} H - T_0 \Delta_{mix} S [T, P] \quad (8.25)$$

Thus, the total exergy of any material streams can be calculated using chemical exergy, physical exergy and the exergy of mixing. Physical exergy and the exergy of mixing depend on the state of the system, whereas chemical exergies depend on the standard chemical exergy values of the process components with respect to a reference environment. Once the exergy of the individual streams, i.e., inlet and outlet streams, are calculated, the exergy loss can be estimated.

Table 8-3 shows the exergy losses in an adiabatic packed bed reactor, carrying out the catalytic partial oxidation of methane to syngas. Other operating conditions used for the simulation are reported in Table 7-1. From Table 8-4, it is clear that although the process takes place adiabatically, there is a loss in exergy due to the process spontaneity. The penalty for the exergy losses has to be accounted in the optimization routine to improve the process performance.

Table 8-3: Exergy Losses in the Catalytic Partial Oxidation of Methane to Syngas in an Adiabatic Packed Bed Reactor

No.	Feed Conditions (mole %)	Inlet Enthalpy (kJ/g)	Outlet Enthalpy (kJ/g)	Inlet Entropy (kJ/g-K)	Outlet Entropy (kJ/g-K)	Inlet Exergy (kJ/g)	Outlet Exergy (kJ/g)	Exergy Loss (kJ/g)
1	CH ₄ : 67 O ₂ : 33	-1.549	-1.549	0.00943	0.01549	26.64	25.00	1.64
2	CH ₄ : 60 O ₂ : 30 H ₂ O: 10	-2.503	-2.503	0.00965	0.01519	24.59	22.93	1.66

The minimization of exergy losses results from the reduction in process irreversibilities and leads to improvement in cost-saving. The incorporation of exergy analysis in the economic evaluation / analysis should help industry in identifying the potential areas for cost-saving and choosing the reactor choice for the applications. The exergy analysis can be carried out in a plant scale (flow-sheet analysis), which will help industry in identifying the thermal losses such as steam losses etc.

8.6 Comparison of Reactor Performance against a Bench Mark Model

A bench mark model is developed to compare the performance of counter-current and co-current heat exchanger reactors. The schematic of the bench mark model is shown in Figure 8-1. The bench-mark model represents the ideal case where ‘almost’ all of the heat released by the exothermic reaction is transferred to the endothermic reaction and the conversion obtained in this bench-mark model is compared to those obtained in recuperative reactor. The bench-mark model also accounts for the original design and operating conditions of the recuperative reactor and, hence, the heat released by the exothermic reaction will be the maximum heat theoretically available for the exchange. In the bench-mark model, at first, the exothermic reaction is conducted adiabatically

(keeping the same design and operating conditions of the recuperative reactor or shell side and setting $U^* = 0$). Then the sensible heat of the exothermic effluent is transferred reversibly to preheat the endothermic feed. The endothermic reaction is conducted adiabatically in the next reactor (here the feed temperature of endothermic reaction is higher due to preheating of the endothermic stream) and the conversion of the endothermic stream at the reactor exit is calculated. The exit conversion of the endothermic reaction is compared with those of counter-current and co-current heat exchanger reactor. This procedure is suited for the recuperative reactor and not for the directly coupled adiabatic reactor, because the separation of endothermic and exothermic streams (to carry out the reaction adiabatically), in particular if a reactant and/or a product participates in both exothermic and endothermic reactions, is less meaningful.

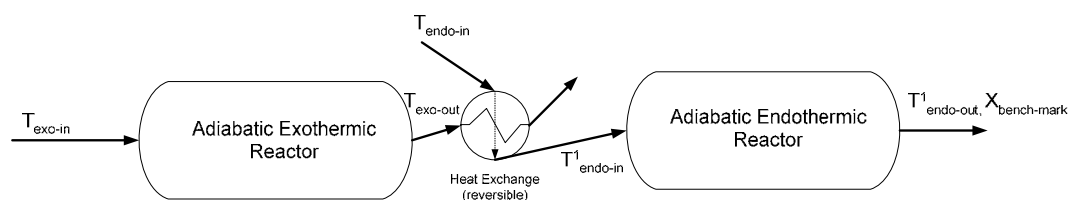


Figure 8-1: Schematic of the Bench-Mark Model

The performance of counter-current and co-current reactors for the parameter set shown in Table 8-1 is presented in Table 8-4. It is clear from Table 8-4 that the co-current reactor results in lower deviation from the maximum achievable conversion (benchmark model) for Case A. Co-current reactor results in higher conversion compared to the counter-current reactor with lower exit temperature for endothermic stream. For the similar set of parameters, the conversion for the endothermic reaction and the dimensionless exit temperature of the endothermic stream in DCAR are 0.6666 and -0.124 respectively. Case B in Table 8-4 corresponds to a shorter reactor, where it is found that the counter-current reactors results in higher conversion (comparing the percentage change in conversion between the bench-mark model and the respective co-current and counter-current cases).

Table 8-4: Performance of Recuperative Reactor against the Bench-Mark Model

Reactors	T_{endo-out} (dimensionless)	Conversion for Endothermic Reactions (X_{endo})	Percentage change in X_{endo} $\left(\frac{X_{Bench-mark} - X_{endo}}{X_{Bench-mark}} * 100 \right)$
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Case A

Bench-Mark	2.75e-4	0.9997	-
Counter-current	0.1187	0.9792	2.05
Co-current	8.57e-4	0.9978	0.19

Case B

Bench-Mark	2.11e-2	0.9737	-
Counter-current	0.024	0.8500	12.7
Co-current	0.051	0.6854	29.6

**Case C.1 – without
inert**

Bench-Mark	2.69e-4	0.9993	-
Counter-current	8.20e-2	0.9854	1.4
Co-current	-2.84e-2	0.9498	5.0

**Case C.1 – with
inert**

Bench-Mark	3.42e-3	0.9914	-
Counter-current	-1.45e-3	0.9810	1.04

Cases C.1 and C.2 correspond to the cases presented in Figures 3-12a and 3-12b where the role of inert packing on reducing the cold-pinch cross over point was demonstrated. For the case without inert packing, it is observed that the co-current reactor results in

lower conversion compared to the counter-current reactor. This is due to the fact that for this case the dimensionless heat of the reaction is low ($\beta^h = \beta^c = 0.4$) and hence the observed temperature rise is low. In the counter-current reactor, on the other hand, the heat source and heat sink are separated from each other (as the exothermic and the endothermic feeds enter at the opposite sides of the shell and tube reactor). This results in a higher temperature profile in the exothermic side and thereby increases the temperature (exit, temperature peak and/or average) and the conversion on the endothermic side. Comparing C.1 and C.2 it is clear that the presence of inert packing did not affect the performance of counter-current reactor from the conversion point of view, where as from Figure 3-12a, it is known that the case with inert packing minimizes/avoids the cold-pinch cross over points and the hot spots. This procedure also confirms that the presence of inert packing results in a similar level of conversion (as one without inerts) while reducing the catalyst requirement.

8.7 Summary

The performance comparison of coupling exothermic and endothermic reactions in the recuperative reactors and DCAR has been demonstrated using exergy analysis. The procedure to calculate the lost work or exergy losses in the reactor has been outlined. A detailed procedure for estimating the total exergies of the reacting material stream has been discussed. A sample calculation showing the exergy losses in the catalytic partial oxidation of methane to syngas in an adiabatic packed bed reactor is presented. These analyses show that recuperative reactors result in extra lost work due to resistive heat transfer through the wall. It is to be noted that the exergy loss in a reactor should be treated as an independent measure of the reactor performance in addition to the conversion and the hotspot for comparing the performance of the various reactor systems. A bench mark model has been proposed, which predicts the maximum achievable conversion due to efficient coupling of exothermic and endothermic reactions. The difference in conversion obtained in the co-current / counter-current recuperative reactor to that obtained in the bench-mark model provides a measure of efficiency of thermal coupling in the heat exchanger reactors.

Chapter 9

Summary, Conclusions and Recommendations

In this work, the coupling of exothermic and endothermic reactions in the recuperative and in the directly coupled adiabatic reactors is theoretically investigated using the steady state and transient pseudo-homogeneous plug flow models. The performance of different reactor systems was compared and the preliminary criteria for the selection of the reactors based on the rate of heat generation and the rate of heat consumption are proposed. The coupling of exothermic and endothermic reactions at the catalyst particle level is analyzed using the boundary-element method. The occurrence of multiple steady states in the catalyst particle is also examined using the newly developed boundary element combined continuation algorithm. The catalytic partial oxidation of methane to syngas in a short contact time packed bed reactor is studied, as a test system, using the plug flow and axial dispersion heterogeneous models. The finite difference based method of lines approach is used to solve the transient models through out this work. It is found that this approach of solving the partial differential equations is robust, simple to develop and easy to implement. Some of the specific conclusions are listed below.

The counter-current reactor for coupling exothermic and endothermic reactions can exhibit the hot pinch and cold pinch cross-over points in its temperature profiles for some of the parameters investigated as indicated by 1-D and 2-D models. At these points, both the exothermic and endothermic streams have identical temperatures. The counter-current reactors also exhibit multiple steady states. The hot spot is an issue in the counter-current reactor, and the use of inert packing in a portion of the reactor reduces the hot spot, whereas the length of inert packing has to be optimized for the specific operating conditions. It is also found that the inert packing reduces the magnitude of the cold pinch cross-over point temperature in the counter-current reactor

as well as the catalyst requirement. In general, it is observed that the counter-current configuration yields higher conversion than the co-current configuration in shorter reactors.

The co-current reactors, generally, result in lower temperature peak on the exothermic side than the counter-current reactor. The magnitude of the temperature peak could be further reduced considerably by suitable catalyst activity profiling in the co-current reactors. However, during the transient mode of operation the temperature peaks on the exothermic side exceed the steady state temperature peak. The wrong-way behavior occurs in counter-current and co-current reactors with both increase and decrease in the feed temperature, and dynamic studies are essential for the optimization of operating variables in these reactors.

Two dimensional models were used to study the effect of design and operational variables on reducing the temperature peak in the recuperative reactors. It is found that the increase in the distance between the tubes (exothermic side, at constant exothermic stream velocity), or increase in the flow rates of the exothermic streams, increase the magnitude of the temperature peak. The radial mixing also plays an important role in determining the magnitude of the hot spot, and the case with lower radial Peclet Number favors the uniform transverse temperature distribution resulting in the lower temperature peak.

In the direct mode of coupling SIMDCAR and SEQDCAR were investigated and compared with the co-current reactor. It is observed that if $\beta^c Da^c > \beta^h Da^h$, the conversion in the adiabatic reactor is lower than that in the co-current reactor, and between the directly coupled adiabatic reactors; SEQDCAR should be used to obtain higher conversion. If $\beta^c Da^c < \beta^h Da^h$, then SIMDCAR results in higher conversion with a lower temperature peak compared to the co-current reactor and SEQDCAR. For the case where $\beta^h Da^h = \beta^c Da^c$, the reactors are to be chosen based on the relative magnitudes of the exothermic and endothermic heats of reactions. It is found that as the catalyst particles in SIMDCAR undergo both exothermic and endothermic reactions

simultaneously, they exhibit multiple steady states, for some parametric range. The presence of endothermic reaction reduces the range of the Thiele Modulus for which multiple steady states occur and multiple steady states vanish at a critical reactant composition (i.e. with more reactants for endothermic reaction) at the catalyst surface.

Exergy analysis of the recuperative and the directly coupled adiabatic reactor show the extra entropic loss (lost work) in the heat exchanger reactor due to the heat transfer across the tube wall between the exothermic and endothermic sides. For most of the cases, the counter current reactor results in a higher exergy loss compared to the co-current or directly coupled adiabatic reactor. The exergy analysis should be combined with other performance parameters such as the exit conversion and the hot spot to obtain a comprehensive understanding of the different modes of coupling. The reactor performance (e.g. achieved conversion) of the co-current and counter-current reactors is also compared against that of the bench-mark model and this procedure of comparing the performance helps in choosing the suitable reactor for the desired application.

In the case study of catalytic partial oxidation of methane to syngas, investigated using the heterogeneous models, it is found that the packed bed reactor exhibits 'predominantly exothermic' and 'predominantly endothermic' regions. In the region where the exothermic reaction dominates, the temperature at the catalyst surface is greater than the gas phase temperature and the opposite being observed where the endothermic reaction is dominant. It is shown that the increase in the mass velocity of the reactants increases the productivity and methane conversion slightly in this short contact time reactors but only at the expense of increased pressure drop. The increase in the conversion is due to the increase in the temperature peak (because of increase in the transport coefficients) and/or due to the increase in the feed temperature due to dispersion. The addition of water in the feed reduces the exit temperature / equilibrium temperature but has the potential of increasing the temperature peak within the reactor. The magnitude of the temperature peak in the reactor depends on the methane-to-oxygen ratio and methane-to-steam ratio in the feed.

The dynamic behavior of this process in the short contact time packed bed reactor is also analyzed. The wrong way behavior in this process is observed both by decreasing or increasing the feed temperature and/or by the sudden addition of steam to the feed. The wrong way could also result in a cold spot in the reactor, due to the presence of endothermic reactions. It is also found that the rise in the temperature peak, due to wrong way, is limited due to the simultaneous occurrence of the endothermic reforming reactions along with the combustion reactions. For the range of parameters investigated, the wrong-way behavior does not affect the reactor performance or pose any severe challenge to the catalyst used.

9.1 Recommendations for Further Work

This research provides the foundation for further investigations in this field. The following are to be studied to understand the phenomenon of coupling exothermic and endothermic reactions and to design an efficient reactor:

- i) Various modes of coupling have to be compared using the heterogeneous models accounting for the deactivation of the catalyst. The catalyst used for these systems, especially for exothermic reactions, could deactivate due to sintering etc., and its effect on the coupling has to be analyzed.
- ii) Different modes of coupling in the catalyst wall coated reactor (such as in monolith reactor) has to be studied and compared with that of the packed bed reactor. This will aid in selecting the appropriate reactor choice.
- iii) Some relevant experiments are to be conducted to confirm the observations reported in this thesis, especially the transient behavior.
- iv) The modeling of the integrated system comprising the reactor for coupling exothermic and endothermic reactions with other heat exchange vessels (such as exchanging heat between the hot effluent and feed stream), to achieve the

desired inlet temperature of the feed, is essential for commercializing some of the reactor systems (for an example, in onboard reformers for generating hydrogen for fuel cell applications in automobiles etc.) and is to be undertaken.

- v) In this work, the conversion and the hotspot obtained in a plug flow type reactor are analyzed. The other limit on the conversion and the hotspot is obtained in a mixed flow reactor. The reactor behavior, with and without the reaction within the porous particles, should be analyzed based on the procedure outlined in one of our papers (Ramaswamy et al., 2005). This may help us in avoiding the hotspot in the reactors.
- vi) The effect of presence of trace higher hydrocarbons in the feed on the ignition temperature and on the product slate has to be analyzed, which are important from the industrial point of view. Similarly one should also study the effect of recycle of the product stream on the reactor performance and on the syngas selectivity.
- vii) The catalytic partial oxidation of reactors in the radial flow reactors has to be studied. By this approach the short residence time can be achieved (as the flow occurs radially, the length traveled by gases will be short) with lower pressure drop, while maintaining higher productivity. This study provides a guide in the scale-up of short contact time reactors.
- viii) The packed bed reactor with distributed oxygen, through appropriate membranes, has to be studied. The distribution of oxygen reduces the magnitude of the hot spot observed in the reactor, as the partial pressure of oxygen at any point in the reactor will be lower compared to the non-distributed case. This should help in improving the thermal efficiency of the process.

Appendix A

Criteria for Using Different Models

A.1. Homogeneous Vs Heterogeneous Models

Mears (1971) proposed a criterion to determine the onset of interphase heat transfer limitation (for Arrhenius type of reaction with negligible interphase mass transfer resistance). This states that the actual reaction rate deviates less than 5% from that calculated based on the bulk conditions, if:

$$\frac{R_T d_p}{h_f T} < 0.15 \frac{d_i T}{E} \quad (\text{A.1})$$

For any arbitrary reaction scheme, it is modified as (Iordanidis, 2002):

$$\text{deviation} = \frac{R_T(T^s, C) - R_T(T, C)}{R_T(T^s, C)} = \frac{\partial R_T(T^s, C)}{\partial T^s} \bigg|_{T^s=T} \frac{R_T(T^s, C)}{h_f a_v R_T(T, C)} < 5\% \quad (\text{A.2})$$

A similar criterion for the interphase concentration difference was given by Hudgins (1972), if

$$\frac{R_i d_p}{2R_i(C_i)k_f} \left| \frac{\partial R_i}{\partial C_i} \right|_{c=c_i} < 0.15 \quad (\text{A.3})$$

Based on the above concepts, we can say that the homogeneous model differs by not more than 5% of the predictions by the heterogeneous models if:

$$\frac{R_i(T^s, C^s) - R_i(T, C)}{R_i(T^s, C^s)} < \varepsilon = 0.05 \quad (\text{A.4})$$

The other ways of determining the effect of film transport resistances and the criterion to check the onset on internal transport resistances within the porous catalyst particles are provided in Ramachandran and Chaudhari (1983).

A.2. Plug Flow Vs. Axial Dispersion Model

As a rule of thumb, if $L/d_p > 30$ then axial dispersion can be neglected. Mears (1971) proposed for a single n^{th} order reaction, the deviation from the plug flow model is less than 5% if the following holds:

$$\frac{L}{d_p} > \frac{20nD_{ez}}{d_p u_s} \ln \frac{C_{inlet}}{C_{outlet}} \quad (\text{A.5})$$

A.3. Importance of Radial Variation in Temperature

For Arrhenius type kinetics with negligible axial heat dispersion, the influence of a non-uniform cross section temperature profile on the heat generation (consumption) is less than 5% (Mears, 1971) if:

$$\frac{|-\Delta H|(1-\varepsilon)R_{cs}d_t^2}{4\lambda_{er}T_w} < \frac{0.4RT_w/E}{1+8d_p/(d_t Bi)} \quad (\text{A.6})$$

Appendix B

Some of the Correlations for Predicting Transport Properties

B.1. Effective Radial Thermal Conductivity

- (i) Yagi and Wakao (1960)

$$\frac{\lambda_{er}}{\lambda_f} = \alpha + \beta \text{Pr Re} \quad (\text{B.1})$$

For glass spheres and broken cement clinkers:

$$\alpha = 6$$

$$\beta = \begin{cases} 0.11, & 0.021 < d_p / d_t < 0.072 \\ 0.09, & 0.12 < d_p / d_t < 0.17 \end{cases}$$

For metal spheres

$$\alpha = 13, \beta = 0.11, 0.021 < d_p / d_t < 0.086$$

Other correlations:

- (ii) Bauer and Schlunder (1978a, 1978b)
 (iii) Dixon and Cresswell (1979), Dixon (1988)
 (iv) Specchia et al. (1980)

B.2. Effective Radial Diffusivity

- (i) Specchia et al. (1980)

$$D_{er} = \frac{u_s d_{pa}}{8.65 \left[1 + 19.4 \left(\frac{d_{pa}}{d_t} \right)^2 \right]} \quad (\text{B.2})$$

Other correlations:

- (ii) Bauer and Schlunder (1978)
 (iii) Rase, H.F. (1990)

B.3. Wall Heat Transfer Coefficient

- (i) Li and Finlayson (1977)

Spherical particle, $0.05 < d_h/d_t < 0.3$, $20 < Re_h < 7600$:

$$Nu_w = \frac{h_w d_{pv}}{\lambda_f} = 0.19 Re_h^{0.79} Pr^{0.33} \frac{d_{pv}}{d_h} \quad (\text{B.3a})$$

Cylindrical particle, $0.03 < d_h/d_t < 0.2$, $20 < Re_h < 800$:

$$Nu_w = \frac{h_w d_{pv}}{\lambda_f} = 0.18 Re_h^{0.93} Pr^{0.33} \frac{d_{pv}}{d_h} \quad (\text{B.3b})$$

Other correlations:

- (ii) Dixon (1988)
 (iii) Specchia et al. (1980)

B.4. Overall heat transfer coefficient for 1-D model, U

(i) Li and Finlayson (1977)

Spherical particle, $0.05 < d_h/d_t < 0.3$, $20 < Re_h < 7600$:

$$\frac{Ud_t}{\lambda_f} = 2.26 Re_h^{0.8} Pr^{0.33} \exp\left(-\frac{6d_h}{d_t}\right) \quad (\text{B.4a})$$

Cylindrical particle, $0.03 < d_h/d_t < 0.2$, $20 < Re_h < 800$:

$$\frac{Ud_t}{\lambda_f} = 1.4 Re_h^{0.95} Pr^{0.33} \exp\left(-\frac{6d_h}{d_t}\right) \quad (\text{B.4b})$$

Other correlations:

(ii) Dixon (1988)

B.5. Axial Heat Dispersion Coefficient, λ_{ez}

(i) Yagi et al.. (1960)

$$\frac{\lambda_{ez}}{\lambda_f} = \frac{\lambda_{ez}^0}{\lambda_f} + \delta Re Pr \quad (\text{B.5})$$

$\delta = 0.7$ for steel balls, $\delta = 0.8$ for glass beads. More data on δ and λ_{ez}^0 are available in Yagi et al., (1960)

Other correlations:

(ii) Vortuba et al., (1972)

(iii) Dixon and Cresswell (1979)

B.6. Axial Mass Dispersion Coefficient, D_{ez}

(i) Wen and Fan (1975)

$$\frac{1}{Pe_{mz}} = \frac{0.3}{Re Sc} + \frac{0.5}{\left[1 + \frac{3.8}{Re Sc}\right]} \quad 0.008 < Re < 400, 0.28 < Sc < 2.2 \quad (B.6)$$

Appendix C

2-D Steady State Model for Co-current Current Heat Exchanger Reactor

The 2-D steady state model equations for the co-current reactor is modified (from those presented in Chapter 4) as follows:

- 1) Scaling of the problem: In Eqs. 4.1-4.4, the radial coordinates for tube and shell side are respectively from $\eta = 0$ to $\eta = \frac{R_1}{R_T}$ and $\eta = \frac{R_1 + t_{wall}}{R_T}$ to $\eta = 1$. The radial coordinates are rescaled so that it runs from 0 to 1, respectively, for both the sides (to match the MATLAB convention and let us call this new variable as λ).
- 2) Expand the radial diffusion term : By this modification, the option corresponding to that of the slab geometry, in PDEPE, can be easily employed for both the sides.

The modified governing equations for the co-current reactor are:

Tube side:

Mass Balance

$$\frac{1}{Da^c} \frac{\partial x_g^c}{\partial \xi} = (1 - \varepsilon_b^c) e^{\gamma^c \left(\frac{\theta_g^c}{1 + \theta_g^c} \right)} (1 - x_g^c) + \frac{1}{\Phi_{Mrc}^2 \chi_1^2} \left(\frac{1}{\lambda} \frac{\partial x_g^c}{\partial \lambda} + \frac{\partial^2 x_g^c}{\partial \lambda^2} \right) \quad (C.1)$$

EnergyBalance

$$\frac{1}{Da^c} \frac{\partial \theta_g^c}{\partial \xi} = \beta^c (1 - \varepsilon_b^c) e^{\gamma^c \left(\frac{\theta_g^c}{1 + \theta_g^c} \right)} (1 - x_g^c) + \frac{1}{\Phi_{Trc}^2 \chi_1^2} \left(\frac{1}{\lambda} \frac{\partial \theta_g^c}{\partial \lambda} + \frac{\partial^2 \theta_g^c}{\partial \lambda^2} \right) \quad (C.2)$$

Shell side:

Mass Balance

$$\begin{aligned} \frac{1}{Da^h} \frac{dx_g^h}{d\xi} &= \alpha(\xi) (1 - \varepsilon_b^h) e^{\gamma^h \left(\frac{\theta_g^h}{1 + \theta_g^h} \right)} (1 - x_g^h) + \frac{1}{\Phi_{Mrh}^2} \left(\frac{1}{((1 - \chi_2)\lambda + \chi_2)(1 - \chi_2)} \frac{\partial x_g^h}{\partial \lambda} \right. \\ &+ \left. \frac{1}{(1 - \chi_2)^2} \frac{\partial^2 x_g^h}{\partial \lambda^2} \right) \quad (C.3) \end{aligned}$$

EnergyBalance

$$\begin{aligned} \frac{1}{Da^h} \frac{d\theta_g^h}{d\xi} &= \alpha(\xi) \beta^h (1 - \varepsilon_b^h) e^{\gamma^h \left(\frac{\theta_g^h}{1 + \theta_g^h} \right)} (1 - x_g^h) + \frac{1}{\Phi_{Trh}^2} \left(\frac{1}{((1 - \chi_2)\lambda + \chi_2)(1 - \chi_2)} \frac{\partial \theta_g^h}{\partial \lambda} \right. \\ &+ \left. \frac{1}{(1 - \chi_2)^2} \frac{\partial^2 \theta_g^h}{\partial \lambda^2} \right) \quad (C.4) \end{aligned}$$

Here, $\lambda \in [0, 1]$

$$\chi_1 = \frac{R_1}{R_T}, \chi_2 = \frac{R_1 + t_{wall}}{R_T}$$

$$tube : \eta = \chi_1 \lambda$$

$$shell : \eta = (1 - \chi_2) \lambda + \chi_2$$

Note that for the shell side, the variable at $\lambda=0$ corresponds to the wall and for the tube side, $\lambda=1$, corresponds to the wall side.

The corresponding boundary conditions are:

$$\frac{dx_g^c}{d\lambda} = 0, \lambda = 0$$

$$\frac{dx_g^c}{d\lambda} = 0, \lambda = 1$$

$$\frac{dx_g^h}{d\lambda} = 0, \lambda = 0$$

$$\frac{dx_g^h}{d\lambda} = 0, \lambda = 1$$

$$\frac{d\theta_g^c}{d\lambda} = 0, \lambda = 0$$

$$\frac{d\theta_g^c}{d\lambda} = \frac{\chi_1 K_{wall} R_T}{t_{wall} \lambda^c} (\theta_{g,\lambda=0}^h - \theta_{g,\lambda=1}^c), \lambda = 1$$

$$\frac{d\theta_g^h}{d\lambda} = 0, \lambda = 1$$

$$\frac{d\theta_g^h}{d\eta} = \frac{(1 - \chi_2) K_{wall} R_T}{t_{wall} \lambda^h} (\theta_{g,\lambda=0}^h - \theta_{g,\lambda=1}^c), \lambda = 0$$

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Publications

- R.C. Ramaswamy, P.A. Ramachandran, and M.P. Duduković, “**Recuperative Coupling of Exothermic and Endothermic Reactions**”, *Chemical Engineering Science*, 61, 459-472, **2006**
- R.C. Ramaswamy, P.A. Ramachandran, and M.P. Duduković, “**Modeling of Solid Acid Catalyzed Alkylation Reactors**”, *International Journal of Reactor Engineering*, A42, Vol.3, **2005**
- R.C. Ramaswamy, P.A. Ramachandran, and M.P. Duduković, “**Exothermic and Endothermic Reactions in Simultaneous and Sequential Directly Coupled Adiabatic Reactors**”, proceedings of 7th World Congress of Chemical Engineering, Glasgow, Scotland (10-14 July 2005)
- R.C. Ramaswamy, and D.N. Saraf, “**Reduced Order Modeling of a Crude Distillation Unit for Online Applications**”, *Journal of Chemical Engineering of Japan*, 35 (8), 714-728, **2002**

- R.C. Ramaswamy, and P.A. Ramachandran, “**Multiple Steady States in Distributed Parameter Systems using Boundary Element and Arc Length Continuation Methods**”, sent for publication
- R.C. Ramaswamy, V. Venkataramani, K. Arora, and B. Khomami, “**Effect of Energetics on Interfacial Stability of Two Polymeric Fluids**”, in preparation
- R.C. Ramaswamy, P.A. Ramachandran, and M.P. Duduković, “**Modeling of Catalytic Partial Oxidation of Methane to Synthesis Gas in Short Contact Time Packed Bed Reactors**”, in preparation
- R.C. Ramaswamy, P.A. Ramachandran, and M.P. Duduković, “**Analysis of Heat Exchanger Reactors using Two Dimensional Models**”, in preparation

Presentations

- *Modeling of Catalytic Partial Oxidation of Methane to Syngas in Short Contact Time Packed Bed Reactors*, AIChE Annual Meeting 2005, Cincinnati, OH, USA, November 2005
- *Reactors for Solid Acid Catalyzed Alkylation Processes*, AIChE Annual Meeting 2005, Cincinnati, OH, USA, November 2005
- *Modeling of Solid Acid Catalyzed Alkylation Reactors*, Tenth Conference on Reactor Engineering (CRE-X), Zacatecas, Mexico, August 2005
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